

Concurrent Checking of Linear Devices

Device is linear if it can be implemented by XOR gates and FFs only

Linear combinational devices:



$$z(t) = y(t) \cdot A \quad \text{all computations mod 2}$$

Example Network computing syndromes for Hamming code
 $(M = 2^m - 1, \quad \text{---} 2^m - m - 1, \quad d = 3)$
~~transmission~~

Linear sequential devices

$$D(t+1) = D(t)A \oplus y(t+1)$$

$$Z(t+1) = D(t+1)$$

$D(t), y(t)$ are n -bit vectors

A is $(n \times n)$ binary matrix



$t=n$

$D(t)$ internal state

Select code C of length t to protect a linear device (C is a (t, k) code $r=t-k$)

A generating matrix of C can always be presented as

$$G = (I \mid P)$$

where I is the $(k \times k)$ identity matrix

and P is $k \times (t-k)$ ~~submatrix~~ matrix

EXAMPLE C is $(7,4)$ HAMMING with check matrix

$$H = \left(\begin{array}{cccc|ccc} 0 & 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 & 1 \end{array} \right)$$

If $(v_1, v_2, v_3, v_4, v_5, v_6, v_7) \in C$ then

$$v_2 \oplus v_3 \oplus v_4 \oplus v_5 = 0$$

$$v_5 = v_2 \oplus v_3 \oplus v_4$$

$$v_1 \oplus v_3 \oplus v_4 \oplus v_6 = 0$$

$$v_6 = v_1 \oplus v_3 \oplus v_4$$

$$v_1 \oplus v_2 \oplus v_4 \oplus v_7 = 0$$

$$v_7 = v_1 \oplus v_2 \oplus v_4$$

$$G = \left[\begin{array}{cccc|ccc} v_1 & v_2 & v_3 & v_4 & v_5 & v_6 & v_7 \\ 1 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{array} \right] \Rightarrow P = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$(v_1, \dots, v_k, v_{k+1}, \dots, v_t) \in C$ iff

$$R(v_1, \dots, v_k) = (v_{k+1}, \dots, v_t) = (v_1, \dots, v_k) P.$$

redundant bits in a codeword

ENCODING

Example For the above $(7,4)$ code

$$(1001) \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = (100)$$

and (1001100) is a codeword

Thus for combinational linear machines ~~for~~
we have for redundant outputs

$$R(z(t)) = y(t) A P = y(t) A'$$

where H' is $H \cdot P$ and $Z(t) = Y(t) A$

EXAMPLE 1 Let the original linear combinational
device is defined as

$$Z(t) = Y(t) \cdot \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{bmatrix} \quad M=5 \quad K=3$$

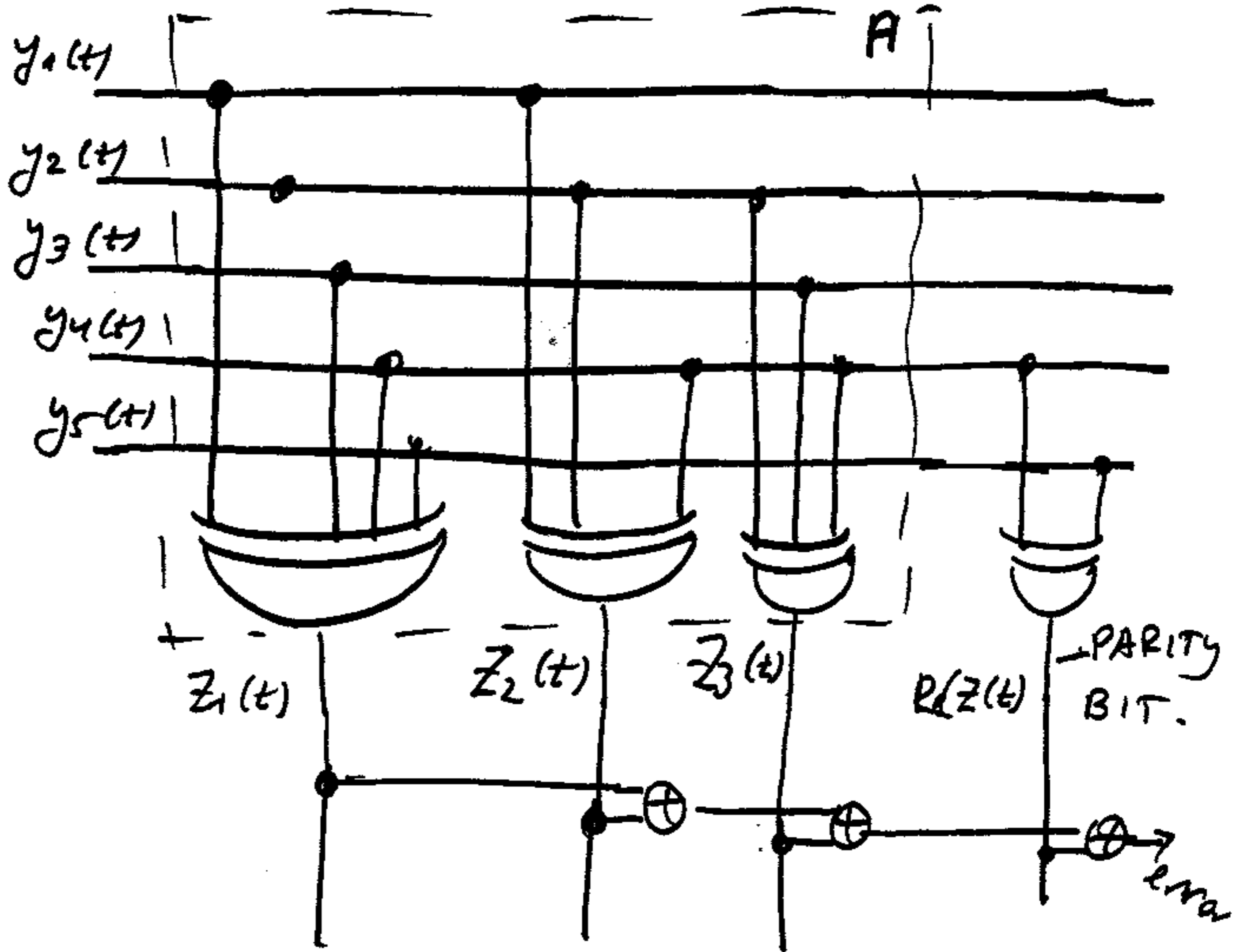
and we want to protect it with (4,3)
1dim parity, then we have for the
parity bit $P = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$$R(z(t)) = y(t) A' = y(t) \cdot \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} =$$

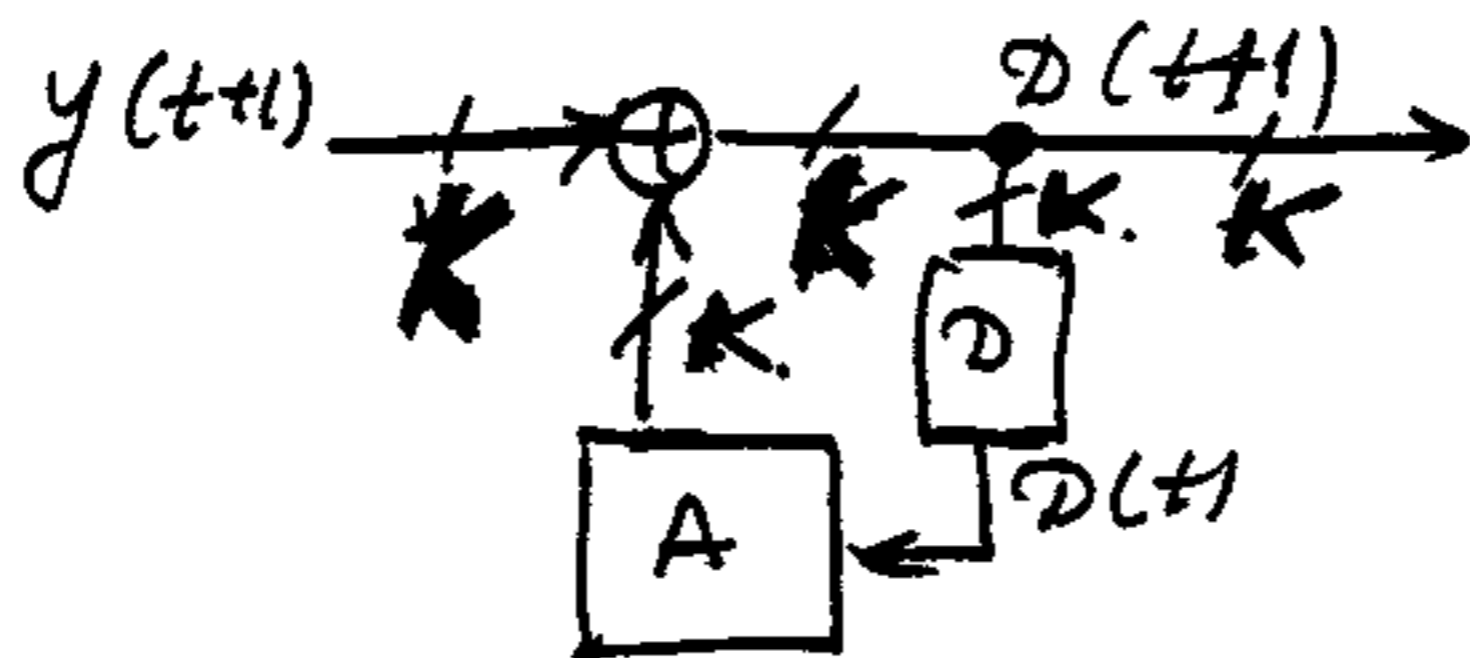
$$= y(t) \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \quad \text{If } y(t) = (y_1(t), y_2(t), y_3(t), y_4(t), y_5(t))$$

Then $R(z(t)) = y_4(t) \oplus y_5(t)$

NETWORK FOR THE PREVIOUS
EXAMPLE



CONCURRENT CHECKING OF LINEAR
SEQUENTIAL DEVICES



$$D(t+1) = D(t) A \oplus y(t+1) \quad D(t), y(t) \in GF(2^K)$$

A is a $(K \times K)$ binary matrix

FOR CONCURRENT CHECKING by the code
C with K inf. bits. with

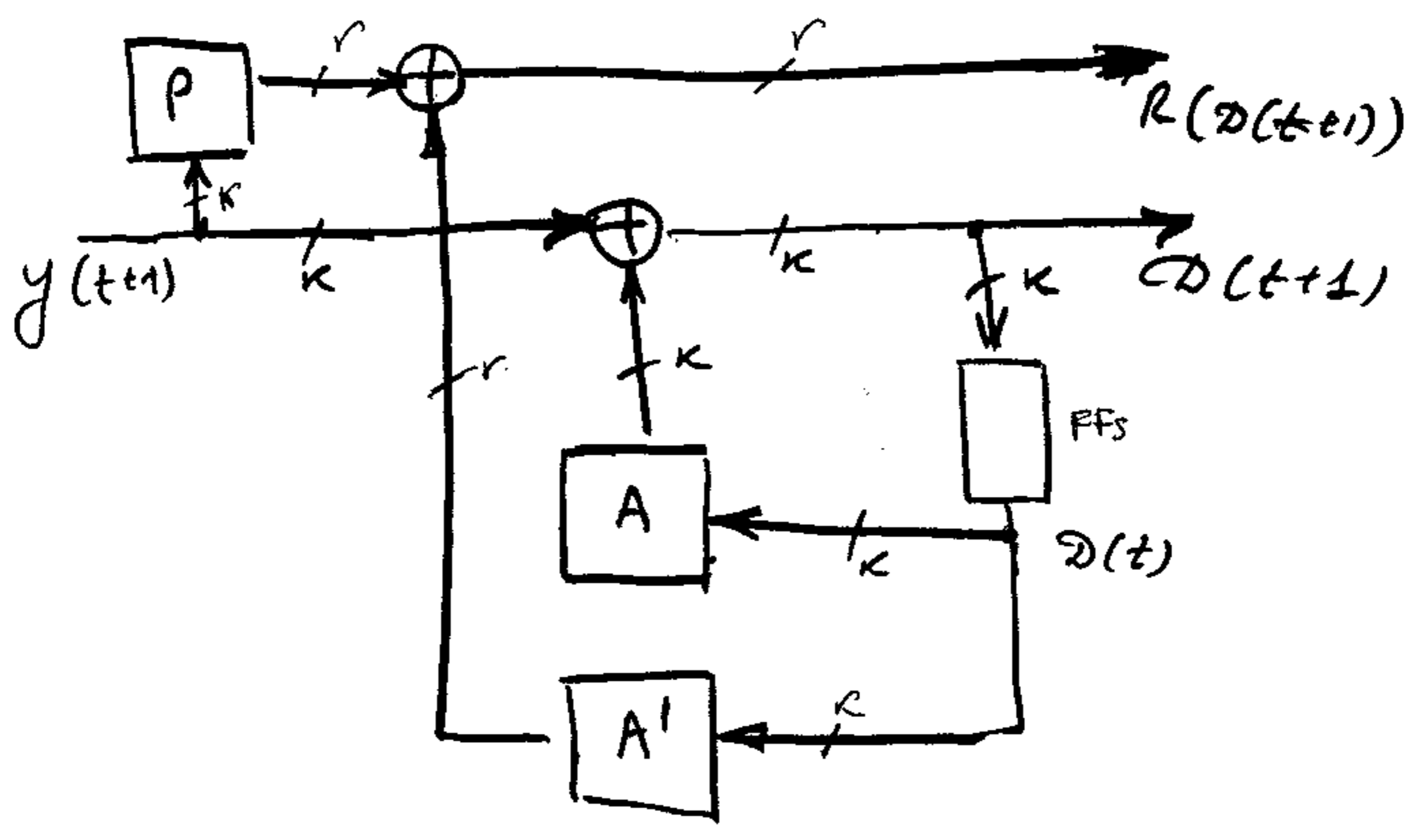
$$G = [I \mid P].$$

we have

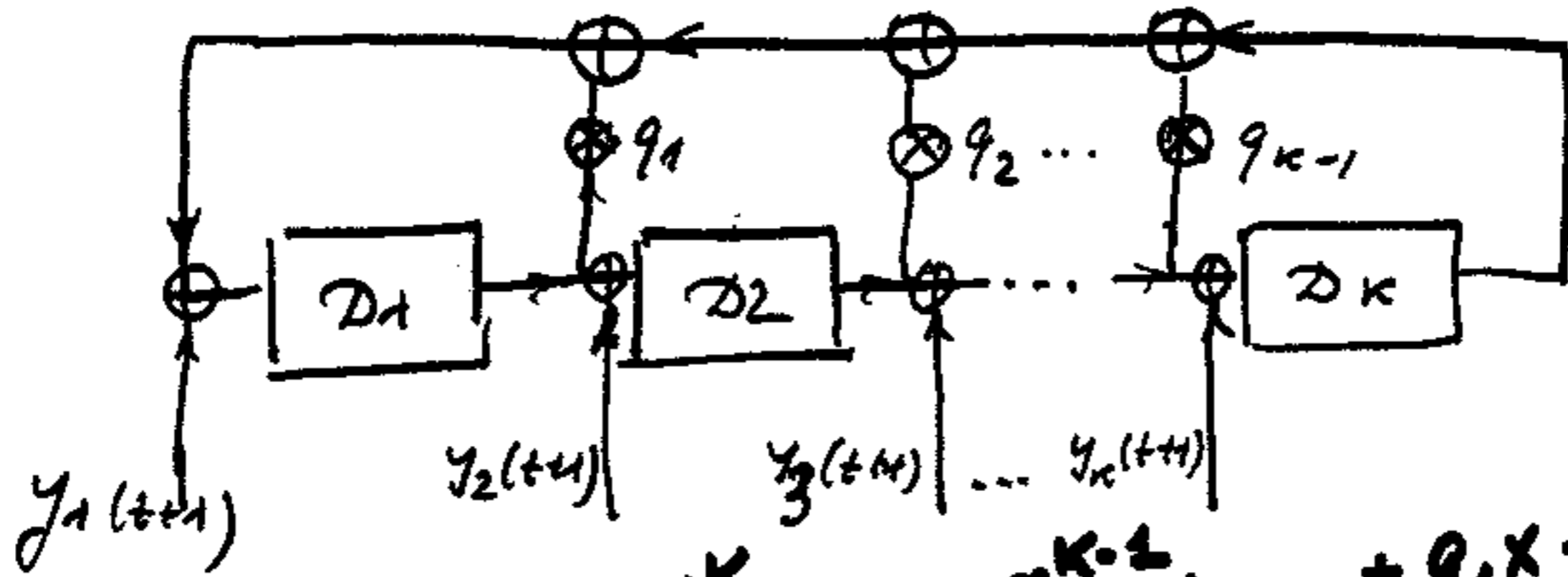
$$\begin{aligned} R(D(t+1)) &= R(D(t)A) \oplus R(y(t+1)) \\ &= D(t)AP \oplus y(t+1)P = \\ &= D(t)A' \oplus y(t+1)P \end{aligned}$$

$$A' = A \cdot P$$

Block diagram for concurrent
checking of linear sequential
devices



EXAMPLE Let the sequential device is
MISR :



Then

$$A = \begin{bmatrix} q_1 & 1 & 0 & 0 & \dots & 0 \\ q_2 & 0 & 1 & 0 & \dots & 0 \\ q_3 & 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ q_{k-1} & 0 & 0 & 0 & \dots & 1 \\ 1 & 0 & 0 & 0 & \dots & 0 \end{bmatrix} \quad \left. \vphantom{A} \right\} \quad C = \begin{bmatrix} q_1 & | & \vdots \\ q_2 & | & \vdots \\ \vdots & | & \vdots \\ q_{k-1} & | & \vdots \\ \hline 1 & | & 0 \dots 0 \end{bmatrix}$$

$x^k + q_{k-1}x^{k-1} + \dots + q_1x + 1$

Select $(k+1, k)$ code to protect this MISR

Then

$$P = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \quad \text{and} \quad A' = AP = \begin{bmatrix} \overline{q_1} \\ \overline{q_2} \\ \vdots \\ \overline{q_{k-1}} \\ 1 \end{bmatrix}, \quad \overline{q_i} = 1 - q_i$$

$$y(t+1)P = \bigoplus_{i=1}^k y_i(t+1)$$

$$D(t)A' = \bigoplus_{i=1}^{k-1} D_i(t) \overline{q_i} \oplus D_k(t)$$

EXAMPLE: $k=3$ 