

# Phoneme restoration and empirical coverage of Interactive Activation and Adaptive Resonance models of human speech processing

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Magnuson [J. Acoust. Soc. Am. **137**, 1481–1492 (2015)] makes claims for Interactive Activation (IA) models and against Adaptive Resonance Theory (ART) models of speech perception. Magnuson also presents simulations that claim to show that the TRACE model can simulate phonemic restoration, which was an explanatory target of the cARTWORD ART model. The theoretical analysis and review herein show that these claims are incorrect. More generally, the TRACE and cARTWORD models illustrate two diametrically opposed types of neural models of speech and language. The TRACE model embodies core assumptions with no analog in known brain processes. The cARTWORD model defines a hierarchy of cortical processing regions whose networks embody cells in laminar cortical circuits as part of the paradigm of laminar computing. cARTWORD further develops ART speech and language models that were introduced in the 1970s. It builds upon Item-Order-Rank working memories, which activate learned list chunks that unitize sequences to represent phonemes, syllables, and words. Psychophysical and neurophysiological data support Item-Order-Rank mechanisms and contradict TRACE representations of time, temporal order, silence, and top-down processing that exhibit many anomalous properties, including hallucinations of non-occurring future phonemes. Computer simulations of the TRACE model are presented that demonstrate these failures. © 2016 Acoustical Society of America.

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## I. INTERACTIVE ACTIVATION AND ADAPTIVE RESONANCE THEORY MODELS OF SPEECH PERCEPTION

Several qualitatively different kinds of models are attempting to explain and predict data about speech and language processing. The *Journal of the Acoustical Society of America* (JASA) article of Magnuson (2015) espouses the TRACE model of McClelland and Elman (1986) that is a member of the family of interactive activation models that were introduced by McClelland and Rumelhart (1981). The conscious ARTWORD, or cARTWORD, model [Fig. 1(b); Grossberg and Kazerounian, 2011], also published in JASA, contributes to the family of Adaptive Resonance Theory, or ART, models of speech and language processing that was introduced by Grossberg (1978a,b) and has been incrementally developed in a series of articles over the past 40 years (e.g., Ames and Grossberg, 2008; Boardman *et al.*, 1999; Bradski *et al.*, 1994; Cohen and Grossberg, 1986; Cohen *et al.*, 1995; Grossberg, 1984, 1986, 2003; Grossberg *et al.*, 1997; Grossberg *et al.*, 2004; Grossberg and Myers, 2000; Grossberg and Pearson, 2008; Grossberg and Stone, 1986a,b; Kazerounian and Grossberg, 2014).

The article by Magnuson (2015) is entirely devoted to a critique of cARTWORD and thus, by extension, the entire emerging ART theory of speech and language processing. Magnuson (2015) criticizes (1) the inability of our model to represent repeated items in working memory; e.g., a list like ABACBD, (2) our claim that the representation in TRACE of temporal order information is not only biologically implausible but also contradicted by psychological and neurophysiological data, (3) our claim that the ability of top-down feedback in TRACE to activate target units, without bottom-up input support, is biologically incorrect and leads to serious computational problems, (4) the limited explanatory range of our model compared to that of TRACE, and (5) our explanation of why TRACE cannot simulate phonemic restoration, which was a key explanatory target of Grossberg and Kazerounian (2011) and of the TRACE simulations that Grossberg and Kazerounian (2011) carried out to demonstrate this failure. Because Magnuson's criticisms are scientifically incorrect or misleading, we are here forced to rebut them. In so doing, our goal is also to provide useful information about how ART explains and predicts challenging psychological and neurobiological data about working memory, speech perception, and language learning that are, in principle, outside the explanatory range of the TRACE model and its variants.

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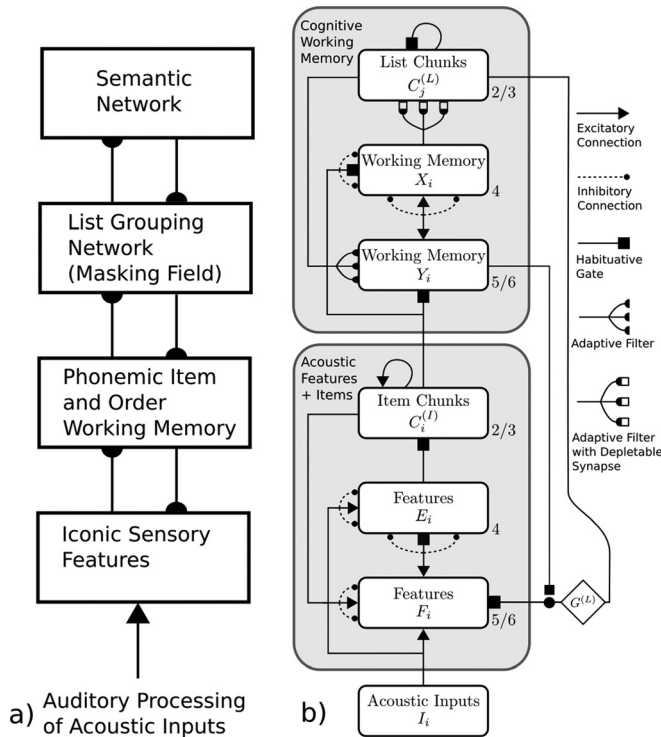


FIG. 1. (a) ARTWORD model macrocircuit. (b) cARTWORD model macrocircuit. cARTWORD includes a hierarchy of two cortical processing levels that model different cortical regions. Each level is organized into laminar cortical circuits that share a similar laminar organization, with cells organized into layers 5/6, 4, and 2/3, and with a similar distribution of inter-laminar connections. In both levels, deep layers (6 and 4) are responsible for processing and storing inputs via feedback signals between them. Superficial layers (2/3) respond to signals from layer 4 to categorize, or chunk, distributed patterns across these deeper layers into unitized representations. The first level is responsible for processing acoustic features (cell activities  $F_i$  and  $E_i$ ) and item chunks (cell activities  $C_i^{(I)}$ ), whereas the second level is responsible for storing of sequences of acoustic items in an Item-and-Order working memory (activities  $Y_i$  and  $X_i$ ), and representing these stored sequences of these items as unitized, context-sensitive list chunks (activities  $C_j^{(L)}$ ). List chunks are selected in a Masking Field, which is a multiple-scale recurrent on-center off-surround network the self-similar and shunting properties of which enable its list chunks to selectively represent sequences of multiple lengths. Top-down connections exist both within and between levels. Intra-level connections enable item chunks in layer 2/3 of the first level to send top-down attentional matching signals to their distributed features in layer 5/6, and list chunks in layer 2/3 of the second level to send top-down signals to their working memory item chunks in layer 5/6. Both types of signals can modulate, but not fire, their target cells when acting alone. Inter-level top-down signals are the ones that can trigger resonance. They occur from list chunks in layer 2/3 of the second level to a basal ganglia gate (triangle), and from stored item chunks in layer 5/6 of the second level to the features in layer 5/6 of the first level. The basal ganglia gate opens when a list chunk in layer 2/3 of the second level is chosen in response to a sequence of item chunks in level 4 of the cognitive working memory. Once the gate opens, top-down feedback from the cognitive working memory in layer 5/6 of the second level can resonate with active item features in level 5/6 of the first level, thereby triggering a coordinated resonant wave that can propagate through bottom-up and top-down signal exchanges throughout both levels of the cortical hierarchy and give rise to conscious percepts. [Reprinted with permission from Grossberg and Kazerounian (2011).]

## II. ART VS TRACE: HOW ARE REPEATED ITEMS REPRESENTED IN WORKING MEMORY?

Magnuson (2015) writes in several places (pp. 1481, 1483, and 1990) that cARTWORD cannot represent sequences

in working memory that have repeated elements. For example, he writes on p. 1481:

“Representing ordered sequences is a fundamental problem in neuroscience, and is particularly salient in the case of speech...models of speech processing must distinguish temporal orderings. Models must also distinguish repetitions of elements; the second /d/ in /dæd/ must be encoded as a second /d/ event, not just further evidence that /d/ has occurred. The same is true for word sequences, such as DOG EATS DOG...Only one model provides truly deep and broad coverage of phenomena in human speech perception and spoken word recognition while providing a basis for representing temporal order including repeated elements: The TRACE model.”

It is true that Grossberg and Kazerounian (2011) did not simulate acoustic sequences with repeated elements. The reason was simply that this was not an explanatory target of that article. However, the more general ART theory of speech and language perception does model how repeated elements can be stored in working memory (e.g., Bradski et al., 1994; Grossberg and Pearson, 2008; Silver et al., 2011) and quantitatively simulates neurophysiological data that support its Item-Order-Rank working memory model of how this is accomplished. In addition, the Item-and-Order

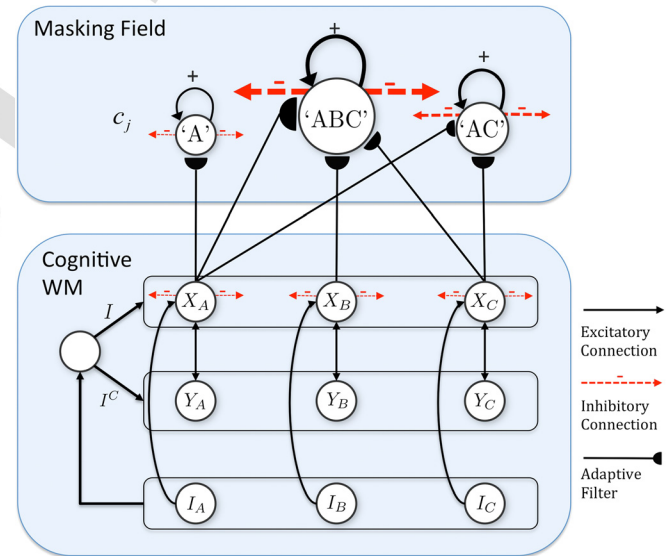


FIG. 2. (Color online) An Item-and-Order working memory for the short-term sequential storage of item sequences can activate a multiple-scale Masking Field list chunking network through a bottom-up adaptive filter. As in Fig. 1(b), the cognitive working memory uses two layers of cells with activities  $X$  and  $Y$ . The inputs are denoted by  $I$ . When embedded in a larger architecture like cARTWORD, these inputs are derived from item chunks, as in Fig. 1(b). Adaptive filter weights from the  $X$  activities to the Masking Field learn to selectively activate list chunks within the Masking Field. For simplicity, the Masking Field shows a single list chunk that receives one input (for the list “A”), two inputs (for the list “AC”), or three inputs (for the list “ABC”) from the cognitive working memory. The larger cell sizes and interaction strengths of the list chunks that categorize longer lists enable the Masking Field to choose the list chunk that currently receives the largest total input, and thus best predicts the sequence that is currently stored in the cognitive working memory. [Reprinted with permission from Kazerounian and Grossberg (2014).]

working memory model (Fig. 2) that was, for simplicity, simulated in Grossberg and Kazerounian (2011) can trivially be extended to an Item-Order-Rank working memory that is capable of storing sequences with repeated elements.

Magnuson (2015) is aware that other ART working memory models have simulated the short-term storage of sequences with repeated elements. He criticizes this fact in two ways: (1) Those demonstrations do not apply to speech and language, and (2) Item-Order-Rank working memories exhibit the same kinds of problems in representing temporal order that TRACE faces. However, both of these assertions are incorrect.

In partial response to the first concern: The ART item-and-order model in Grossberg and Pearson (2008) quantitatively simulated psychophysical data about linguistic working memory in humans using the same working memory model that was used to quantitatively simulate neurophysiological data about motor working memory in monkeys. An Item-Order-Rank working memory was used by Silver *et al.* (2011) to simulate neurophysiological data about the role of spatial working memories in the learning and control of saccadic eye movement sequences by monkeys; see Fig. 7 in the following text.

Why should a similar kind of working memory circuit be used for linguistic, motor, and spatial working memories? To understand this property, and also why the ART and TRACE mechanisms of temporal order are fundamentally different, one needs to review how Item-and-Order working memories are designed, how they are naturally extended to Item-Order-Rank working memories, and why a similar recurrent shunting on-center off-surround network design, properly regulated by rehearsal and inhibition-of-return mechanisms, is used to represent all linguistic, motor, and spatial working memories. Indeed, if an Item-Order-Rank working memory was used in the Grossberg and Kazerounian (2011) simulations, instead of an Item-and-Order working memory, it would have yielded the identical results, because the inputs used in these simulations included no repeated phonemes. Why this is so is explained in Sec. III L.

It should be noted in advance that none of the properties of ART working memories, and of the psychological and neurophysiological data that support them, can be explained by the TRACE mechanism of sequence representation. Indeed, these data contradict the key TRACE hypotheses. Why this is so can be explained in Sec. IV after the following summary of key properties of ART working memories and some of the data that support them.

### III. ART WORKING MEMORY AND LIST CHUNKING

#### A. The predicted link between working memory and list chunking

The Grossberg (1978a,b) neural model of working memory (WM) posits that a temporal stream of inputs is stored through time as an evolving spatial pattern of content-addressable item representations. These WM patterns are, in turn, unitized through learning into list chunk representations that can control context-sensitive behaviors. This WM model is called an Item-and-Order model because, in it, individual

nodes, or cell populations, represent list items, and the temporal order in which the items are presented is stored by an activity gradient across the nodes.

The classical work of Miller (1956) on the Magical Number Seven showed that a key functional unit in speech and language is abstract, namely, the “chunk,” that “the memory span is a fixed number of chunks [and] we can increase the number of bits of information that it contains simply by building larger and larger chunks, each chunk containing more information than before.” Chunks can thus be learned from multiple types of acoustic inputs that vary in size. Item-and-Order models like cARTWORD extend the classical work of Miller (1956) on chunks by defining the functional units that are proposed to exist at successive levels of the brain’s speech and language hierarchy. Instead of levels that process phonemes, letters, and words (e.g., McClelland and Rumelhart, 1981), Item-and-Order model levels represent distributed features, item chunks, and list chunks (Grossberg, 1978a,b, 1984, 1986). An item chunk selectively responds to prescribed patterns of activity across the distributed feature detectors within a prescribed time interval (e.g., a phoneme). A list chunk selectively responds to prescribed sequences of item chunks that are stored in working memory. The properties of these functional units can explain data about word superiority effect, list length effect, and related speech phenomena that are incompatible with alternative processing levels; see following text and Secs. IV–VI.

#### B. Correct temporal order is stored temporarily in the brain by a primacy gradient

A primacy gradient stores items in WM in the correct temporal order. In a primacy gradient, the first item in the sequence activates the corresponding item chunk with the highest activity, the item chunk representing the second item has the second highest activity, and so on, until all items in the sequence are represented. For example, a sequence “1-2-3” of items is transformed into a primacy gradient of activity with cells encoding “1” having the highest activity, cells encoding “2” with the second highest activity, and cells encoding “3” having the least activity. Item-and-Order working memories can, in a similar way, easily store sequences composed of the same items presented in different orderings.

#### C. Rehearsal and inhibition-of-return

How is a stored spatial pattern in WM used to recall a sequence of items performed through time? A rehearsal wave that is delivered uniformly, or non-specifically, from the basal ganglia to the entire WM enables read-out of stored activities (Fig. 3). The node with the highest activity is read out fastest and self-inhibits its WM representation. Self-inhibition of the item that is currently being read out helps to explain the cognitive concept of inhibition-of-return, which prevents perseveration on the most recent item to be performed. This self-inhibition process is repeated until the entire sequence is reproduced in its correct order and there are no active nodes left in the WM. How different rehearsal strategies may depend on experimental conditions, such as



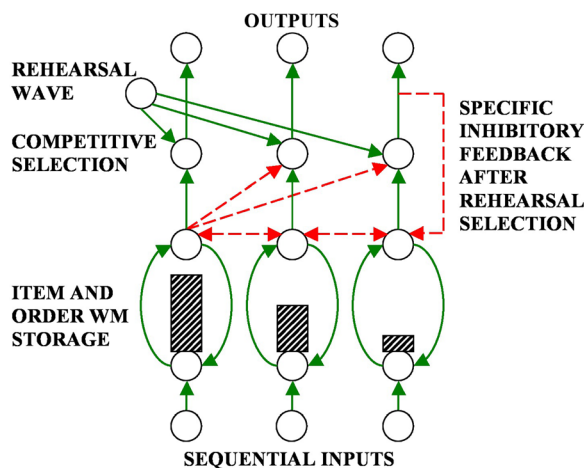


FIG. 3. (Color online) A temporal sequence of inputs creates a spatial pattern of activity across item chunks in an Item-and-Order working memory (height of hatched rectangles is proportional to cell activity). Relative activity level codes for item and order. A rehearsal wave allows item activations to compete before the maximally active item elicits an output signal and self-inhibits via feedback inhibition to prevent its perseverative performance. The process then repeats itself. Solid arrows denote excitatory connections. Dashed arrows denote inhibitory connections (adapted from Grossberg, 1978a).

during immediate free recall vs immediate serial recall, is discussed in Grossberg and Pearson (2008).

D. Competitive queuing and primacy models

Since Grossberg (1978a,b) introduced the Item-and-Order model, many modelers have used it and variations thereof (e.g., Boardman and Bullock, 1991; Bohland et al., 2010; Bradski et al., 1994; Bullock and Rhodes, 2003; Grossberg and Pearson, 2008; Houghton, 1990; Page and Norris, 1998). For example, Page and Norris (1998) used a primacy model to explain and simulate cognitive data about immediate serial order working memory, notably experimental properties of word and list length, phonological similarity, and forward and backward recall effects. The Item-and-Order model is also known as the competitive queuing model (Houghton, 1990).

E. Psychological and neurophysiological data confirm Item-and-Order predictions

Both psychophysical and neurophysiological data have supported the Grossberg (1978a,b) predictions that neural ensembles encode item order with relative activity levels and are reset by self-inhibition. For example, Farrell and Lewandowsky (2004) did psychophysical experiments in humans that studied the latency of responses following serial performance errors. They concluded that (p. 115)

“Several competing theories of short-term memory can explain serial recall performance at a quantitative level. However, most theories to date have not been applied to the accompanying pattern of response latencies...Data from three experiments...rule out three of the four representational mechanisms. The data support the notion that serial order is represented by a primacy gradient that is accompanied by suppression of recalled items [italics ours].”

Electrophysiological experiments have directly demonstrated these predicted properties. For example, macaque monkeys stored primacy gradients in their dorsolateral prefrontal cortex to control their performance of arm movement sequences that copy geometrical shapes (e.g., Averbeck et al., 2002). The predicted properties of a primacy gradient and a self-inhibitory form of inhibition-of-return are evident in these data [Fig. 4(a)], which were simulated [Fig. 4(b)] by a motor Item-and-Order working memory in the laminar cortical LIST PARSE model of Grossberg and Pearson (2008) that is a precursor of cARTWORD. An Item-Order-Rank spatial working memory in the listELOS model (Silver et al., 2011) was used to simulate neurophysiological data (Histed and Miller, 2006) about how microstimulation changes a stored primacy gradient and thus the order of sequential saccadic eye movement performance. These examples illustrate that the Item-and-Order model predicted the kind of working memory representation that occurs in mammalian brains more than 20 years before it was supported by neurophysiological experiments.

F. Bowed gradients during free recall

Item-and-Order working memories have been used to explain and predict many types of data about temporal order and how it is unitized through learning by list chunks. A key theme in this development surrounds the question: What is the longest list that the brain can store in working memory in the correct temporal order? Why can only relatively short lists be stored with the correct temporal order in vivo? In an Item-and-Order working memory, this question translates into: What is the longest primacy gradient that the working memory can store? And why is it so short? Indeed, in free recall tasks, if too long a list is presented, a bowed serial position curve is often observed, such that items at the beginning and the end of the list are performed earliest, and with the highest probability of recall (Fig. 5).

Grossberg (1978a,b) noted that these free recall properties have a natural explanation if the working memory gradient that stores the list items is also bowed, with the first and last items having the largest activities, and items in the middle having less activity. If the item with the largest activity is read out first, whether at the list beginning or end, and then self-inhibits its item representation to prevent preservation, then the next largest item will be read out, and so on in the order of item relative activity. The greater probability of items being recalled at the beginning and end of the list also has a simple explanation because items that are stored with larger activities have greater resilience against perturbation by cellular noise. Transpositions of order recall are also easily explained because they belong to items with similar stored activities.

G. Magical numbers four and seven: Immediate and transient memory spans

What is the longest primacy gradient that can be stored? The classical Magical Number Seven, or immediate memory span, of  $7 \pm 2$  items that is found during free recall (Miller, 1956) estimates the upper bound. Grossberg (1978a)

303 distinguished between the immediate memory span and the  
 304 then new concept of *transient memory span*. The transient  
 305 memory span was predicted to be the result of recall from  
 306 short-term working memory without the benefit of top-down  
 307 read-out of learned expectations from list chunks. That is,  
 308 the transient memory span is the longest list for which a

primacy gradient may be stored in short-term memory solely  
 as the result of bottom-up inputs. In contrast, the immediate  
 memory span was predicted to arise from the combined  
 effect of bottom-up inputs and top-down long-term memory  
 read-out. Grossberg (1978a) proved that the read-out of top-  
 down long-term memories can only increase the maximal

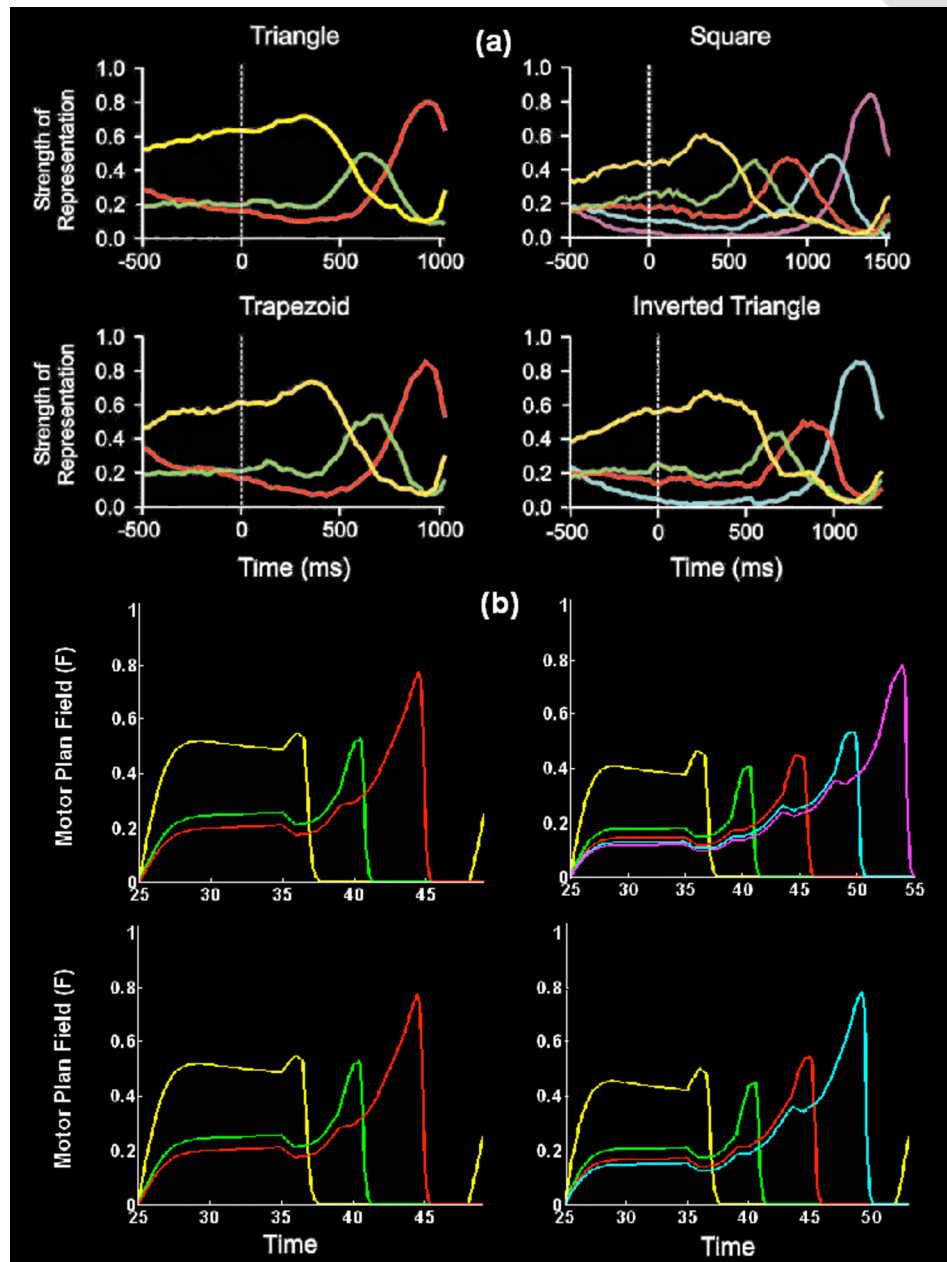


FIG. 4. (Color online) Neurophysiological data and simulations of monkey sequential copying data. (a) Each plot shows the relative strength of representation to control drawing of each segment for each time bin (at 25 ms) of the task. The number of movement segments is due to the starting positions of each movement sequence on the corresponding geometrical figure. Time 0 indicates the onset of the template. Lengths of segments were normalized to permit averaging across trials. Plots show parallel representation of segments before initiation of copying. Further, rank order of strength of representation before copying corresponds to the serial position of the segment in the series. The rank order evolves during the drawing to maintain the serial position code. At least four phases of the Averbeck *et al.* [2002; Fig. 9(a)] curves should be noted: (1) presence of a primacy gradient; that is, greater relative activation corresponds to earlier eventual execution in the sequence during the period prior to the initiation of the movement sequence (period ~500–400 ms); (2) contrast enhancement of the primacy gradient to favor the item to be performed (greater proportional representation of the first item) prior to first item performance (period ~100–400 ms); (3) inhibition of the chosen item's activity just prior to its performance and preferential relative enhancement of the representation of the next item to be preformed such that it becomes the most active item prior to its execution (period ~400 ms to near sequence completion); and (4) possible re-establishment of the gradient just prior to task completion. (Reprinted with permission from Averbeck *et al.*, 2002.) (b) Simulations of item activity across the motor plan field of the LIST PARSE model for three, four, and five item sequences vs simulation time. The secondary increases in activity after all the stored items are performed increase in their original temporal order. (Reprinted with permission from Grossberg and Pearson, 2008.)

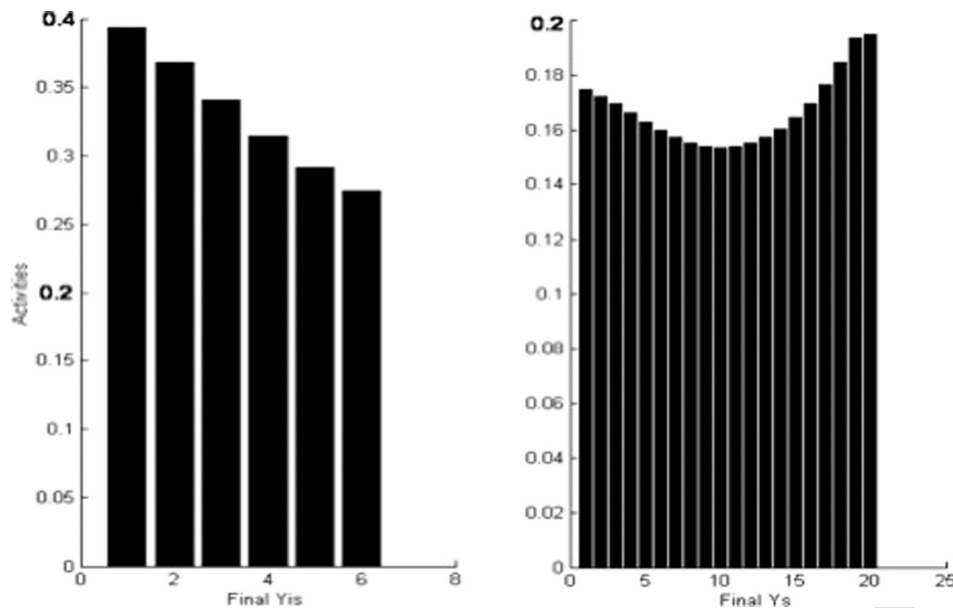


FIG. 5. The simulation to the left shows a primacy gradient of activation that is stored in working memory in response to presenting a list of seven items. The simulation to the right shows how this primacy gradient becomes a bowed gradient when more items are presented. Note, in addition, that the activities of the stored items in response to the longer list are smaller due to the self-normalizing network competition, which realizes the Normalization Rule. [Reprinted with permission from Grossberg and Pearson (2008).]

primacy gradient that can be stored and thus that the immediate memory span is longer than the transient memory span. Given an estimated immediate memory span of approximately seven items, it was estimated that the transient memory span should be approximately four items. Cowan (2001) has beautifully summarized data showing that when the influences of long-term memory and grouping effects are minimized, there is indeed a working memory capacity limit of  $4 \pm 1$  items. There is thus also a Magical Number Four, as predicted. As will be discussed in Sec. V, neither magical number can be explained by the TRACE model because of how it represents temporal order information.

#### H. LTM Invariance Principle: Designing working memory to learn stable list chunks

Why is the transient memory span so short? To explain this, Grossberg (1978a,b) noted that it is pointless to store sequences temporarily in short-term working memory if they cannot lead to learning of unitized list chunks. And without such learning, it would be impossible to learn language, motor skills, or spatially organized movements or navigation routes. Grossberg (1978a,b) therefore predicted that all working memories for the short-term storage of items are designed to enable learning and stable memory of list chunks and showed that two simple postulates imply these properties: The Long Term Memory (LTM) Invariance Principle and the Normalization Rule. Item-and-Order working memories were derived from these postulates. Grossberg (1978a,b) then proceeded to demonstrate mathematically how these postulates can be realized and thereby derived laws for Item-and-Order working memories, and how they generate primacy and bowed gradients to help explain free recall data. Since this early derivation, the understanding of how these working memories are realized *in vivo* has been incrementally refined (e.g., Bradski *et al.*, 1992, 1994), leading most recently to laminar cortical models of how prefrontal circuits realize Item-Order-Rank working memories (Grossberg and Pearson, 2008; Silver *et al.*, 2011).

The LTM Invariance Principle implies that novel sequences of items may be stored and chunked through learning in a way that does not destabilize memories of previously learned chunk subsequences. Without such a property, longer chunks (e.g., for MYSELF) could not be stored in short-term working memory without risking the catastrophic forgetting of previously learned memories of shorter chunks (e.g., for MY, SELF, and ELF). Language, motor, and spatial sequential skills would then be impossible. The LTM Invariance Principle insists that if bottom-up inputs activate a familiar subset chunk, such as the word MY, then the arrival of the remaining portion SELF of the novel word MYSELF during the next time interval will not erode the previously learned weights that activate the list chunk of MY. This principle is achieved mathematically by preserving the *relative activities*, or ratios, between previously stored working memory activities as new items are presented through time. Newly arriving inputs may, however, alter the *total activity* of each active cell across the working memory.

How does preserving activity ratios help to stabilize previously learned categories? These activities send signals to the next processing stage, where the category cells are activated. The signals are multiplied by adaptive weights, or LTM traces, before the net signals activate their target categories (Fig. 2). The total input to a category thus multiplies a *pattern*, or vector, of activities times a *pattern*, or vector, of LTM traces. By preserving relative activities, the relative sizes of these total inputs to the category cells do not change through time and thus nor do the corresponding LTM patterns that track these activities when learning occurs at their category cells.

Consider, for example, what happens as bottom-up acoustic inputs arrive in time, activating their corresponding chunked (word) representations. As these inputs arrive, a chunk such as “MY” may become active once it receives all or most of its expected bottom-up input. If the acoustic inputs are then followed immediately by silence, the chunked representation of MY could stably learn from the stored STM pattern of activity that first supported it.



On the other hand, as is often the case, the acoustic inputs might not simply be followed by silence but rather by further acoustic information (e.g., the inputs corresponding to the super-set word or chunk “MYSELF”). In this case, the newly arriving inputs could drastically alter the pattern of activation reverberating in STM if the LTM Invariance Principle did not hold. As a result, the chunked representation for MY would begin to degrade as the weights to MY change in response to the now altered STM pattern in working memory. If, however, the newly arriving inputs (corresponding to “SELF”) leave intact the relative pattern of activity in STM of the already occurring acoustic inputs (corresponding to MY), a new chunk for the full superset word (in this case, MYSELF) could be learned without destabilizing the already learned LTM pattern for its subset components (e.g., MY).

The Normalization Rule insists that, when a working memory is activated, its maximal activity tends to be independent of the number of items stored in working memory. Thus if more items are stored in working memory, then each item tends to be stored with less activity (see Figs. 4 and 5). This normalization property implies the familiar *limited capacity* of working memory by redistributing, rather than simply adding, activity when new items are stored.

#### I. Bowed gradients for long lists follow from self-stabilizing memory

Grossberg (1978a,b) mathematically proved that if both the LTM Invariance Principle and the Normalization Rule hold in a working memory, then there is a transient memory span; that is, lists no longer than the transient memory span can be stored as a primacy gradient and thus recalled in their correct temporal order. If a list is longer than the transient memory span, the primacy gradient that is initially stored will evolve into a *bowed gradient* as more items are stored.

In other words, the ability of a working memory to enable learning and stable memory of stored sequences implies an upper bound on the length of lists that can be temporarily stored in the correct temporal order. The bowed serial position curves of free recall data could then be understood as the price paid for being able to rapidly learn, and stably remember, language and sequential spatial and motor skills.

These results hold when the same amount of attention is paid to each item as it is stored. If attention is not uniform across items, then multi-modal bows can occur, as during von Restorff (1933) effects, also called isolation effects (Hunt and Lamb, 2001), which occur when an item in a list “stands out like a sore thumb” and is thus more likely to be remembered than other list items.

#### J. Universal design for linguistic, spatial, and motor working memories

If all working memories obey these postulates, then all linguistic, motor, and spatial working memories should have a similar design. Psychological and neurobiological data have supported this prediction as reviewed in Grossberg and Pearson (2008), Silver *et al.* (2011), and Grossberg (2013). Such data exhibit similar data patterns across modalities,

including bowing effects on performance order and error probabilities. In particular, the LIST PARSE model of Grossberg and Pearson (2008) used a prefrontal *linguistic* working memory to quantitatively simulate psychophysical data about immediate serial recall, and immediate, delayed, and continuous distractor free recall; and a similarly designed prefrontal *motor* working memory to quantitatively simulate neurophysiological data about sequential recall of stored motor sequences (Fig. 4). The lisTELOS model of Silver *et al.* (2011) used a prefrontal *spatial* working memory to quantitatively simulate neurophysiological data about the learning and planned performance of saccadic eye movement sequences.

Such results provide accumulating evidence for the prediction that all working memories have a similar design because they all need to obey the LTM Invariance Principle. List chunks in all these modalities can then be learned and stably remembered, and cross-modality interactions of such working memories can occur because they all obey variations of the same circuit design. Because of this shared design, it becomes easier to understand how language in young children can begin to develop in a way that parallels the motor behaviors of adult teachers during mutual play (Bruner, 1975) or how sign language by hearing adults can coordinate signing with speaking (Neville *et al.*, 2002).

It remains to answer the nagging question: What is this shared design?

#### K. Recurrent shunting on-center off-surround networks embody working memories

Are postulates such as the LTM Invariance Principle and the Normalization Rule too sophisticated to be discovered by evolution? This type of concern arises whenever one confronts the variety of intelligent brain competences, whether it is about the origins of working memory, numerical representation, or handwriting. This concern was allayed by the demonstration that both the LTM Invariance Principle and the Normalization Rule occur within a ubiquitous neural design; namely, a recurrent on-center off-surround network of cells that obey the membrane equations of neurophysiology, otherwise called shunting dynamics. How such recurrent shunting networks process ratios (LTM Invariance Principle) and conserve total activity (Normalization Rule) was mathematically proved in Grossberg (1973) and reviewed in Grossberg (1978a, 1980). Bradski, Carpenter, and Grossberg (1992, 1994) went on to prove theorems about how Item-and-Order recurrent shunting working memory networks generate primacy and bowed gradients, among other properties, as a function of network parameters.

In brief, the excitatory feedback due to the recurrent on-center interactions in such a network helps to store an evolving spatial pattern of activities in response to a sequence of inputs. The recurrent shunting off-surround, in concert with the on-center, helps to preserve the relative activities that are stored. A volitional rehearsal wave from the basal ganglia enables the highest stored activity to be read out first, and self-inhibitory feedback prevents perseverative performance of this most highly activated cell population, thereby

enabling less active populations to be performed (Fig. 3), while the network as a whole gradually renormalizes its activity through time.

The effects of recurrent inhibition are evident in the data and simulation within Fig. 4: After the next-to-last item is performed, the population storing the last item is disinhibited and reaches the highest activity through time of any population that stored the list.

#### L. Storing lists with multiple item repetitions: Item-Order-Rank coding

In its simplest form, an Item-and-Order working memory does not represent the same item in multiple positions, or *ranks*, of a list. However, humans can easily do this, and there are many examples in cognitive data of sensitivity to list position (e.g., Henson, 1998), including spoonerisms, wherein phonemes or syllables in similar positions in different words are selectively interchanged; e.g., “hissed my mystery lesson.” It is also known that the activity of some neurons in prefrontal cortex for a given list item is sensitive to the rank of that item within the sequence (e.g., Averbeck *et al.*, 2003; Barone and Jacobs, 1989; Funahashi *et al.*, 1997; Inoue and Mikami, 2006; Kermadi and Joseph, 1995; Ninokura *et al.*, 2004). Error data in human serial recall experiments also indicate that rank information is available that some models of serial recall have incorporated (see Grossberg and Pearson, 2008 for a review).

Despite some positive results from rank-based models, Farrell and Lewandowsky (2004) have, as noted in the preceding text, shown that latency data from error trials can be best explained by models that use a primacy gradient and self-inhibition (i.e., Item-and-Order models) but not by those that use rank alone. Some Item-and-Order models incorporated rank information (e.g., Bohland *et al.*, 2010; Bradski *et al.*, 1994). Indeed, Bradski *et al.* (1994) proposed the first Item-Order-Rank working memory model that can incorporate rank-order coding into an Item-and-Order working memory to represent item repeats at arbitrary list positions; e.g., ABACBD.

The LIST PARSE model (Grossberg and Pearson, 2008, Fig. 18) deepened understanding of where such rank order coding may arise in the brain, and how it gets represented in working memory. This model predicted how an Item-Order-Rank working memory can be created in prefrontal cortex by deriving its rank selectivity from the analog spatial representations of numbers in the parietal cortex via parietal-prefrontal projections. This prediction built upon the Spatial Number Network, or SpaN, model of Grossberg and Repin (2003) that simulated how the known analog map of ordered numerical representations in inferior parietal cortex may control the ability of animals and humans to estimate and compare sufficiently small numerical quantities. The predicted properties of SpaN model parietal neurons were supported by neurophysiological data of Nieder and Miller (2004), who also studied the prefrontal projections of these parietal numerical representations.

In such an Item-Order-Rank working memory, a spatial gradient of activity still represents temporal order with the

most active cell population being performed first. To enable the storage of the same item at multiple list positions in this gradient, the parietal-prefrontal projection of the analog spatial map of parietal numerical representations embeds numerical *hypercolumns* into the prefrontal working memory, so that each item is stored in a different position in its hypercolumn if it is repeated in the list more than once (Fig. 6). A single numerical hypercolumn that represents a particular list item can store that item in multiple list positions, just as a positional hypercolumn in the visual cortical map of the primary visual cortex can selectively respond to multiple orientations at that position (Hubel and Wiesel, 1962, 1963). For example, to store and perform in its correct order the short list ABAC, item A would be stored in two different positions within its hypercolumn, whereas items B and C would be stored only in one position in their respective hypercolumns. A primacy gradient of activity would still represent the temporal order of a short stored list, whether or not it had repeated items. Davis (2010) has proposed a related concept to model letter repetitions during visual word identification.

The recurrent on-center off-surround network that stores items in an Item-Order-Rank working memory can still have the same simple anatomy as it does for an Item-and-Order

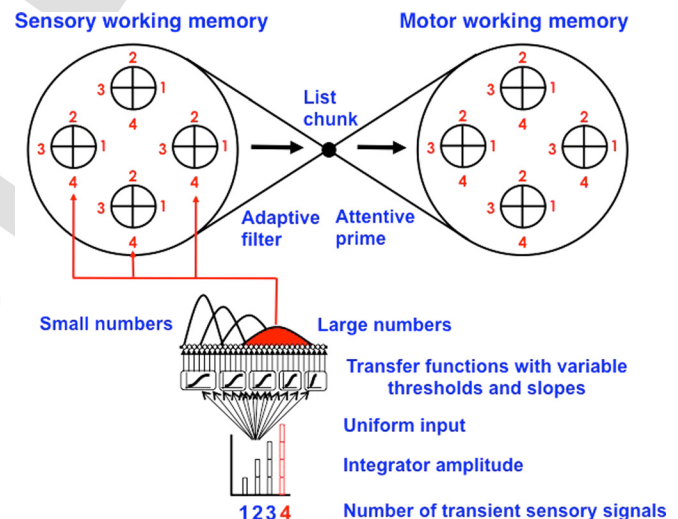


FIG. 6. (Color online) How inputs from the analog number field that is found in the parietal cortex can generate rank-sensitive inputs (see numbers 1, 2, 3, and 4) to a prefrontal Item-and-Order working memory that convert it into an Item-Order-Rank working memory that can store the same item at multiple positions in a list. Each circle in the sensory working memory represents a different item. The numerical hypercolumn for each item has, in this example, four cell populations that can be activated by the parietal numerical map after one, two, three, or four items have been presented. The maximum number 4 was chosen for ease of exposition. In response to a sequence of sensory inputs, an integrator cell population increases its activity proportionally and broadcasts this activity to the entire parietal numerical map. The map responds by shifting its locus of maximal activity to the right as larger numbers of inputs occur [see Grossberg and Repin (2003) for an explanation of how this is proposed to happen]. Each parietal locus projects to a corresponding position in multiple prefrontal numerical hypercolumns. A prefrontal cell can fire only if it receives an item input *and* a numerical input. Thus in response to a list ABA, the item representation for A will be activated in hypercolumn slots 1 and 3, and the item representation for B will be activated in hypercolumn slot 2. A primacy gradient will develop over these three active item representations. [Reprinted with permission from Grossberg and Pearson (2008).]



585 working memory that does not store repeats: Self-excitatory  
 586 feedback from each cell population to itself and a broad off-  
 587 surround that equally inhibits all other populations in the  
 588 working memory.

#### 589 M. Simulating Item-Order-Rank working memory cells 590 in prefrontal cortex

591 The lisTELOS model of Silver *et al.* (2011) built upon  
 592 the TELOS model of Brown, Bullock, and Grossberg (2004)  
 593 to implement the Grossberg and Pearson (2008) proposal by  
 594 simulating an Item-Order-Rank model of spatial working  
 595 memory in prefrontal cortex, and its interactions with other  
 596 brain regions, to control working memory storage, planning,  
 597 and execution of saccadic eye movement sequences. The  
 598 model predicts and simulates how the supplementary eye  
 599 fields (SEF) may select saccades from sequences that are  
 600 stored in this prefrontal working memory. It also predicts  
 601 and simulates how SEF may interact with downstream  
 602 regions such as the frontal eye fields during memory-guided  
 603 sequential saccade tasks and how the basal ganglia may con-  
 604 trol the flow of information through time. Model simulations  
 605 reproduce behavioral, anatomical, and electrophysiological  
 606 data under multiple experimental paradigms, including visu-  
 607 ally and memory-guided single and sequential saccade tasks,  
 608 and behavioral data from SEF microstimulation paradigms.  
 609 In particular, lisTELOS simulates neurophysiological prop-  
 610 erties of rank-sensitive working memory cells in monkey  
 611 SEF, thereby clarifying how Item-Order-Rank working

612 memories store sequences of repeated target positions in  
 613 brain *spatial* working memories (Fig. 7).

614 Given that all working memories have a similar network  
 615 design in order to realize the LTM Invariance Principle and  
 616 Normalization Rule, the Item-Order-Rank working memory  
 617 of the lisTELOS model is a prototype for linguistic and  
 618 motor working memories, no less than for spatial working  
 619 memories. Indeed, the basal ganglia play a gating function in  
 620 cARTWORD [Fig. 1(b)] that is similar to its role in  
 621 lisTELOS.

622 The preceding summary thus shows that ART models of  
 623 temporal order information can, and have, simulated chal-  
 624 lenging data about the storage of lists with repeated items in  
 625 linguistic, motor, and spatial working memories. Moreover,  
 626 these Item-Order-Rank working memories embody design  
 627 principles about how the brain can stably learn list chunks,  
 628 such as syllables and words, because of the way that these  
 629 working memories are designed. None of these principles,  
 630 mechanisms, or data can, in principle, be explained by  
 631 TRACE.

#### 632 IV. REBUTTING MAGNUSON'S CLAIMS AGAINST 633 cARTWORD AND FOR TRACE

634 With this background of concepts, data, and their  
 635 explanations, we can now respond to various of Magnuson's  
 636 criticisms of cARTWORD and, by extension, the ART fam-  
 637 ily of speech and language models to which it contributes, as  
 638 well as his claims for the TRACE model. Section V will  
 639 present additional ART design principles and mechanisms

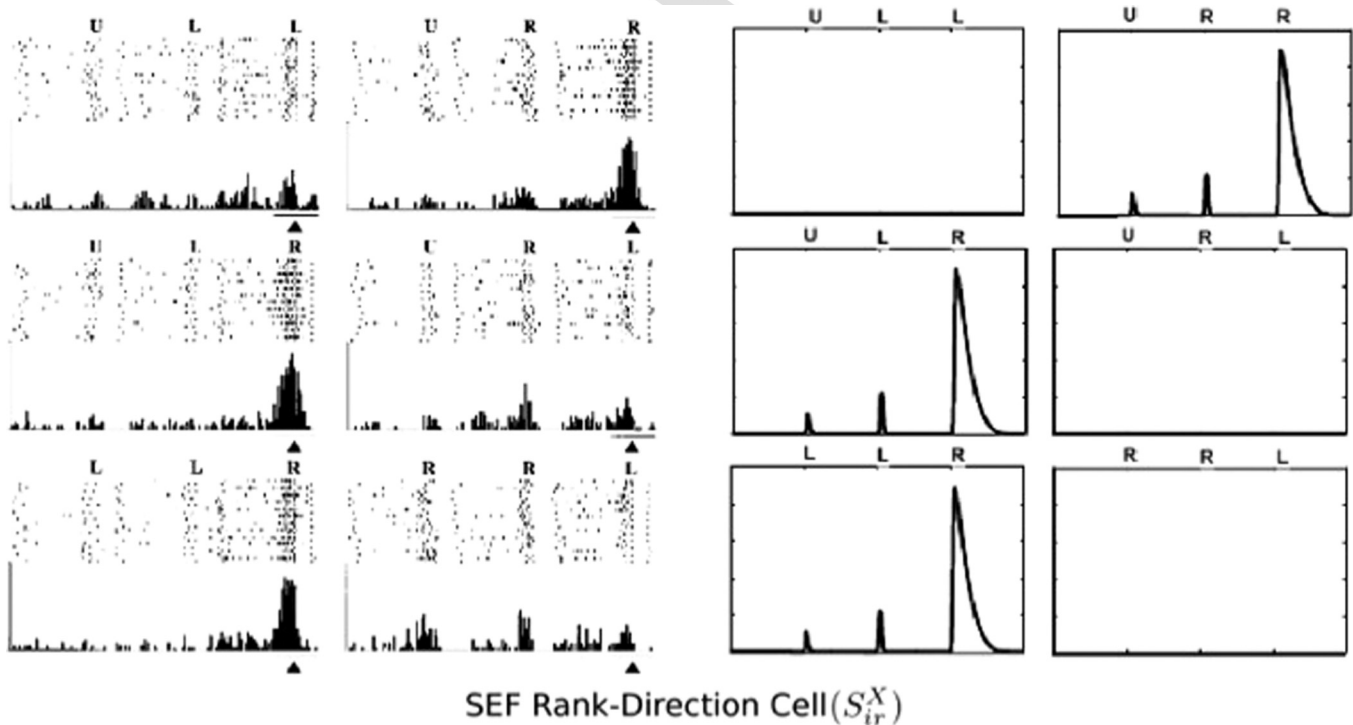


FIG. 7. Left two columns: SEF rank-direction cell that responds phasically before rightward saccades that occur at the third ordinal position in a sequence of saccades. Each row, from left to right, shows the cell's responses when the first, second, and third saccades occur. Symbols U, L, and R denote upward, left, and right saccades. The cell responds vigorously only when the third saccade in the sequence moves to the right, as summarized in the left column and last two rows, and the right column and top row. [Data adapted with permission from Isoda and Tanji (2002).] Right two columns: SEF rank-direction model cell activity  $S_{ir}^X$  of a cell that codes the same properties. [Simulations reprinted with permission from Silver *et al.* (2011).]

that have been used to explain other data that cannot, in principle, be explained by TRACE. This review will, in particular, explain how ART can represent and store sequences with repeated words, thereby contradicting another criticism of Magnuson.

#### A. Claim that cARTWORD cannot, in principle, store repeated items in working memory

Magnuson asserts in multiple places that

“First and most crucially, cARTWORD can represent sequences, but *cannot* [italics his] represent sequences that contain repeated elements....This rules out cARTWORD as a plausible model of sequence encoding for word recognition” (p. 1483).

The cARTWORD simulations of Grossberg and Kazerounian (2011) did not include repeated elements because that was not the explanatory goal of this article. However, because cARTWORD uses an Item-and-Order working memory, it can easily be extended to include rank-sensitivity in an Item-Order-Rank working memory to simulate speech and language data where rank sensitivity is needed, without undermining any results that are derived where it is not, as was explained in Sec. III L.

If Magnuson’s claim about the rank-sensitivity of cARTWORD is to be taken literally (e.g., “cARTWORD *cannot* represent sequences that contain repeated elements”), then it must be interpreted as a claim that, *in principle*, such an extension of cARTWORD is impossible. That claim is false.

#### B. Claim that IOR working memory needs time-specific slices and slice-specific inhibition

Magnuson does discuss the Silver *et al.* (2011) use of an Item-Order-Rank working memory on p. 1483:

“...it is not clear how to extend it sufficiently for speech, where each IOR [Item-Order-Rank] node might need to be capable of coding dozens of time steps (again reflecting perhaps the duration of echoic memory). Furthermore...time-specific inhibitory connectivity between IOR nodes would likely be required, as in TRACE. Indeed, extending the IOR approach in these ways would result in a mechanism for encoding temporal sequences not terribly different from that employed by TRACE, since each “pie slice” in an IOR phoneme node because a time-specific representation of that phoneme—exactly the reduplication problem cARTWORD claims to avoid. Similar problems necessarily arise at supra-phonemic levels of encoding (cARTWORD’s list chunks and lexical nodes); repeated words will be as problematic as repeated phonemes, and the IOR framework must again be extended to include many time-specific representations for words.”

These claims are mistaken. To understand this misunderstanding, one needs to realize that TRACE creates a new

“slice” that reduplicates each phonetic item at every time. If 1000, or 10 000, time steps have occurred since a phonetic item occurred just once, then there are 1000, or 10 000, duplications of this phonetic item in TRACE. This representation is physically implausible and would cause a major combinatorial explosion when dealing with natural speech. Such a representation also cannot support learning of speech in real time and has no neurobiological evidence to support it. Indeed, because of this reduplication property, TRACE has no representation of real time as explained in the following text and in Sec. VII D.

In contrast, there is now abundant psychological and neurobiological evidence of Item-Order-Rank coding, some of it summarized in Sec. III. There is no replication of each phonemic item through time in an Item-Order-Rank working memory. Its unique content-addressable item chunks get activated just once. If a phonemic item occurs more than once in a sequence, then its unique rank-sensitive representations get activated just once, as neurophysiological data from prefrontal cortex have shown; e.g., Fig. 7. There is no need for “time-specific inhibitory connectivity between IOR nodes.” Instead, as noted in Sec. III L, a uniform off-surround from every cell to all other cells is sufficient whether or not there is rank-sensitive coding. These off-surrounds respond in real time to whatever combination of item chunks is activated by a particular input sequence.

Magnuson’s discussion seems to conflate the passage of real time with “time steps,” as in his phrase “coding dozens of time steps.” This is indeed a property, and a problem, of the TRACE model. There is no evolution of real time in TRACE because it formally creates new time slices to represent each new sequential input. In contrast, an Item-Order-Rank working memory represents “temporal order” not time steps. When one considers temporal order information, which is studied ubiquitously in the cognitive psychology of language, motor control, and space, one needs to explain the Magical Numbers Four and Seven, which the Item-and-Order framework explains in a principled way, and indeed predicted the Magical Number 4 and its explanation (Sec. III G). These Magical Numbers, and the bowed gradients that occur when they are exceeded, have no natural explanation within TRACE’s myriad of artificially created “slices.”

#### C. TRACE is incompatible with psychophysical and neurobiological data

Magnuson notes (p. 1482) that “McClelland *et al.* (2014) remind us that TRACE is not meant to provide a neural-level solution. ‘The structure of the TRACE model should not be viewed as a literal claim about the neural mechanism.’” However, TRACE’s way of representing sequences is directly contradicted by psychophysical and neurobiological data about sequence representation, some of it summarized in the preceding text. These data also directly support an Item-Order-Rank model of working memory and also support the prediction of the LTM Invariance Principle that there exists an intimate linkage between mechanisms for storing sequences in short-term working memory and for

learning list chunks of these sequences. A nice example of this linkage between STM and LTM during the learning of novel arm movement sequences is provided by human psychophysical data of [Agam et al. \(2007\)](#).

If the foundational hypotheses of sequence representation in TRACE are wrong, then there is no logical reason to believe any conclusion that is derived from them. Any resemblance between data and a TRACE simulation must therefore be interpreted as a simulation of weak model-independent properties of the data, ones that do not constrain, or explain, how the brain actually works. Indeed, [Magnuson et al. \(2012\)](#) himself has written about the importance of such a model failure:

“[M]odel success or failure can be linked to one of four levels of decreasing importance: Theory, parameters, or linking hypotheses. As we have just discussed, a ‘failure’ or ‘success’ due to improper linking hypotheses is not informative in the same way that an experimental failure due to improper operational definitions is not informative. A failure at the level of theoretical assumptions is of greatest interest and holds the greatest possibility for progress (i.e., theory falsification).”

Magnuson (p. 1482) goes on to write that “while TRACE can be fairly criticized for its reduplication mechanism, it is not wildly implausible.” In reality, its item replication mechanism is not just implausible; it has been directly disconfirmed by neurophysiological evidence. To support the claim that TRACE is “not wildly implausible,” Magnuson asks the reader to

“consider a model of echoic memory based on a frequency-by-time matrix (perhaps 1 to 4 s in duration, the approximate duration of echoic memory for speech; [Connine et al., 1991](#); [Watkins and Watkins, 1980](#)) with the simplifying assumption that time is discretized into steps. Now as auditory input is encountered at time 0, the time = 0 frequency vector would encode the input on position 0. At time = 1, the time = 0 vector would shift to position 1, and the new input would be encoded at slot 0 (and at some point, the system would have to ‘wrap,’ recycling position 0, etc.). It is a small step to imagine a similar memory where frequency vectors would be replaced or augmented by phonemic vectors, or some other phonetic or phonemic recoding. As each phoneme is processed, the matrix corresponding to the previous phonological state could be shifted on the memory matrix, replaced with the current one aligned at slot 0.”

This is the primary assumption of the once-popular [Atkinson and Shiffrin \(1971\)](#) shift-register model of working memory, which is not cited. Although this model was a useful contribution 40 years ago, it has long ago been discarded because it is neurally impossible and incapable of learning.

## D. The explanatory power of ART vs TRACE

[Magnuson \(2015\)](#) claims in several places that the explanatory range of cARTWORD is far inferior to that of TRACE; e.g., his claims that cARTWORD “has been applied to only one phenomenon (phoneme restoration)” (p. 1481) and that “no other model comes close to the depth and breadth of TRACE’s coverage” (p. 1483). These claims are based upon the fact that the [Grossberg and Kazerounian \(2011\)](#) article focused on providing the first real-time neural simulation of phonemic restoration in which future context can disambiguate noise-occluded previously occurring phonemes and generate a temporally evolving representation of the restored sequence that is consciously heard, including the order, timing, and amplitude with which the restored phoneme is heard. Magnuson’s criticism is, however, misleading in two major ways:

- (1) As we have noted already, cARTWORD is just one contribution to 40 years of incremental development of the ART theory of speech and language learning, perception, and recognition. The models PHONET, ARTPHONE, ARTWORD, cARTWORD, ARTSPEECH, and NormNet, as well as SPINET and ARTSTREAM, all embody the same core design principles. Each incremental refinement of these models includes the same core mechanisms of working memory storage and unitization of sequences in working memory to selectively activate list chunks that can represent phonemes, syllables, and words. This ART theory has explained and predicted many psychological data that are outside the explanatory range of TRACE. Many of these data describe how consciously heard speech sounds depend on past or future linguistic contexts that can span 100–150 ms, and how the brain attempts to form a rate- and speaker-independent representation of variable-rate and variable-speaker speech from multiple auditory streams (e.g., [Ames and Grossberg, 2008](#); [Boardman et al., 1999](#); [Cohen and Grossberg, 1986](#); [Cohen et al., 1995](#); [Grossberg et al., 1997](#); [Grossberg, 1978a,b, 1984, 1986, 2003](#); [Grossberg et al., 2004](#); [Grossberg and Myers, 2000](#); [Grossberg and Stone, 1986a,b](#)). Because TRACE has no representation of the passage of real time, it can explain none of these data.
- (2) cARTWORD is a neural model of speech that is defined by a hierarchy of cortical processing regions whose networks embody cells in *laminar* cortical circuits [Fig. 1(b)]. Variations of these same circuits have also been used in the three-dimensional (3D) LAMINART model to explain data about 3D vision and figure-ground separation ([Cao and Grossberg, 2005, 2012](#); [Fang and Grossberg, 2009](#); [Grossberg and Swaminathan, 2004](#); [Grossberg and Versace, 2008](#); [Grossberg and Yazdanbaksh, 2005](#); [Grossberg et al., 2008](#); [Raizada and Grossberg, 2003](#)) and in the LIST PARSE model to simulate data about immediate serial recall; immediate, delayed, and continuous distractor free recall; and sequential planned arm movement control ([Grossberg and Pearson, 2008](#)). Thus cARTWORD is part of a larger theory of how the cerebral cortex works, which has



already explained how variations on the same canonical laminar cortical circuits can support several kinds of biological intelligence.

cARTWORD hereby contributes to the rapidly emerging paradigm of laminar computing. Laminar computing describes how the cerebral cortex is organized into layered circuits whose specializations can support all forms of higher-order biological intelligence. Indeed, the laminar circuits of cerebral cortex seem to realize a revolutionary computational synthesis of the best properties of feedforward and feedback processing, digital and analog processing, and data-driven bottom-up processing and hypothesis-driven top-down processing (Grossberg, 2007, 2013). The fact that variations of the same canonical laminar cortical circuits, supported by data about identified neurons, have been used to simulate challenging data about vision, speech, and cognition provides converging evidence that the models that embody these circuits are tapping real brain designs. TRACE cannot make any such claim.

The ART neural models of speech and language are also part of the more comprehensive ART cognitive and neural theory of how the brain autonomously learns to attend, recognize, and predict objects and events, and sequences of them, in a changing world. ART currently has the broadest explanatory and predictive range, and all of its main predictions have been supported by psychological and neurobiological data; see Grossberg (2013) for a review. This explanatory and predictive range emerges from ART analyses of mechanistic links between processes of Consciousness, Learning, Expectation, Attention, Resonance, and Synchrony (the CLEARS processes) during both unsupervised and supervised learning. These general design principles and mechanisms are specialized in ART architectures for speech and language.

TRACE, in contrast, cannot explain *any* neural data because the main representations of TRACE have been directly contradicted by neurophysiological data; e.g., Figs. 4 and 7. The mechanisms of TRACE capture neither the design heuristics nor the mechanistic properties of brain representations. Thus whereas ART is a principled cognitive and neural theory that has rapidly expanded its explanatory and predictive range over the years, TRACE offers a computational metaphor.

## V. LEARNING CHUNKS OF VARIABLE LENGTHS AND SEQUENCES OF REPEATED WORDS

### A. Masking Field working memory chunks variable-length lists

This section describes ART properties that contradict another of Magnuson's claims, one that must be faced by all models of language; namely, that "repeated words will be as problematic as repeated phonemes" (p. 1493). The section also reviews ART explanations that contradict another strong claim of Magnuson, namely, that "only one model provides truly deep and broad coverage of phenomena in human speech perception and spoken word recognition while providing a basis for representing temporal order including

repeated elements: The TRACE model." This claim is countered, first, by summarizing some of the other data for which ART has proposed principled explanations but which TRACE cannot explain; second, by demonstrating that claims about data that TRACE can explain are inaccurate; and third by the fact that in subsequent modeling efforts, Magnuson himself has attempted to move beyond the representations of temporal order as used in TRACE and IA models. For example, the ART explanation of how sequences of repeated words, not just repeated phonemes, are represented in the brain also helps to explain the Magical Numbers Four and Seven that directly contradict the TRACE representation of temporal order.

A neural explanation of the Magical Numbers Four and Seven was first given using an Item-and-Order working memory that is called a Masking Field (Fig. 2; Grossberg, 1978a, 1984, 1986). A Masking Field is a specialized type of Item-and-Order working memory. As with all Item-and-Order working memories, it is defined by a recurrent on-center off-surround network the cells of which obey the membrane equations of neurophysiology. In a Masking Field, however, the "items" are *list chunks* that are selectively activated, via a bottom-up adaptive filter, by prescribed sequences of items that are stored in an Item-and-Order working memory at an earlier processing level (Figs. 1 and 2). In other words, Masking Field cells represent list chunks because each of them is activated by a particular temporal sequence, or list, of items that is stored within the Item-and-Order working memory at the previous processing level. Thus both levels of the item and list processing hierarchy are composed of working memories that obey similar laws.

For Masking Field list chunks to represent lists (e.g., syllables or words) of multiple lengths, its cells interact within and between multiple spatial sizes, or scales, with the cells of larger sizes capable of selectively representing item sequences of greater length, and of inhibiting smaller Masking Field cells that represent item sequences of lesser length. As items are stored in working memory, an adaptive filter activates the learned Masking Field list chunks that represent the most predictive item groupings at any time, while its recurrent inhibitory interactions suppress less predictive list chunks. Kazerounian and Grossberg (2014) have simulated how variable-length list chunks of a Masking Field can be learned as a list of items is stored in working memory learned in real time as a list of items is stored in working memory.

An item is more properly called an *item chunk*, which, just like any chunk, is a compressed representation of a spatial pattern of activity within a prescribed time interval. In the case of an item chunk, the spatial pattern of activity exists across acoustical feature detectors that process sounds through time and that are compressed by an adaptive filter to activate item chunks. The prescribed time interval is short and is commensurate with the duration of the shortest perceivable acoustic inputs, on the order of 10–100 ms. Some phonemes may be coded as individual items, but others, in which two or more spatial patterns are needed to identify them, may be coded in working memory as a short sequence of item chunks, and are fully unitized as a list chunk. Thus the model in Fig. 2 first compresses spatial patterns of

feature detectors into item chunks, and then sequences of the item chunks that are stored in working memory are compressed into list chunks.

## B. Temporal Chunking Problem: Learning words of variable length

Masking Fields were introduced to solve the *temporal chunking problem* (Cohen and Grossberg, 1986, 1987; Grossberg, 1978a, 1986, 1987), which asks how an internal representation of an unfamiliar list of familiar speech units—for example, a novel word composed of familiar phonemes or syllables—can be learned under the type of unsupervised learning conditions that are the norm during daily experiences with language. Before a novel word, or list, can fully activate the adaptive filter, all of its individual items must first be presented. By the time the entire list is fully presented, all of its familiar sublists will have also been presented. What mechanisms prevent the familiarity of smaller sublists (e.g., MY, ELF, and SELF), which have already learned to activate their own list chunks, from forcing the novel longer list (e.g., MYSELF) to always be processed as a sequence of these smaller familiar chunks, rather than eventually as a newly learned unitized whole? How does a not-yet-established word representation overcome the salience of already well-established phoneme, syllable, or word representations to enable learning of the novel word to occur?

## C. Self-similar competition solves the temporal chunking problem

A Masking Field accomplishes this using cells with multiple cell and receptive field sizes, or scales (Fig. 2), that are related to each other by a property of *self-similarity*; that is, each scale's properties, including its cell body sizes and their excitatory and inhibitory connection lengths and interaction strengths, are a multiple of the corresponding properties in another scale. Such a self-similarity property can develop as a result of simple activity-dependent growth laws (Cohen and Grossberg, 1986; Grossberg, 1987) in the following way.

It is assumed that item chunk cells are endogenously active during a critical period of development. As a result, Masking Field cells that receive inputs from a larger number of item chunk cells receive a larger total input activity through time. Activity-dependent cell growth causes the Masking Field cell bodies and connections to grow approximately proportionally. This property is called *self-similar* growth. Cell growth terminates when the cell bodies become large enough to dilute their activities sufficiently in response to their inputs no longer exceed a growth-triggering threshold. Cells that receive more inputs grow larger as a result, so that the effects of individual inputs are smaller on larger cells. In effect, self-similar growth normalizes the total effect of all the inputs that converge on a Masking Field cell. Consequently, such a cell only fires vigorously if it receives active inputs from all of its item chunk cells.

Due to self-similar growth, larger list chunks selectively represent longer lists because they need more inputs, and thus more evidence, to fire. Once they fire, their stronger

inhibitory interaction strengths than those of smaller list chunks can inhibit the smaller list chunks more than conversely (“asymmetric competition”). The intuitive idea is that, other things being equal, the longest lists are better predictors of subsequent events than are shorter sublists because a longer list embodies a more unique temporal context. The stronger inhibition from list chunks of longer, but unfamiliar, lists (e.g., MYSELF) enables them to inhibit the chunks that represent shorter, but familiar, sublists (e.g., MY), more than conversely, thereby providing a solution of the Temporal Chunking Problem.

## D. Magical Number Seven and word superiority

The word length effect in word superiority studies and the Magical Number Seven both follow from the self-similarity property. This word length effect was discovered by Samuel, van Santen, and Johnston (1982, 1983), who showed that a letter is progressively better recognized when it is embedded in longer words of lengths from 1 to 4. The word length effect is relevant to self-similarity because larger list chunks are more potent and predictive than smaller list chunks in a Masking Field. However, self-similarity implies that the list chunk of a familiar multi-letter word can inhibit the list chunk of a familiar letter, which seems to contradict the property that the word can facilitate perception of its constituent letters, which is the main result of word superiority studies.

This problem is resolved in ART systems with item chunk and list chunk processing levels. The cARTWORD model is such an ART system, as was its predecessor, the ARTWORD model (Grossberg and Myers, 2000). Their list chunk levels are represented by a Masking Field (Figs. 1 and 2). In particular, although chunks that represent lists of multiple lengths *compete within the Masking Field* that categorizes list chunks, the top-down *expectations from the list chunk level to the item chunk level are excitatory*. By self-similarity, list chunks that represent longer words generate larger recurrent inhibitory signals and larger top-down excitatory priming signals to the item chunk level.

The Magical Number Seven also arises due to self-similarity and asymmetric inhibition among list chunks that represent multiple list lengths. This is easy to see by considering how all the cells of a given scale in a Masking Field interact among themselves via a recurrent on-center off-surround network. Call such a network a single-scale network. Each single-scale network is self-similar to all the other single-scale networks that comprise the Masking Field, but each single-scale network chunks item lists of a different length. The largest active chunks tend to win the asymmetric competition in a Masking Field in response to an input sequence. How big these chunks are will depend on prior experience. By the self-similarity of Masking Field scales, the same number of winning chunks will tend to be active, no matter how big their chunks may be. This explains the Magical Number Seven because, as noted by Miller (1956), “the memory span is a fixed number of chunks.” This number turns out to be seven plus or minus two because of

parameter choices that define these working memory networks (see Bradski *et al.*, 1994).

These explanations of the Magical Number Seven and the word length effect provide further support for the ART prediction that item chunk and list chunk levels process speech and language (Grossberg, 1978a, 1984) rather than the phoneme, letter, and word levels that were used in the interactive activation model (McClelland and Rumelhart, 1981).

## E. Conscious speech is a resonant wave: The units of speech and language

Both ARTWORD and cARTWORD simulated parametric psychophysical data about speech that illustrate the revolutionary ART predictions that “conscious speech is a resonant wave” and that “perceived silence is a temporal break in the rate that the resonance evolves.” In particular, the “resonant wave” that embodies the properties of phonemic restoration illustrates how the conscious percepts of speech sounds can proceed from past to future, even while sounds that are heard in the past are determined by future contextual information.

ARTWORD further illustrated how listeners integrate temporally distributed phonemic information into coherent representations of syllables and words. During fluent speech perception, variations in the durations of speech sounds and silent pauses can produce different perceived word groupings. For example, increasing the silence interval between the words “gray” and “chip” in the utterance “gray chip” may result in the percept “great chip,” whereas increasing the duration of fricative noise in “chip” may alter the percept to “great ship” (Repp *et al.*, 1978). In the “gray chip” to “great chip” example, why should increasing the silence interval between two words, which one might think should make them more distinct, increase the probability that the fricative noise from the second word would leap backward-in-time over 100 ms of silence to join the percept of the first word? In the “gray chip” to “great ship” example, why should increasing the duration of fricative noise in the second word cause that noise to jump backwards-in-time over an interval of 30–80 ms of silence to join the first word? The ARTWORD neural model explains how these percepts arise naturally from ART concepts, and quantitatively simulates these context-sensitive speech data, data of a kind that TRACE cannot explain because of how it represents time and silence.

## F. Item-Order-Rank Masking Field hierarchy chunks lists of repeated words

With this background in mind, it is easy to explain how ART represents lists of repeated words. This can be accomplished by a three-level network (Fig. 8): Each processing level in this network is an Item-Order-Rank (IOR) working memory that can store sequences with repeated items in short-term memory. The second and third IOR working memories are, in addition, multiple-scale Masking Fields that can chunk input sequences of variable length, and choose the sequence, or sequences, for storage that receive

the most evidence from its inputs. Each level receives its bottom-up inputs from an adaptive filter and reads-out top-down expectations that focus attention on the feature patterns in their learned prototypes at the previous level. The first level stores sequences of item chunks. The second level stores sequences of list chunks. The individual list chunks of the third level thus represent sequences of list chunks at the second level, including sequences with repeated words, as in the “DOG EATS DOG” example in Magnuson (2015, p. 1481).

## VI. HOW DOES TOP-DOWN ATTENTIVE FEEDBACK WORK?

### A. TRACE top-down feedback is incompatible with the data

Magnuson (2015) comments that

“Grossberg and Kazerounian (2011) also take issue with TRACE’s lack of absolute constraints on top-down feedback (specifically, they argue that top-down feedback must not be allowed in the absence of any bottom-up support). They cite a passage from McClelland and Elman (1986) (p. 75) where those authors speculated about how feedback might be used in a learning variant of TRACE. Grossberg and Kazerounian (2011) argue that the mechanism outlined there would lead to unstable learning...” (pp. 1482–1483).

Grossberg and Kazerounian (2011) did not write that “top-down feedback must not be allowed in the absence of

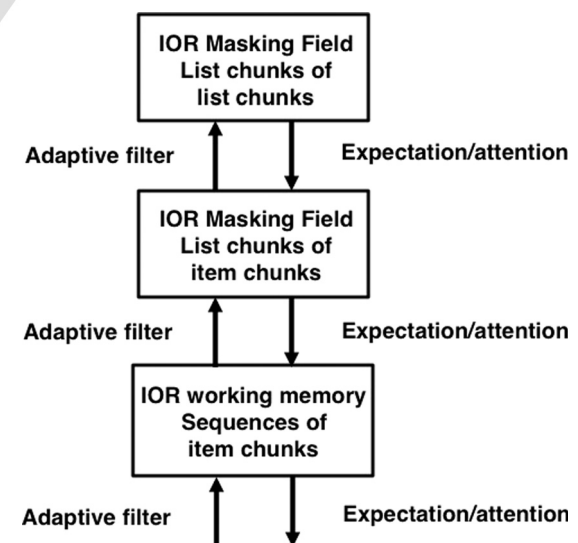


FIG. 8. Hierarchy of speech processing levels. Interactions among three speech processing levels are capable of learning, working memory storage, and performance of word sequences. Each level consists of an Item-Order-Rank working memory. The second and third levels are, in addition, multiple-scale Masking Fields that enable selection and storage of sequences of variable length. All the levels are connected by Adaptive Resonance Theory bottom-up adaptive filters and top-down learned expectations and their attentional focusing capabilities. The first level stores sequences of item chunks. Its inputs to the second level enable that level to store list chunks of item chunks. The inputs of the second level to the third level enable it to store list chunks of list chunks, in particular, sequences of words.



any bottom-up support.” Top-down feedback is ubiquitous in the brain. It is, however, *modulatory* feedback, not *driving* feedback, under most conditions, unlike the feedback in TRACE. Driving top-down feedback is feedback that can activate cells without bottom-up support. Driving feedback is incompatible with a large number of psychological and neurobiological experiments about how top-down attention works. These experiments confirm that attention is controlled by a top-down, *modulatory* on-center, off-surround network. A modulatory on-center cannot drive its target cells without bottom-up support. It can only sensitize or prime its target cells to respond more vigorously to matching bottom-up inputs that may or may not occur. Because the competitive off-surround can suppress unattended feature combinations, this kind of attentional network is sometimes called “biased competition” (Desimone, 1998).

These mechanisms and data about how attentional matching works were predicted by ART and are said to obey the ART Matching Rule. Recent models agree about how to mathematically instantiate the ART Matching Rule. Moreover, as Grossberg and Kazerounian (2011) have reviewed, the ART Matching Rule has been mathematically proved to enable fast category learning to occur without catastrophic forgetting, and its violation can cause catastrophic forgetting, as proved by Carpenter and Grossberg (1987). Many subsequent psychophysical and neurophysiological experiments have supported the ART prediction about how this form of top-down feedback can modulate plasticity, for example, during visual perceptual learning (Ahissar and Hochstein, 1993), auditory learning (Gao and Suga, 1998) and somatosensory learning (Krupa *et al.*, 1999; Parker and Dostrovsky, 1999); see reviews by Grossberg (2013) and Kaas (1999).

Problems with using driving top-down feedback were noted in Magnuson *et al.* (2012).

“An intriguing aspect of ART’s processing assumptions is that its version of top-down feedback cannot cause hallucinatory representations. A ‘2/3 rule’ means that weak inputs (e.g., phonetic features corrupted by noise) can be strengthened once recognized by higher levels of processing, but completely absent inputs cannot be created from nothing. As we discuss below, a common criticism of feedback in TRACE is that it could make the system hallucinate (Norris *et al.*, 2000). Although, in practice, misperception in TRACE seems generally similar to misperception in humans (Mirman, McClelland, and Holt, 2005) and the default TRACE parameters also give it strong, bottom-up priority, future modeling efforts might benefit from nonsymmetrical feedback rules such as those implemented in ART.”

The ART Matching Rule also enables top-down feedback to generate suprathreshold responses when it is supplemented by basal ganglia volitional inputs; e.g., Fig. 1(b). This allows top-down feedback to activate visual imagery and internal thought by being converted from a modulatory to a driving mode. However, if this basal ganglia input becomes tonically hyperactive, it can create visual or

auditory hallucinations, as can occur during schizophrenia (Grossberg, 2000). Such considerations are, however, entirely outside the explanatory range of TRACE.

## B. The ART Matching Rule implies phonemic restoration

The previous discussion illustrates that a major prediction of ART concerns how fast learning can occur without causing catastrophic forgetting; that is, ART proposes how to solve the *stability-plasticity dilemma*. ART predicted in the 1970s that this is accomplished by learned top-down expectations that are matched against bottom-up information. The match focuses attention upon expected combinations of critical features. As noted in the preceding text, ART predicted that this ART Matching Rule is realized by a top-down, modulatory on-center, off-surround network. In brief, the ART Matching Rule shows how attentional matching enables fast learning with self-stabilizing memory.

In the case of speech perception, the ART Matching Rule implies the main properties of phonemic restoration: A top-down expectation can select a bottom-up signal that is consistent with it, such as those noise components that match the learned features in the expectation. However, because it is modulatory, such a top-down expectation cannot create something out of nothing, so silence does not lead to restoration. Because it takes awhile for a resonance to form, future context can influence the expectation that controls restoration. Thus phonemic restoration in response to future context is a consequence of the brain’s mechanism for learning language quickly without experiencing catastrophic forgetting. Said in another way, phonemic restoration supplies additional experimental evidence for the ART Matching Rule operating in real time.

These observations about phonemic restoration were made long before cARTWORD was developed; e.g., in Grossberg (1986). It took almost 30 years of theory development to finally be able to simulate how restoration could be generated in real time in the correct temporal order within a laminar cortical model of speech and word recognition, such as cARTWORD.

The TRACE model uses driving top-down feedback that embodies none of the properties of the ART Matching Rule. Hence it cannot provide the kind of elegant explanation of phonemic restoration that ART and cARTWORD have provided as a manifestation of the brain’s ability to learn language quickly and stably.

This leaves one remaining question: Can TRACE simulate phonemic restoration at all?

## VII. TRACE CANNOT EXPLAIN PHONEMIC RESTORATION DUE TO HOW IT PROCESSES SPEECH

This section shows that, contrary to claims in Magnuson (2015), TRACE cannot simulate phonemic restoration. Our demonstrations of this failure also highlight fundamental problems with the representations in TRACE of time, temporal order, silence, and top-down processing.

## 1282 A. Background leading to Magnuson's research

1283 A reviewer of the Grossberg and Kazerounian (2011)  
1284 manuscript presented simulations that purported to emulate  
1285 phonemic restoration using the TRACE model, and used  
1286 them to claim that TRACE can explain this class of phenom-  
1287 ena. Grossberg and Kazerounian (2011) responded to those  
1288 simulations by showing that, when they were carefully ana-  
1289 lyzed, they did not simulate phonemic restoration and indeed  
1290 illustrated fundamental problems of the TRACE model.  
1291 Magnuson (2015) purported yet again to simulate phonemic  
1292 restoration and focused again on purported shortcomings of  
1293 the cARTWORD model in Grossberg and Kazerounian  
1294 (2011).

1295 The criteria laid out in Grossberg and Kazerounian  
1296 (2011) argued that any model of phonemic restoration  
1297 should show three things in accordance with psychological  
1298 data. First, when phonemes are replaced with silence, the  
1299 model should not give rise to a percept of the removed pho-  
1300 neme. Second, when a phoneme is replaced with broadband  
1301 noise, the model should give rise to a percept of the phoneme  
1302 that was removed. And third, a model of phonemic restora-  
1303 tion should be able to explain “backwards effects in time.”  
1304 For example, Warren and Sherman (1974) found that when  
1305 replacing the phonemes /v/ and /b/ in “delivery” and  
1306 “deliberation,” which are contextually neutral up to the  
1307 removed portion, restoration of the removed phoneme could  
1308 only occur when the disambiguating portions, “ery” and  
1309 “eration,” were finally presented. As such, restoration of the  
1310 removed phonemes relies on future information in order to  
1311 determine what is to be restored.

1312 The initial referee report claiming to show restoration in  
1313 TRACE, as well as Magnuson's subsequent paper, focused  
1314 on showing phonemic restoration using the word “luxury”  
1315 (represented in TRACE as 'lʰksʰri') and how restoration  
1316 can occur when word initial (/l/), medial (/s/), and final (/i/)  
1317 portions, are replaced. To show restoration, Magnuson first  
1318 modified noise representations, such that input noise no lon-  
1319 ger ramped on and off (as is the case with normal phonemes  
1320 in TRACE), and modified representations of silence, such  
1321 that they do not contain the overlapping (co-articulated) por-  
1322 tions of adjacent phonemes. However, simulations resulting  
1323 from these modifications alone [as shown in Fig. 3 of  
1324 Magnuson (2015)] do not show phonemic restoration for a  
1325 number of reasons.

1326 Most critically, as can be seen in Fig. 4 of Magnuson  
1327 (2015), or in our recreation of it in Fig. 9, when the initial /l/  
1328 and medial /s/ phonemes are replaced by noise, the most  
1329 active phoneme representations are not /l/ and /s/ but rather  
1330 /k/ and /g/. Furthermore, in the case of replacement of the  
1331 initial /l/, Magnuson claims that only the activity of the cor-  
1332 responding phoneme activity prior to cycle 25 should be  
1333 considered. In this time window, it is clear that the /l/ pho-  
1334 neme becomes active between time cycles 5 and 15. What  
1335 Magnuson does not show, however, is that in this simulation,  
1336 the lexical node for “luxury” first becomes active at time  
1337 cycle 20, which is *after* the phoneme activation levels for /l/  
1338 have already dropped below zero. This means that the peak  
1339 in the /l/ activation that Magnuson claimed as evidence for

restoration could not have been due to top-down feedback 1340  
from the lexical representation of luxury. Indeed, the noise 1341  
has only just turned off by time cycle 12, so there is no plau- 1342  
sible way for restoration resulting from lexical feedback to 1343  
have occurred in the 5–15 cycle time window. This problem, 1344  
and more generally the issue of how it arises from 1345  
the TRACE representation of time, is discussed in detail in 1346  
Sec. VII C. 1347

To try to overcome the problem that the initial modifi- 1348  
cations to noise/silence representations in TRACE resulted 1349  
in the wrong phonemes becoming most active, Magnuson 1350  
then collapsed the input feature specifications for the pho- 1351  
nemes, so that every phoneme receives an equivalent 1352  
amount of bottom-up input. This was done to prevent noise 1353  
from preferentially activating certain phonemes over 1354  
others. As before, however, this change was insufficient for 1355  
showing phonemic restoration when either the initial or 1356  
medial phonemes have been replaced by noise. This can be 1357  
seen in Fig. 8 of Magnuson (2015). When /l/ and /s/ are 1358  
replaced with noise, their phoneme representations are 1359  
again not the most active ones over the course of the simu- 1360  
lation, suggesting that alternative phonemes would in fact 1361  
be perceived. 1362

Magnuson argued that this is due to biasing of phonotac- 1363  
tic probabilities for certain phonemes by way of early top- 1364  
down feedback from the full lexicon. Because top-down 1365  
feedback from the lexical layer begins as soon as any lexical 1366  
node becomes active, any lexical entry that even partially 1367  
codes for some of the incoming acoustic input can begin to 1368  
feed back and excite phoneme representations. As such, with 1369  
any non-trivial lexicon, the distribution of phonemic activa- 1370  
tions at various locations in a word will be skewed, resulting 1371  
in top-down feedback from active lexical nodes that prefer- 1372  
entially excites phonemes occurring more often at a particu- 1373  
lar location than the phonemes that occur less frequently in 1374  
that position. Magnuson argues that the skewed excitatory 1375  
top-down feedback, to certain phonemes over others, means 1376  
that “...a pure test of lexical restoration in TRACE is virtu- 1377  
ally impossible in a lexicon with even 200 words....” To 1378  
eliminate such bias from the lexicon, Magnuson next 1379  
removed all lexical entries—that is, all word representa- 1380  
tions—except for the single word luxury. 1381

Although Magnuson claims that the model, when incor- 1382  
porating all these changes, with only the single word lexicon, 1383  
is then able to show phonemic restoration, his simulations do 1384  
not reflect the data. In the simulation results in Fig. 12 of 1385  
Magnuson (2015), not only does noise replacement of the 1386  
initial phoneme fail to show restoration (i.e., positive activa- 1387  
tion of the /l/ phoneme), but also, in cases where the initial 1388  
/l/ and final /i/ have been replaced by silence, the activities 1389  
of the corresponding phoneme representations become acti- 1390  
vated and thus would be perceived despite having been 1391  
replaced by silence. Moreover, in the cases where a percept 1392  
is formed when the word medial and final /s/ and /i/ are 1393  
replaced by noise, the lexical representation for luxury has 1394  
already become active, meaning that none of the instances of 1395  
restoration show any backwards effects in time. 1396

To demonstrate these results in enough detail for these 1397  
problems to be fully understood, we did our own simulations 1398

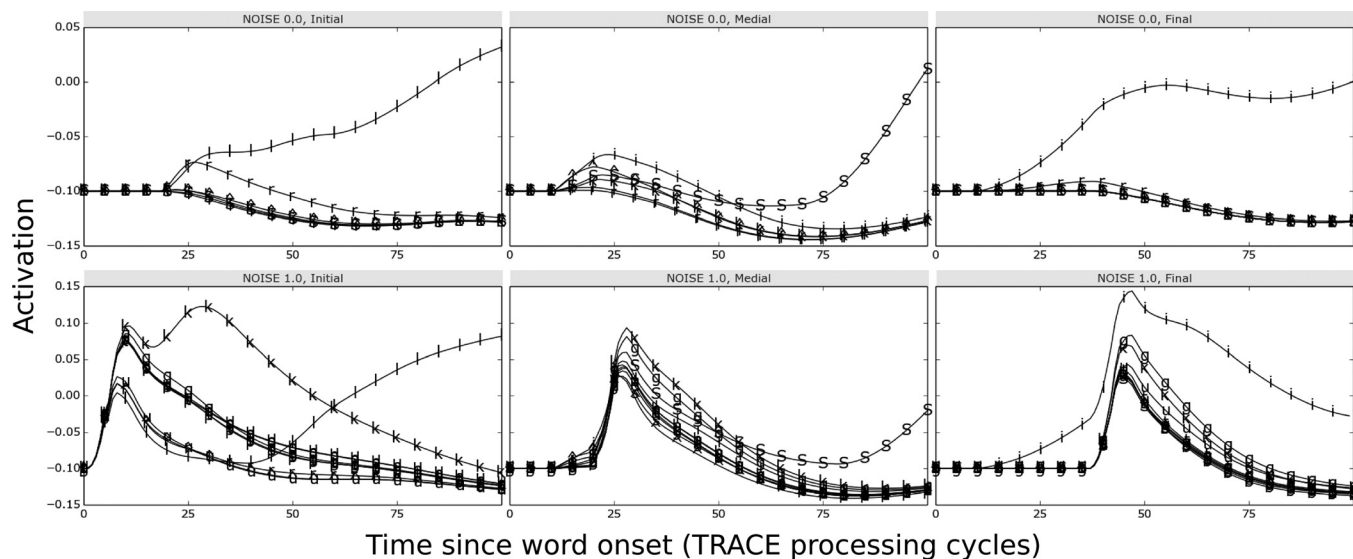


FIG. 9. Recreation of Fig. 4, Magnuson (2015). This figure summarizes the phoneme activation levels for correctly time-aligned phonemes of the word “luxury,” represented as the sequence ‘l<sup>h</sup>kS<sup>h</sup>ri’ in TRACE, when replaced by true silence (0.0 noise, top row), or by full noise (1.0 noise, bottom row). Each curve in the simulation is labeled with its phonemic descriptor. In this simulation, noise and silence have been modified according to Magnuson (2015). The plots in the first column show replacement of the word initial /l/, second column show replacement of word medial /S/, and the final column show replacements of word final /i/. As can be seen in the top row, despite receiving no input, the /l/, /S/, and /i/ grow steadily through time with /l/ and /i/ becoming activated during the course of the simulation, thereby causing a kind of auditory hallucination. Bottom row: the most active phoneme representations when /l/ and /S/ have been replaced by noise, are /k/ and /g/ rather than the expected /l/ and /S/.

that incorporate the changes made by Magnuson to the TRACE model and inputs. In particular, to verify that our additional simulations accurately reflect the modifications made by Magnuson to the TRACE model and inputs, two of his figures were replicated after incorporating these changes. With this verification in hand, two new simulations were done to illustrate the seriousness of TRACE’s failures. After reviewing these results, a discussion is provided in the following text of how these problems follow from the representations of time, temporal order, silence, and top-down processing in TRACE.

## B. Recreating the Magnuson (2015) simulations

The first simulation, in Fig. 9, replicates Fig. 4 of Magnuson (2015). It shows the time-aligned phoneme node activations in response to the input word luxury (‘l<sup>h</sup>kS<sup>h</sup>ri’), with the word initial, medial, or final phonemes, /l/, /S/, or /i/, replaced with either silence (0.0 noise) or with true noise (1.0 noise). These simulations include the noise and silence input representations introduced by Magnuson (2015) that, for the case of silence, remove overlapping portions of co-articulated phonemes and for noise, use values that do not ramp on and off. Although the changes made for these simulations do not on their own suffice to show restoration, they are recreated here to validate our additional simulations. Indeed, in the case of silence in row 1, they show activations of phonemes that receive no bottom-up inputs, and in the case of noise in row 2, they show maximal activations of phonemes other than those that were replaced by noise.

Figure 10 replicates Fig. 12 of Magnuson (2015). This simulation is the culmination of all changes made to the TRACE model and inputs and is claimed by Magnuson to show the model correctly restoring phonemes when a

removed phoneme is replaced by noise but not by silence. The changes include the initial modifications to noise/silence input representations (as in Fig. 9), modification to the phoneme/feature specifications such that all phonemes receive equivalent bottom-up support, and removal of all words from the lexicon except luxury (‘l<sup>h</sup>kS<sup>h</sup>ri’).

In the case that silence replaces the word initial /l/ and word final /i/ (first and third columns of the top row), the responding phonemes become positively activated, and all of them grow during the same time windows as when the phoneme is either intact or replaced by noise. Moreover, as can be seen in the first column, /l/ grows less when its activation is supported by noise (second row) than when it receives no input (first row). Thus to advance a claim of phonemic restoration, if /l/ is assumed to be heard when it is supported by noise, then it must also be heard when it is replaced by silence, thereby contradicting the facts of phonemic restoration. In addition, /l/ grows less when it receives a noise input (second row, first column) than /i/ grows when it receives no inputs (first row, third column). Thus if /l/ is heard when it are supported by noise, then both /l/ and /i/ are heard when they are replaced by silence, thereby contradicting phonemic restoration properties even more seriously. Another problem is that if /l/ is assumed not to be heard when it is replaced by silence, then neither /l/ nor /S/ can be heard when they are supported by noise because they both attain no more than the maximal value of 0.1, again contradicting basic data about phonemic restoration.

## C. Silence, top-down processing, and hallucinations in TRACE

The preceding simulation raises the question of how, during simulations of phonemic restoration with the TRACE



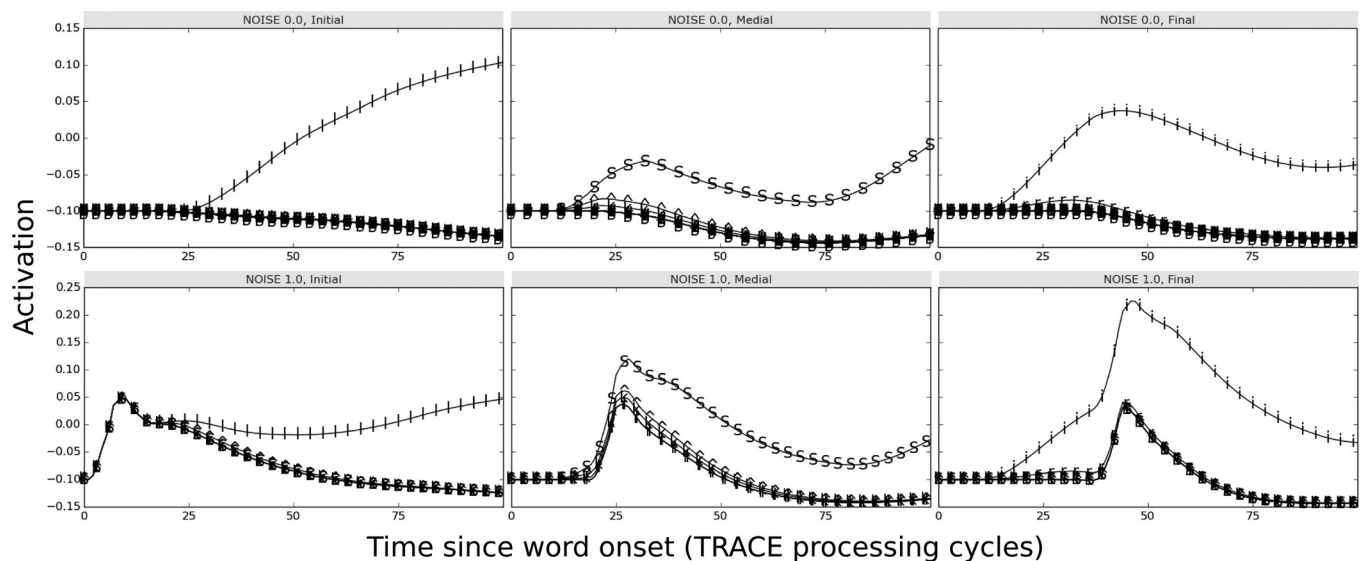


FIG. 10. Recreation of Fig. 12, Magnuson (2015). This figure shows the phoneme activation levels when incorporating all the changes made by Magnuson to show restoration. This includes the modified noise/silence representations, the collapsed phoneme feature specification, and the use of a one-word lexicon. The properties of this simulation do not match properties of phonemic restoration in multiple cases. See the text for details.

model, does a phoneme, when replaced by silence, give rise to a percept of the removed phoneme, in contradiction of the data? In TRACE, this hinges on whether or not excitatory top-down feedback from the lexical layer is sufficient on its own to activate, or drive, phoneme nodes that have not received any bottom-up input. If a phoneme representation becomes active due solely to such top-down signals, despite the removal of acoustic input to that phoneme, then TRACE would incorrectly predict that the phoneme was nonetheless perceived.

Given that this does happen in Fig. 10, how does Magnuson argue that these simulations accurately reflect restoration phenomena? Magnuson makes two claims to defend this position.

First, Magnuson claims that we should ignore late-cycle activations of the phoneme representations: “The early time window is the critical region for restoration; what matters is whether there is a basis for differential behavior as the word is being experienced, rather than many time steps after the noise (e.g., approximately 30 slices after replacement onset, where the 0.0 noise case catches up to the noise replacements).”

Second, in footnote 5, Magnuson claims that late advantages for silence (0.0 noise) over true noise (1.0 noise)-replaced phonemes, can be “wiped out” by reducing the amount of phonemic lateral inhibition, which was presumed to decrease activations for noise-replaced phonemes.

The issues of time and late cycle activations are discussed in more detail in Sec. VIID. It is useful, however, to immediately note that in the final simulations purporting to show restoration, Magnuson’s two claims do not alleviate the problems that are exhibited in the TRACE simulations. First, note that in the case of replacement of the word final /i/ by silence, the phoneme representation for /i/ becomes active between time cycles 30 and 60, roughly the same time window that the phoneme is active when replaced by noise. Because the phoneme is active during the same window for noise and silence replacement, Magnuson’s claim provides no relief in this case, and thus the supra-threshold activation of

/i/ in response to silence is contradicted by phonemic restoration data. Moreover, if one attempts to claim that the maximum activity of /i/ is not sufficient to generate a percept, then other cases where a percept should occur will also not generate a percept, as noted in the previous section. Thus both the times of response and their amplitudes force the conclusion that phonemic restoration data are not properly simulated.

In the case of replacement of the word initial /l/ by silence, the phoneme representation becomes active at approximately time cycle 50 and only continues to become more active as the simulation proceeds. While Magnuson’s choice of time interval seems to apply in this case, the time cycle threshold he uses appears to be selected arbitrarily, and, more importantly, does not comport with the how time, and time-aligned phonemes, are represented in TRACE, as will be discussed further in the next section.

As for the second claim, when the TRACE model uses true silence representations, it is instructive to consider how the model actually prevents phoneme nodes from becoming active solely in response to top-down feedback. Magnuson is correct in noting that it has something to do with lateral inhibition within the phoneme layer. It is problematic, however, to suggest that TRACE can prevent activation of silence-replaced phonemes simply by decreasing the amount of phonemic lateral inhibition. In fact, because lateral inhibition is the only thing preventing top-down feedback from activating phoneme representations that did not receive any bottom-up input, a number of problems arise which are independent of any parameter choice for the level of inhibition in that layer.

Consider, for example, what happens when the word initial /l/ is replaced with silence. During normal presentation of the word luxury (‘lʰʊksʰʊri’), the inputs corresponding to /l/ would be presented for 12 time cycles, ramping up to a peak at cycle 6, and ramping off by cycle 12. The inputs for the subsequent phoneme, /ʌ/, begin ramping on at time cycle 6, to a peak at time cycle 12, and ramping off by cycle 18. Subsequent

phonemes would be presented in similar fashion, with co-articulated portions overlapping with one another. When the initial /l/ phoneme has been spliced out, the full 12 cycles of the corresponding /l/ input are removed as are the first 6 cycles of the ramping on of /ʌ/. The primary source of inhibition on the /l/ phoneme centered at the peak of its input (time cycle 6), is the strong activation of the following phoneme, /ʌ/, centered on the peak of its input at time cycle 12.

An obvious consequence of this fact is that if the temporal extent of the silence is increased, the phoneme representation for /ʌ/ has less time to receive bottom-up input, thereby resulting in a lower activation level of the /ʌ/ phoneme node. This in turn will result in decreased inhibition of the time-aligned /l/ phoneme, allowing it to become more active than if the silence was shorter. At a psychophysical level, this would imply that replacing a *larger* portion of the acoustic signal for the word luxury by silence would *increase*, rather than *decrease*, the percept of the removed portion as one might expect from the data. Importantly, because this is a structural problem with the way TRACE deals with driving top-down feedback, there is no clear parametric fix for this. For example, decreasing top-down feedback will not help because it will remain the case that a larger silence window that replaces a portion of the word will lead to stronger activations of the replaced phoneme(s) than smaller silence windows. Indeed, the simulations in Fig. 11 show that the maximum activities in response to the slightly extended silence are, in the cases of /S/ and /i/, at least three times larger than in the corresponding cases in Fig. 10. These activities must, moreover, be considered supra-threshold, and thus generate percepts, if the /S/ trace in response to a noise input in Fig. 10 (second row, second column) is considered to be supra-threshold.

In particular, the simulations of TRACE in Fig. 11 incorporate all the changes made by Magnuson in the simulations that he claimed to show restoration. Although not shown, additional simulations have shown that these results also hold when the model has a full lexicon as well as an uncollapsed feature set. In the first simulation, instead of replacing only the first 12 cycles of input with silence, the amount of silence was extended by an additional cycle so that the first 13 cycles of acoustic input are now replaced with true silence. When replacing the medial /S/ with silence, the silence was extended in both directions so that

there is an additional time cycle of silence before and after the normal window (i.e., 14 cycles of total silence rather than 12). For word final /i/, the silence was again extended by 1 time step. In all cases, not only do all the phoneme nodes become strongly active despite the fact that they have been replaced by silence, but they become more active in the time window prescribed by Magnuson.

Even more problematic, perhaps, is what happens when larger chunks of the word are replaced with nothing but silence. In the case where the lexicon represents only one word, for example, suppose that only inputs corresponding to the first two phonemes, /l/ and /ʌ/, are presented. Because there are no lexical competitors, top-down feedback will activate all the remaining phonemes that comprise the word luxury, aside from the phoneme representation for /k/. Interestingly, the positive activation of the remaining phonemes occurs simultaneously. In Fig. 12, this can be seen as the temporally overlapping traces for /S/, /ʌ/, /r/ and /i/, suggesting further problems with how TRACE deals with time. If instead we splice the /ʌ/ phoneme, such that its acoustic input ramps up to a maximum with the following ramp-off portion totally removed, the problem becomes worse. Although not shown for the purpose of conserving space, in this instance the model not only hallucinates the final four phonemes (/S/, /ʌ/, /r/, and /i/), but also hallucinates the medial phoneme /k/ as well. In any case, this result shows that TRACE hallucinates four phonemes that were never present in the acoustic signal.

In the full lexicon case, presenting only /l/ and /ʌ/ causes the model to hallucinate /k/ because the most active word is “luck.” If /S/ is also presented, so that the total presentation is ‘lʌkS’, then top-down excitation will activate the remaining /r/ and /i/, causing the TRACE model to hallucinate the final portions of luxury. In all, in addition to not simulating critical properties of phonemic restoration, the TRACE model also hallucinates sequences of phonemes for which no inputs are presented and can do so more vigorously if more silence is present in a given word.

#### D. Time and temporal order in TRACE

Another foundational problem of the TRACE model concerns how it represents time, which is a central concern for any model of speech and language. One of the defining characteristics of speech perception is the fact that speech is

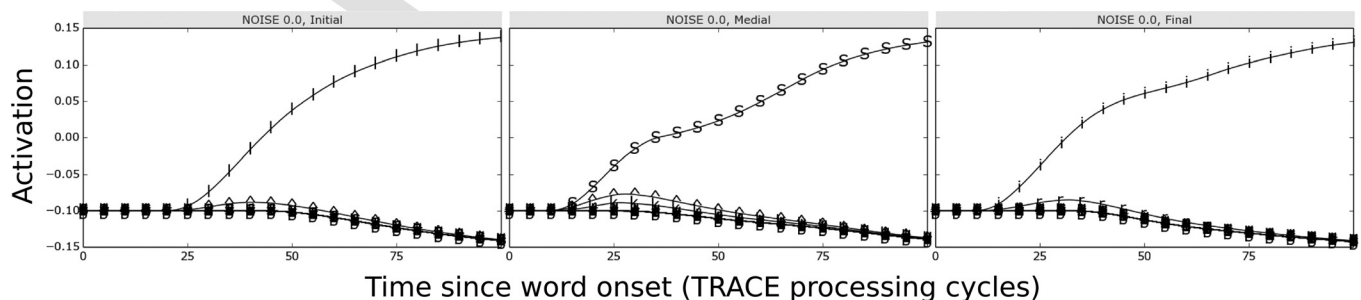


FIG. 11. Simulation of TRACE showing phoneme activations when word initial /l/, medial /S/, and final /i/ have been replaced by extended temporal silence. In previous simulations, when /l/ is replaced by silence, the first 12 time cycles of acoustic input were removed. In this case, the first 13 time cycles are replaced by silence, thereby removing an additional time cycle during which the acoustic inputs for /ʌ/ had previously been active. Similarly, the silence window for /S/ and /i/ have been extended, such that 14 cycles of acoustic input are replaced by silence in the case of /S/, while 13 cycles are removed in the case of /i/.

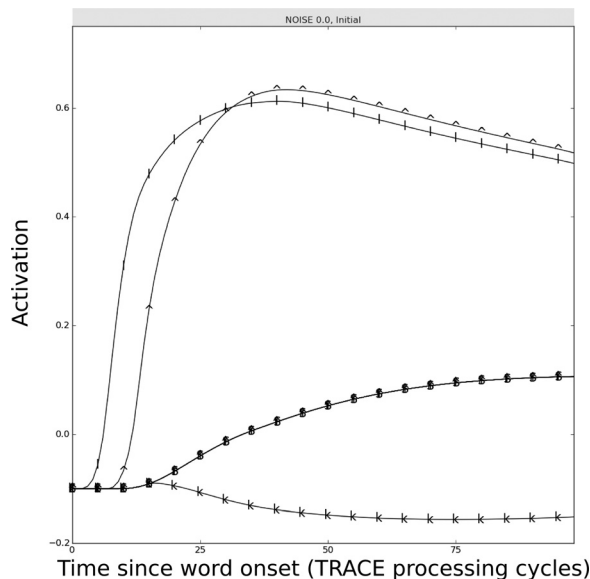


FIG. 12. Simulation of TRACE with presentation of the acoustic input containing only the first two phonemes of “luxury,” /l/ and /ʌ/. The activation of each of the correctly time aligned phonemes (that is, phoneme /l/ aligned at position 2, /ʌ/ aligned at position 4, /k/ at position 6, /s/ at position 8, /r/ at position 10, /t/ at position 12, and /i/ at position 14) is shown over the course of the simulation. Despite the fact that only bottom-up input for the phonemes /l/ and /ʌ/ are present, the final four phonemes that comprise the word “luxury” become active. The four curves are super-imposed over one another, as they become simultaneously active (that is, have activity greater than 0) at approximately time cycle 30, reaching a final activation of approximately 0.1 by time cycle 100. The middle phoneme /k/ remains inhibited due to its proximity to the /ʌ/ phoneme at position 4. This shows the TRACE model hallucinating the final four phonemes of the word “luxury” despite their absence from the acoustic input. It is worth noting that this simulation results from presenting the full inputs for /l/ and /ʌ/, including both ramp-on and ramp-off portions of each, while eliminating all other inputs. The hallucination of the subsequent phonemes becomes worse when the input for /ʌ/ is spliced such that its ramping-off portion is removed as well. In those simulations, the model hallucinates the /k/ phoneme, in addition to the final four phonemes in the word.

inherently temporal. Speech perception is also context-dependent with both past and future contexts determining conscious speech percepts, as phonemic restoration illustrates. As such, a biologically plausible model of speech perception must be able to describe, not only how the brain represents long-term memory, or LTM, traces of learned temporal sequences, but also how these representations are temporarily stored in working memory in response to bottom-up acoustic inputs arriving in real time, even before sequence learning occurs. After learning occurs, such a theory needs to show how learned sequence chunks interact with bottom-up acoustic inputs as they arrive in real time and activate working memory. A theory of speech and language perception must thus explain both what we hear, and when we hear it, let alone how we learn this information through past experiences.

TRACE sidesteps the issue of how temporal order, and in particular, temporal sequences, are represented in the brain by using a “twofold” representation of time. Acoustic inputs are presented sequentially in what is referred to as “real time,” whereas phoneme and lexical representations use a method of temporal alignment that requires multiple reduplications of each representation over many points in time. Each phoneme representation is copied, so that there is one centered at every

three real-time slices, with each phoneme spanning six real-time slices. The “first” phoneme representation for a given phoneme would, for example, process inputs spanning from real-time slices 0 to 6, while the “second” representation for that phoneme would process temporal inputs from slices 3 to 9, the “third” from 6 to 12, and so on. These reduplicated phoneme representations are said to occur at various alignment positions. When the acoustic input for the word luxury is presented, the /l/ features ramp on from time slice 0, to a maximum level at time slice 6, ramping off by time slice 12. As such, they most activate the /l/ representation at alignment position 2. The features corresponding to /ʌ/ begin ramping on at time slice 6, to a maximum at slice 12, and ramp off by slice 18, these features maximally activate the /ʌ/ representation at alignment position 4. Note here that the /ʌ/ representations at time alignment positions 3 and 5 will also receive some bottom-up input (because the representation for /ʌ/ at alignment position 3 processes acoustic inputs occurring between slices 6–12, and /ʌ/ at alignment position 5 processes those occurring between time slices 12 and 18), neither receives as much bottom-up input as the representation at alignment position 2, which is fully centered over the portion of its corresponding acoustic inputs when maximally activated. Lexical representations are similarly reduplicated, so that all positions in real time can be covered by one of the copies of the lexical entry.

As discussed earlier, this method of representing time is at odds with both biological and psychophysical data. Some of these shortcomings were mentioned in the original TRACE paper. As McClelland and Elman (1986) note:

“One fundamental deficiency of TRACE is that fact that it requires massive duplication of units and connections, copying over and over again the connection patterns that determine which features activate which phonemes and which phonemes activate which words. As we already noted, learning in activation models (e.g., Hinton, Sejnowski, and Ackley, 1984; Grossberg, 1976a; Grossberg, 1976b; Rumelhart and Zipser, 1985) usually involves the retuning of connections between units depending on their simultaneous activation. Given TRACE’s architecture, such learning would not generalize from one part of the Trace to another and so would not be accessible for inputs arising at different locations in the Trace. A second problem is that the model, as is, is insensitive to variation in global parameters, such as speaking rate, speaker characteristics and accent, and ambient acoustic characteristics.”

In addition to their inherent implausibility, such duplication is contradicted by psychophysical data concerning how phonemes and words are represented (e.g., Bowers *et al.*, 2015; Toscano *et al.*, 2013). More relevant to the issue of phonemic restoration is the failure of such a representation to explain what is perceived and when it is perceived. Each of the phoneme and word representations, at every alignment position, has an activation value for all of the real-time cycles of any given simulation. This leaves open various possible methods for determining which phonemes are perceived at a given point in time.



In the first possible method, all of the phonemes centered at a particular alignment position (or potentially adjacent positions) are interpreted as competing hypotheses about what is perceived at that position in time. The activity of those representations, as simulation real-time cycles unfold, then represent changes in those hypotheses in response to bottom-up and top-down interactions.

The second possible method assumes that, outside of the need to process acoustic inputs at various points in time, the alignment positions do not matter as such. To determine what is perceived at any given moment in real time, simply look at all the phoneme representations (across all alignment positions) at a given point in real-time cycles, and read out the most active representation.

A third possibility is to use some hybrid procedure, whereby phonemes at a given alignment position determine what is perceived at the real-time cycles that position is centered on but with an additional coordination mechanism that prescribes certain time-windows within which that representation is deemed to be relevant. No such method appears to have ever been elicited in any detail, and even if it had, there would be no clear mechanism for explaining how this coordination would occur, either in the model or in the brain. The very fact that the linking hypothesis between model representation and perception is so indeterminate is itself a problem, especially when it is contrasted with the unambiguous brain-to-behavioral linking hypotheses that naturally arise in neural models such as cARTWORD (Grossberg and Kazerounian, 2011).

Indeed, Dahan, Magnuson, and Tanenhaus (2001, p. 336) note why such a coordination procedure is problematic (albeit in the context of word activations):

“Determining activations from TRACE is not a trivial process. Word units in TRACE function as templates. For a word unit to become highly active, it must be well aligned with phonemic (and featural) inputs. TRACE avoids the alignment problem by aligning a copy of each word unit every three input slices. Given input, TRACE reports the activity of copies of each word unit aligned at different slices. *The experimenter must decide how to decode the word-unit patterns of activation* [italics ours]. The method we used was to determine which copy of a word unit reached the highest activation and then use the activation of that unit over all input cycles as the activation of that word.... *This procedure is problematic because it cannot be implemented in an incremental fashion; it requires an omniscient observer* [italics ours] to compare peak activations after processing is finished. Incremental methods are possible. Each lexical item could have an associated decision node that would either summate the responses of all copies of the word template at all slices or report the activation of the most active word template at each slice. For the purposes of the current article, we use the simple method we have described and leave this issue open for future research.”

It should be noted that an implementation of such a decision node would itself involve an omniscient observer who would need to be able to selectively determine where and

when in the corpus of slices only certain activities should be counted. This would have to be repeated for all lexical units. Then all the decision nodes, or omniscient observers, would need to be globally coordinated, perhaps by an even more omniscient observer.

In either of the first two cases that were summarized in the preceding text, the problem with time remains. Imagine, for example, a phoneme at alignment position 10 with an activity value at real-time cycle 6 that is higher than that of a phoneme at alignment position 2 at the same time cycle. If the only relevant factor is the alignment position, then it does not matter that the phoneme aligned at position 10 has early activity that is higher than that of the phoneme aligned at position 2. To know what is perceived at time-cycle 6, one has to consider only the activity of the phonemes aligned at position 2, not just at the given time cycle, but over the whole course of the simulation (preventing the possibility of ignoring late cycle activations).

On the other hand, if the phoneme that is perceived at time-cycle 6 only depends on the activity of phonemes, independent of alignment position, then a large number of problems arise. For example, in the restoration case, if word-medial /S/ is replaced by noise, the phoneme representation for /S/ aligned at position 8 will show positive activation, but phoneme representations at earlier alignment positions (e.g., /k/ aligned at position 6) will still have higher activity than the activity level of /S/ at the correct position. This would mean that in all the simulations of restoration, a phoneme from a different alignment position that received full bottom-up acoustic input would maintain higher activation levels than the restored phoneme at the correct alignment position.

## VIII. CONCLUSIONS

As shown in the preceding sections, whereas ART is a principled cognitive and neural theory, TRACE is a computational metaphor whose properties exhibit major foundational problems in its representations of time, temporal order, silence, and top-down processing. The phenomenon of phonemic restoration highlights ART's strengths and TRACE's weaknesses in representing these fundamental processes.

In particular, to argue that the TRACE model can simulate phonemic restoration phenomena, Magnuson made a series of changes to the model inputs and representations. Despite these changes, his simulation results fail to exhibit the most basic properties of phonemic restoration. Even when all changes have been made, phonemes that are replaced by silence can become more active than phonemes that are replaced by noise. Indeed, replacing more phonemes by silence only makes their activations bigger, and hallucinations can occur of future phonemes for which there is no bottom-up evidence. These problems can be traced to fundamental representational deficiencies in how both the original TRACE model, and Magnuson's variations thereof, represent time, temporal order, silence, and top-down processing.

In particular, Magnuson's simulations fail to show how restoration occurs when the word-initial phoneme has been

replaced by noise. Furthermore, by removing all lexical entries aside from luxury, the single remaining word node that represents luxury becomes active in response to minimal bottom-up inputs. Masking Fields were introduced and developed (Cohen and Grossberg, 1986; Grossberg, 1978a) to solve this Temporal Chunking Problem (Secs. VB and VC), thereby ensuring that list chunks in a Masking Field network can only be activated by bottom-up inputs from working memory when there is sufficient evidence for them. Because TRACE has not solved the Temporal Chunking Problem, in the case of word medial and final replacements, top-down feedback is available prior to the arrival of the replaced phoneme. This means that Magnuson's simulations not only fail to show restoration on their own, but they fail the additional constraint that a model be able to show how future context can influence conscious percepts of earlier noise-occluded phonemes; that is, they fail to show backward effects in time.

The driving top-down feedback used by TRACE defeats any attempt to use TRACE to explain phonemic restoration. This strong conclusion follows from the fact that increasing the duration of a silence replacement robustly results in greater activation of the deleted phoneme representation than does a shorter silence replacement. The idea that replacing a portion of acoustic input with a *larger* amount of silence, rather than a smaller amount, results in an increased likelihood or strength of a percept for the removed phonemes, is *prima facie* implausible. This is not a parametric failure, or a failure of linking hypotheses, but rather a fundamental weakness of the TRACE model.

In addition to the problems with silence and top-down signals, the temporal order representations in TRACE are not only theoretically untenable, but force contradictory interpretations of model simulations. The use of temporally aligned phoneme and word representations, each of which is responsible for processing acoustic inputs in a predetermined time window, makes it impossible to say what is perceived, and when it is perceived. If, as Magnuson argues, only phoneme activations up to approximately 30 time cycles should be considered after the onset of its corresponding input, what allows us to ignore the fact that the previously activated phoneme is much more strongly activated than a noise-replaced phoneme in that 30 cycle window?

The phenomenon of phonemic restoration thus deeply probes issues about the representation of time, temporal order, silence, and top-down processing that expose fundamental weaknesses of TRACE, while also illustrating how design principles and mechanisms of cARTWORD, and temporal ART models more generally, can naturally explain percepts that are highly context-dependent, including percepts that depend for their conscious representations on future disambiguating contextual information. In particular, unlike TRACE, cARTWORD simulations include a clear representation of what is perceived, and when it is perceived, as well as of why silence-replaced portions of an acoustic signal do not lead to a percept of the removed phoneme, while replacement of that phoneme by broadband noise leads a listener to perceive the phoneme as though it was intact, even when the disambiguating context occurs after these

silence and noise intervals. These key issues are all ones to which the TRACE model provides either no answer, or an answer that is contradicted by the data. In contrast, in ART, these properties emerge from its psychophysically and neurobiologically supported explanations of how top-down expectations and attention dynamically stabilize the rapid and stable learning of auditory representations in real time, and upon which future theoretical developments can build with confidence.

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