

ERROR DETECTING / CORRECTINGCODES

Consider set F_q^m of all m -dimensional vectors $y = (y_0, \dots, y_{m-1})$ where

y_i is a b bit binary vector and

$$q = 2^b$$

Code V is any subset of F_q^m

$$V \subseteq F_q^m$$

vectors from a code are codewords

FOR ANY $y, z \in F_q^m$

$$y \oplus z = (y_0 \oplus z_0, \dots, y_{m-1} \oplus z_{m-1}) \in F_q^m$$

HAMMING distance

FOR ANY $y, z \in F_q^m$

$d(y, z)$ = number of noncoinciding components in y and z

EXAMPLE $b=2, q=4, m=3$

$$\begin{aligned}
 y &= (00, 10, 11) \\
 z &= (10, 10, 01) \\
 y \oplus z &= (10, 00, 10)
 \end{aligned}$$

$$d(y, z) = 2$$

FOR ANY $y, z \in F_q^m$

$$0 \leq d(y, z) \leq m$$

$$d(y, z) = 0 \Rightarrow y = z$$

$$\text{for } b=2, q=2, d(y, z) = m \Rightarrow y = \bar{z}$$

$d(0, y) = \|y\|$ HAMMING NORM of y = number of nonzero components in y

$$0 = (0, \dots, 0)$$

Error - Detecting / Correcting Codes.

Hamming Distance:

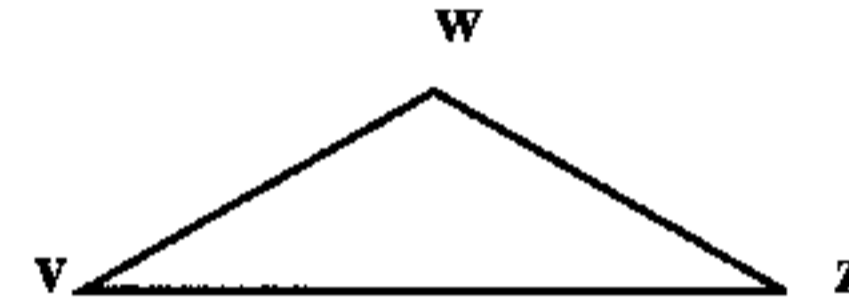
FOR $b=2$

$$v = (v_1, \dots, v_n), w = (w_1, \dots, w_n) \Rightarrow d(v, w) = \sum_{i=1}^n (v_i \oplus w_i)$$

Example: $n = 5, d(10110, 11001) = 4$

FOR ANY b :

$$0 \leq d(v, w) \leq n; \quad d(v, w) + d(w, z) \geq d(v, z)$$



Code with distance d:

Set of vectors U such that $\min_{v, w \in U} d(v, w) = d$

Example: $U = \{ 00000, 10011, 01110, 11101 \}$. Code with distance $d(U) = 3$, $\phi = 2$

(D. P. Sewiorek, R.S. Swartz, "Theory and Practice of Reliable System Design, Ch3 and Appendix A).

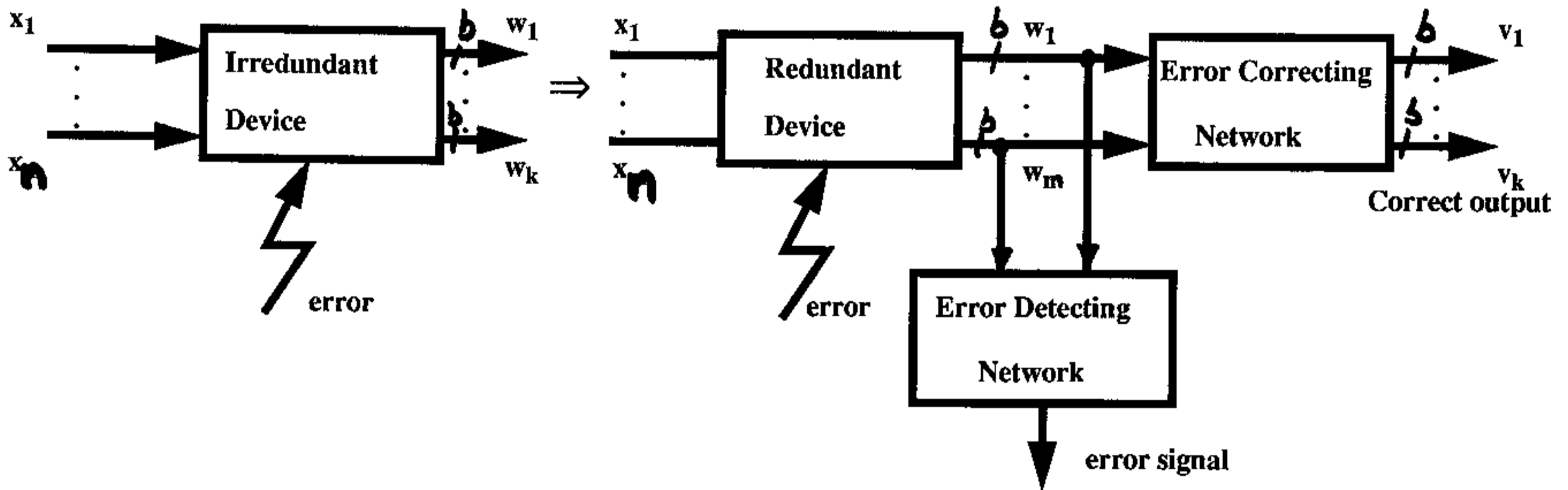
$$d(\tau \oplus v, \tau \oplus w) = d(v, w) \Rightarrow (0, 0, \dots, 0) \in U$$

Error : $v \rightarrow w, \quad e = v \oplus w$
 $e_i \neq 0$ if v_i is distorted.

Multiplicity ℓ of an error:

$$\ell = d(v, w) = d(e, 00 \dots 0) = \|e\|$$

Example $e : 01110 \rightarrow 01010, e = 00100, \|e\| = 1$



For fault - free device $v = w$

Code vectors $(v_1, \dots, v_k, v_{k+1}, \dots, v_{k+r})$, $k+r = n$, satisfy r equations.

Problems :

- 1. Relation between multiplicity of errors and distance of the code (simple).**
- 2. Construction of an optimal code with the given distance (difficult).**
- 3. Implementation of error detecting / correcting networks.**

Error Correcting Codes.

Geometrical Interpretation.

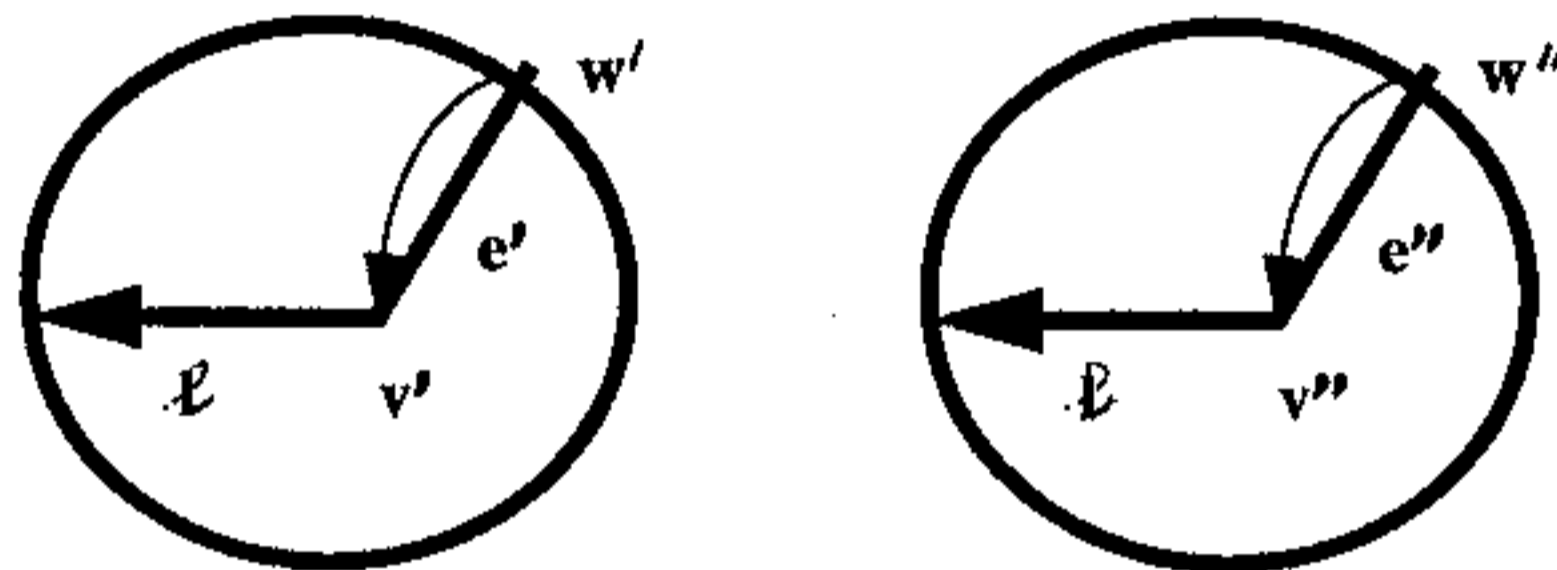
Error correction :

v', v'' - fault - free output ; $v', v'' \in \mathcal{V}$

e', e'' - errors ; $\|e'\|, \|e''\| \leq \ell$

w', w'' - faulty outputs

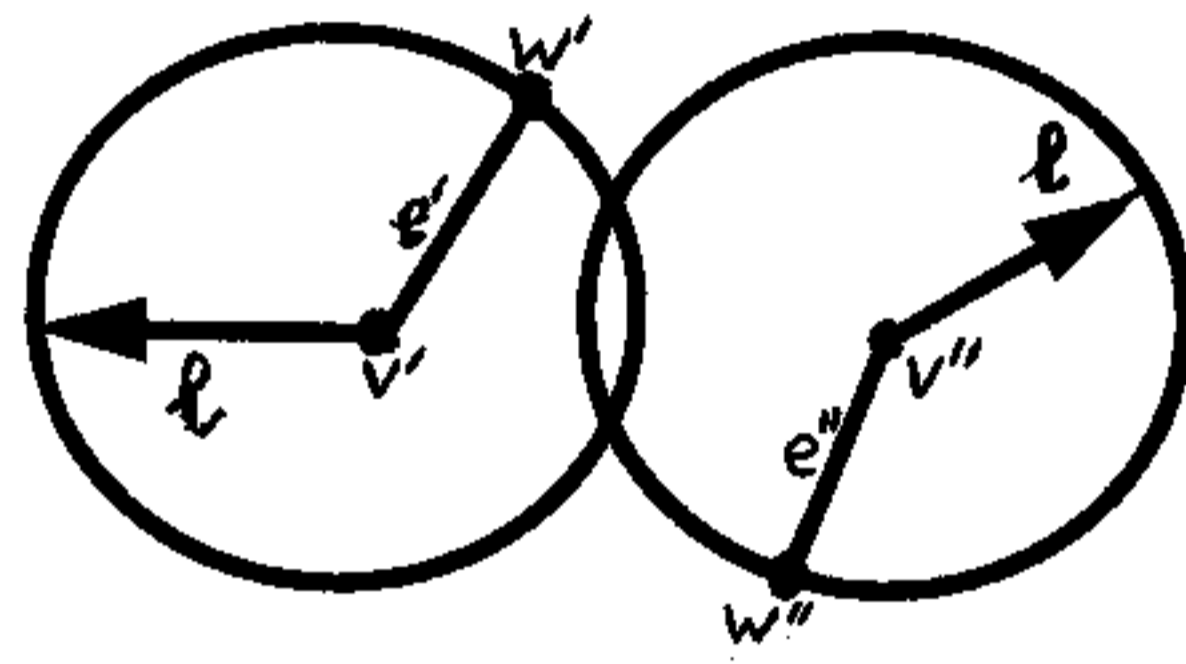
ℓ - multiplicity of errors.



For error correction spheres must not intersect $\Leftrightarrow d(v', v'') \geq 2\ell + 1$

$$d(\mathcal{V}) \geq 2\ell + 1$$

Error Detection :



$$v', v'' \in U$$

$$e', e'' - \text{errors} ; \|e'\|, \|e''\| \leq l$$

$$w' = v' \oplus e'$$

$$w'' = v'' \oplus e''$$

Any sphere doesn't contain a center of another one $\Leftrightarrow d(v', v'') \geq 2l + 1$

$$d(v) \geq 2l + 1$$

Set of all vectors at the distance exactly (up to) $\leq l$ from any given vector y is the Hamming sphere (ball) with radius l and center y .

the size of a ball with radius l

$$V(l) = \sum_{i=0}^l \binom{n}{i} (q-1)^i$$

the size of a sphere with radius l

$$S(l) = \binom{n}{l} (q-1)^l$$

$$\frac{S(l)}{V(l)} \approx 1 \quad \text{skin effect for large } n.$$

∴ Code V is linear (systematic)

if for $v_1, v_2 \in V \Rightarrow v_1 \oplus v_2 \in V$

∴ one-dimensional parity checks,
two-dimensional parity checks and
Hamming codes are linear, BCH is linear
RM codes are linear.

∴ Code is cyclic if a cyclic shift
of a codeword is another codeword.

∴ BCH codes are cyclic codes

∴ All cyclic codes are linear

Code V is linear iff for any

$$y, z \in V \Rightarrow y \oplus z \in V$$

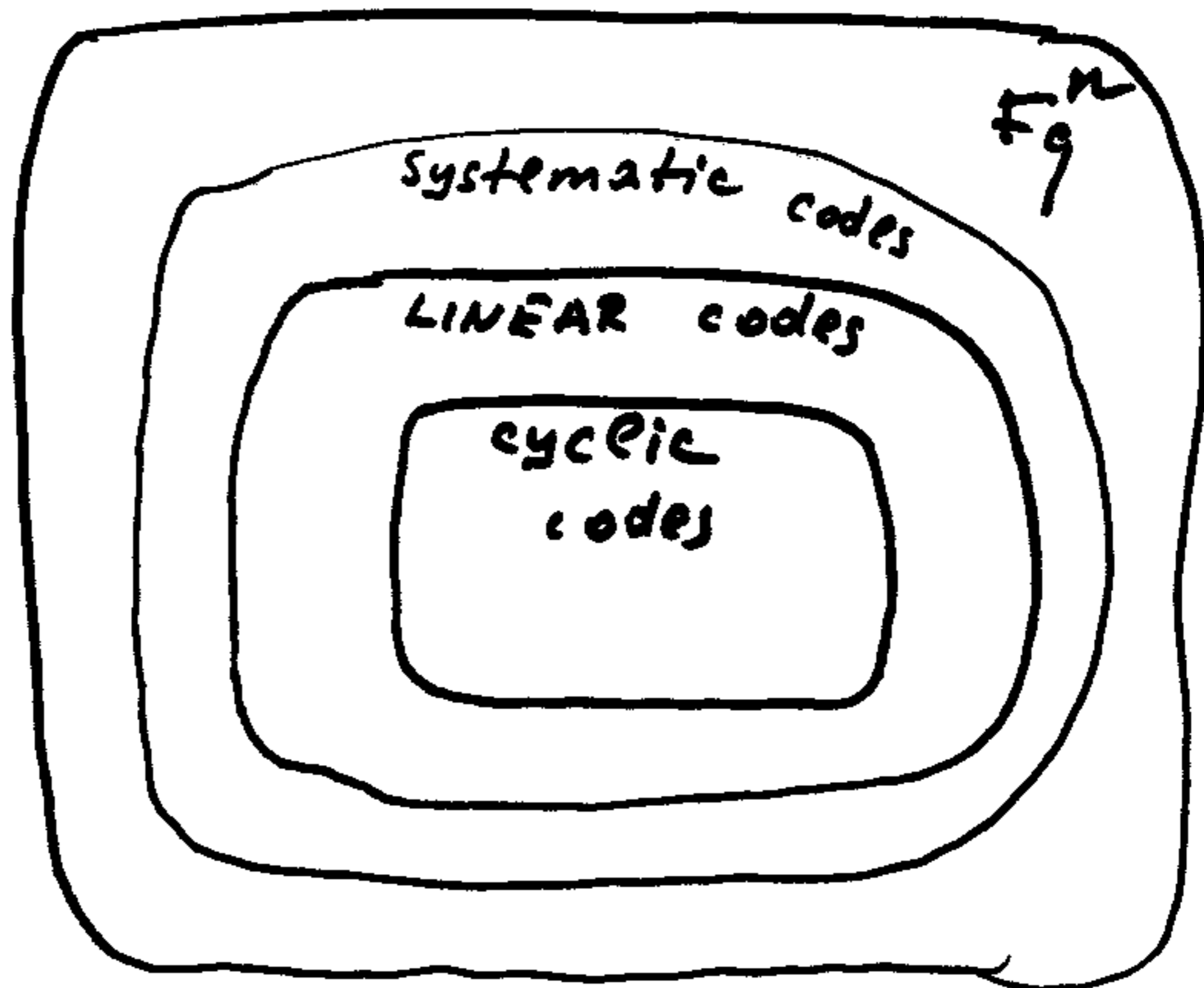
For linear a code V $|V|$ - number of codewords $|V| = q^k$ where k is a number of information digits

Code is systematic if one can distinguish between information and redundant digits

Any linear code is systematic
(Opposite is not true)

A code is cyclic iff any cyclic shift of a codeword is a codeword

If code is cyclic then it is linear-
let F_q^n set of all vectors y of length n with components y_i being b -bit vectors where $q = 2^b$



Linear codes of length n
 with k information ~~bits~~ digits
 and distance d are denoted
 $[n, k, d]$ codes

TRANSITION RATE $0 < R = \frac{k}{n} < 1$

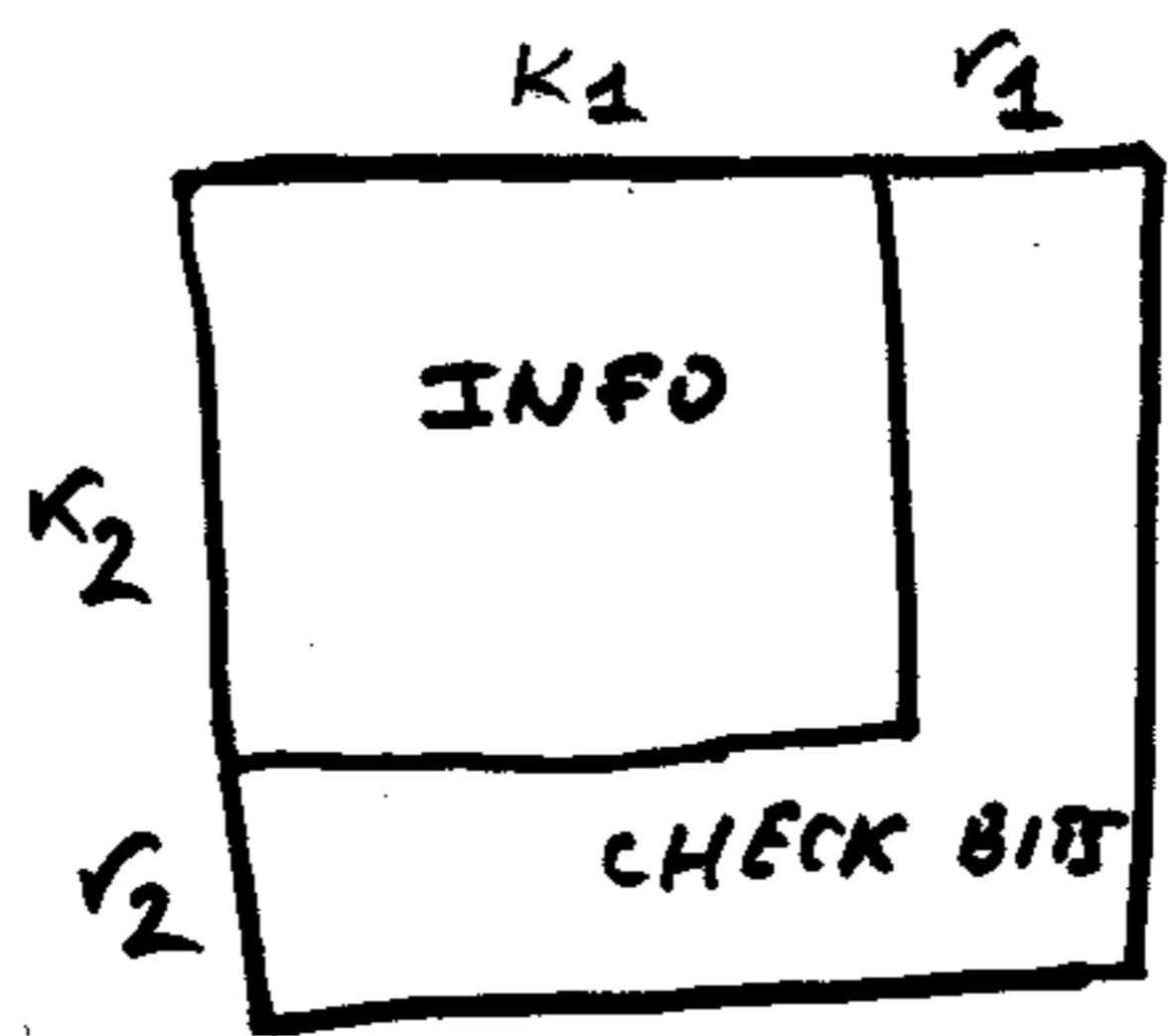
DIRECT PRODUCT OF CODES

V_1 : $[n_1, k_1, d_1]$ code

$r_1 = n_1 - k_1$

V_2 : $[n_2, k_2, d_2]$ code

$r_2 = n_2 - k_2$



$V_1 \times V_2$

$$V_1 \times V_2 : [n_1 n_2, \kappa_1 \kappa_2, d_1 d_2]$$

$$\text{If } V_1 = V_2$$

$$V_1^2 : [n_1^2, \kappa_1^2, d_1^2]$$

$$\text{For } R(V_1^2) = \frac{\kappa_1^2}{n_1^2} = (R(V_1))^2$$