

FUNCTIONS WITH FLAT AUTOCORRELATION AND THEIR GENERALIZATIONS

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Abstract

Several new constructions for functions with flat autocorrelation are presented. Correlation functions considered in this paper are defined with respect to p -adic ($p \geq 2$) shifts (vector additions modulo p) of variable length. We show that the total autocorrelation function for a function $f(x)$, (f is a mapping from an n -dimensional vector space V_n over $GF(q)$ onto $GF(q)$), is flat (invariant for any shift of the space) iff its maxima are minimum over all possible mappings $\{f\}$. We construct a class of functions $f: V_n \rightarrow GF(q)$ with a flat total autocorrelation by quadratic forms over $GF(q)$. Moreover, the autocorrelation function for the characteristic function $f_i(x) \in \{0,1\}$, $f_i(x) \equiv 1$ iff $f(x) = i$, $i \in GF(q)$, is also shown asymptotically flat as $n \rightarrow \infty$. Applications of functions with flat autocorrelation to compression of test responses and error-detecting codes for channels with unknown statistics of errors will be described.

1 Introduction

A function $f(x)$ is "bent" iff $|\{x \mid f(x) = f(x+e)\}|$ is constant (flat) for $e \neq 0$. The terminology follows from the fact that shifts of linear subspaces result in either their cosets or subspaces themselves, hence, in this sense bent functions are the furthest functions from being linear [1]. In this paper we will confine ourselves to the shifts of function with respect to vector additions modulo p (p -adic shifts $p \geq 2$). Similar results for constructing bent functions with respect to cyclic shifts may be found in [9-11].

Two major results concerning the constructions of q -ary bent functions and binary asymptotically bent functions are presented. Applications of these results in data compression for VLSI testing and error-detecting codes will be described. In Section 1 we will define autocorrelation for q -ary functions, and show the equivalence between constant autocorrelation functions and minimum maxima of autocorrelation.

1.1 Definition

Autocorrelation functions for a q -ary function $f(x)$ [2] where $x \in V_n$, $V_n \in GF(q)$ (V_n denotes n -dimensional vector space) and $f(x) \in GF(q)$, $q = p^s$ defined by

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$$B_{\Sigma}(e) = \sum_i B_i(e) = \sum_i \sum_x f_i(x)f_i(x+e) = |\{x \mid f(x)=f(x+e)\}|. \quad (1)$$

The characteristic function $f_i(x) \in \{0,1\}$ is defined as $f_i(x)=1$ iff $f(x)=i$, $i \in GF(q)$. Note that $x+e$ is defined in V_n over $GF(q)$ and the summations Σ are integer additions. Furthermore, $B_{\Sigma}(e)$ is the size (cardinality) of the set $\{x \mid f(x)=f(x+e)\}$ and

$$B_i(e) = |\{x \mid f(x)=f(x+e)=i\}|. \quad (2)$$

$B_{\Sigma}(e)$ and $B_i(e)$ are referred to as the total autocorrelation function and the autocorrelation function of the i th characteristic function $f_i(x)$, respectively.

Functions with flat autocorrelation are important for compression of test responses and error detection for channels with unknown error distributions. For VLSI compression testings $B_{\Sigma}(e)$ is the number of error-masking events, $(x,e): f(x)=f(x+e)$, for a given error e , where x is a fault-free response. Similarly, for error-detecting codes, $B_i(e)$ is the number of error-masking events, $(x,e): f(x)=f(x+e)=i$, for a given error e , where x is a codeword of the code $C = \{x \mid f(x)=i\}$.

Let us consider the following example illustrating (1).

Example 1. Let $f(x)=uv$, $x=(u,v)$ $u,v \in GF(3)$, that is, $f(x): V_2$ over $GF(3) \rightarrow GF(3)$. Truth tables of $f(x)$, and $f(x+e)$ for $e = (0,1)$, $(1,2)$ and $(2,2)$ and the values of $B_i(e)$, $i=0,1,2$ and $B_{\Sigma}(e)$ are listed in Table 1(a) and 1(b).

x	f	f_0	f_1	f_2	$x+e$	f	f_0	f_1	f_2	$x+e$	f	f_0	f_1	f_2	$x+e$	f	f_0	f_1	f_2					
00	0	1	0	0	01	0	1	0	0	12	2	0	0	1	21	2	0	0	1	22	1	0	1	0
01	0	1	0	0	02	0	1	0	0	10	0	1	0	0	22	1	0	1	0	20	0	1	0	0
02	0	1	0	0	00	0	1	0	0	11	1	0	1	0	20	0	1	0	0	21	2	0	0	1
10	0	1	0	0	11	1	0	1	0	22	1	0	1	0	01	0	1	0	0	02	0	1	0	0
11	1	0	1	0	12	2	0	0	1	20	0	1	0	0	02	0	1	0	0	00	0	1	0	0
12	2	0	0	1	10	0	1	0	0	21	2	0	0	1	00	0	1	0	0	01	0	1	0	0
20	0	1	0	0	21	2	0	0	1	02	0	1	0	0	11	1	0	1	0	12	2	0	0	1
21	2	0	0	1	22	1	0	1	0	00	0	1	0	0	12	2	0	0	1	10	0	1	0	0
22	1	0	1	0	20	0	1	0	0	01	0	1	0	0	10	0	1	0	0	11	1	0	1	0
$e=(0,0)$					$e=(0,1)$					$e=(1,2)$					$e=(2,1)$					$e=(2,2)$				

Table 1(a). Truth tables for $f(x+e)=(u+t)(v+r)$ over $GF(3)$

e	(0,0)	(0,1)	(0,2)	(1,0)	(1,1)	(1,2)	(2,0)	(2,1)	(2,2)
$B_0(e)$	5	3	3	3	2	2	3	2	2
$B_1(e)$	2	0	0	0	1	0	0	0	1
$B_2(e)$	2	0	0	0	0	1	0	1	0
$B_{\Sigma}(e)$	9	3	3	3	3	3	3	3	3

Table 1(b). Values of Autocorrelation functions

Theorem 1

$B_{\Sigma}(e)$, $e \neq 0$, is constant (not equal to q^n) iff $B_{\Sigma}(e) = q^{n-1}$. □

Proof

By summing both sides of (1) over all $e \neq 0$, together with the fact that

$$\sum_{e \neq 0} B_i(e) = \sum_{e \neq 0} \sum_x f_i(x) f_i(x+e) = B_i(0) (B_i(0) - 1), \quad (3)$$

((3) is readily verified by interchanging the summations, for example, see Table 1(b)). Thus we have

$$Q \triangleq \max_{e \neq 0} B_{\Sigma}(e) \geq \left| (q^n - 1)^{-1} \sum_i B_i(0) (B_i(0) - 1) \right|. \quad (4)$$

Minimization of (4) over a set of all possible mappings $\{f\}$ with the constraint

$$\sum_i B_i(0) = q^n, \quad (5)$$

results in:

$$Q^* \triangleq \min_{\{f\}} \max_{e \neq 0} B_{\Sigma}(e) \geq q^{n-1}. \quad (6)$$

Therefore, the equality in (6) holds iff $B_{\Sigma}(e) = q^{n-1}$ for all $e \neq 0$. □

1.2 Binary Bent Functions

For the case of binary bent functions $f(x) \in \{0,1\}$ we have the following relationship between $B_{\Sigma}(e)$, $B_1(e)$ and $B_0(e)$. Since for $f(x) \in \{0,1\}$ and $f_0(x)$ can be written as $f_0(e) = 1 - f_1(0)$ (arithmetic minus), (1) becomes

$$B_{\Sigma}(e) = B_0(e) + B_1(e) = q^n - 2B_1(0) + 2B_1(e). \quad (7)$$

Generalized binary bent functions can be defined as $f(x) \in \{0,1\}$, $f: V_n$ over $GF(q)$, $q = p^s$, $\rightarrow \{0,1\}$, and characterized by the dichotomy induced by f on the space into $C_i = \{x \mid f(x) = i\}$, $i = 0,1$, such that $B_{\Sigma}(e) = q^{n-1}$.

Let us consider the following example to show the lower bound on Q and the uniqueness of $|C_i| = B_i(0)$ for the case of binary bent functions with $p=2$.

Example 2. Consider $f(x) \in \{0,1\}$ where $x \in V_n$ over $GF(2)$. From (4) and (5)

$$Q^* = \min_{\{f\}} Q = \min_{\{y\}} (2^n - 1)^{-1} \beta(y), \quad y \triangleq B_1(0) \text{ and } \beta(y) = 2y^2 - 2^{n+1}y + 2^n(2^n - 1). \quad (8)$$

One can see that $\beta(y) \geq \beta(2^{n-1})$, however, 2^{n-1} does not divide $\beta(2^{n-1})$. Moreover, $\beta(2^{n-1} - \Delta) = \beta(2^{n-1} + \Delta)$. Let $y = 2^{n-1} + \Delta$, then we have, $\beta(\Delta) = 2\Delta^2 + 2^n(2^n - 1)$. By letting $\Delta = 0$, we have, $Q^* \geq \lceil 2^{n-1} - 2^{n-1}(2^n - 1)^{-1} \rceil = 2^{n-1}$ (see (6)) which implies $\Delta = \pm 2^{n/2-1}$. Since $\beta(y)$ is convex, binary bent functions exist only for $B_i(0) = 2^{n-1} \pm 2^{n/2-1}$, $i \in \{0,1\}$. □

Binary bent functions [1,2,7-10] $f(x)$ ($f: V_n$ over $GF(2) \rightarrow \{0,1\}$) can be constructed by the following formula

$$f(x) = f(u,v) = \langle u, \pi(v) \rangle + G(u), \quad (9)$$

where $u, v \in V_{n/2}$ over $GF(2)$, $\langle \cdot, \cdot \rangle$ denotes inner product and $\pi(v)$ denotes permutation on components of v .

It is important to note, that n must be even for the existence of $f(x)$ ($x \in V_n$ over $GF(q)$).

Often [1,2,7-10] $F(x) \Delta (-1)^{f(x)}$, $F: V_n$ over $GF(2) \rightarrow \{1,-1\}$, was considered instead of $f: V_n$ over $GF(2) \rightarrow \{0,1\}$. In this case the autocorrelation function (1) of $F(x)$ becomes the difference in sizes of the sets $\{x \mid f(x)=f(x+e)\}$ and $\{x \mid f(x) \neq f(x+e)\}$. Moreover, one have for the Walsh-Hadamard coefficients of $F(x)$, $\hat{F}(\omega) = \pm 2^{n/2}$ for all ω . The relation between the autocorrelation function of $F(x)$ to $B_{\Sigma}(e)$ is given by

$$\sum_x F(x)F(x+e) = 2^n - 2B_{\Sigma}(e). \quad (10)$$

2 Q-Ary Bent Functions

A construction of q -ary bent function defined by $B_{\Sigma}(e) = q^{n-1}$ is given in the following theorem.

Theorem 2

For $f(x) = f(u,v) = \langle u,v \rangle$, (11)

where $f(x) \in GF(q)$, $x \in V_n$ over $GF(q)$, $q=p^s$, $u,v \in V_{n/2}$ over $GF(q)$, we have $B_{\Sigma}(e) = |\{x \mid f(x)=f(x+e)\}| = q^{n-1}$ for all $e \neq 0$. □

The function $f(x) = uv$, $x \in V_2$ over $GF(3)$ and $u,v \in V_1$ over $GF(3)$ considered in Example 1 is in fact an example of bent function constructed by (11). Let us consider another example of q -ary bent function of the form given in (11).

Example 3. Let $f(x) = f(u,v) = \langle u,v \rangle$ be defined in $f(x) \in GF(2^3)$, $x \in V_{2m}$ over $GF(2^3)$, $u,v \in V_m$ over $GF(2^3)$. Let $u = (u_0, u_1, \dots, u_{m-1})$, $v = (v_0, v_1, \dots, v_{m-1})$, $u_i, v_i \in GF(2^3)$ and the polynomial representations of u_i, v_i are $u_i = u_{2,i}\alpha^2 + u_{1,i}\alpha + u_{0,i}$, $v_i = v_{2,i}\alpha^2 + v_{1,i}\alpha + v_{0,i}$, $u_{j,i}, v_{j,i} \in GF(2)$. Then for the irreducible polynomial used in the construction of $GF(2^3)$ being $\alpha^3 + \alpha + 1$, we have

$$f(x) = u_0v_0 + u_1v_1 + \dots + u_{m-1}v_{m-1} = g_2(u,v)\alpha^2 + g_1(u,v)\alpha + g_0(u,v), \quad (12)$$

where $g_2(u,v) = g_{2,0}(u_0,v_0) + g_{2,1}(u_1,v_1) + \dots + g_{2,m-1}(u_{m-1},v_{m-1})$,

$$g_1(u,v) = g_{1,0}(u_0,v_0) + g_{1,1}(u_1,v_1) + \dots + g_{1,m-1}(u_{m-1},v_{m-1}),$$

$$g_0(u,v) = g_{0,0}(u_0,v_0) + g_{0,1}(u_1,v_1) + \dots + g_{0,m-1}(u_{m-1},v_{m-1}),$$

$g_j(u,v), g_{j,i}(u_i,v_i) \in GF(2)$ and

$$g_{2,i}(u_i, v_i) = u_{2,i}v_{2,i} + u_{0,i}v_{2,i} + u_{1,i}v_{1,i} + u_{2,i}v_{0,i},$$

$$g_{1,i}(u_i, v_i) = u_{2,i}v_{1,i} + u_{1,i}v_{2,i} + u_{2,i}v_{1,i} + u_{0,i}v_{1,i} + u_{1,i}v_{0,i},$$

$$g_{0,i}(u_i, v_i) = u_{1,i}v_{2,i} + u_{2,i}v_{1,i} + u_{0,i}v_{0,i}.$$

The autocorrelation function of $f(x)$, $B_{\Sigma}(e) = q^{n-1} = 2^{6m-3}$, for all $e \neq 0$, implies that

$$\begin{aligned} B_{\Sigma}(e) &= |\{x \mid f(x) = f(x+e)\}| \\ &= |\{x \mid g_2(x) = g_2(x+e), g_1(x) = g_1(x+e), g_0(x) = g_0(x+e)\}|. \end{aligned} \quad (13) \quad \square$$

From the above example we see that q -ary bent functions constructed by (11) with $q=p^s$ may be viewed as a system of s p -ary bent functions. This brings us the following theorem.

Theorem 3

Consider

$$f(x) = \langle u, v \rangle = (g_0(x), g_1(x), \dots, g_{s-1}(x)), \quad (14)$$

defined in (11) where $g_i(x)$, $i=0,1,\dots,s-1$ are functions corresponding to the coefficients of the polynomial representation of $f(x)$. Then any system $G(x)$ consisting of r arbitrarily chosen functions from $\{g_i(x), i=0,1,\dots,s-1\}$ has the property that

$$|\{x \mid G(x) = G(x+e)\}| = p^{2ms-r}, \quad 1 \leq r \leq s-1. \quad (15) \quad \square$$

The construction of q -ary bent functions considered in this section, implies a partition of the space V_n over $GF(q)$ into q equivalent classes C_i , $i=0,1,\dots,q-1$, where

$$C_i = \{x \mid f(u, v) = \langle u, v \rangle = i\}, \quad i \in GF(q). \quad (16)$$

Moreover, $B_i(0) = |\{x \mid f(x) = i\}| = |C_i|$, $i=0,1,\dots,q-1$, such that $B_{\Sigma}(e) = q^{n-1}$ is unique.

In the next section we will investigate autocorrelation functions $B_i(e)$ of characteristic functions $f_i(u, v)$ and show that $B_i(e)$ is asymptotically bent as $n \rightarrow \infty$.

3 Asymptotically Bent Binary Functions

A binary function $f_i(x)$, $f_i: V_n$ over $GF(q) \rightarrow \{0,1\}$, $q=p^s$, we are now considering, is the i th characteristic function of $f(u, v) = \langle u, v \rangle$, $u, v \in V_{n/2}$ over $GF(q)$. Let $n=2m$, then

$$f_i(x) \in \{0,1\}, \quad f_i(x) = 1 \text{ iff } f(x) = \langle u, v \rangle = i, \quad i \in GF(q), \quad u, v \in V_m \text{ over } GF(q). \quad (17)$$

Theorem 4 [5]

The autocorrelation function of the ith characteristic function

$$B_i(t, \tau) = | \{ x \mid f(u, v) = f(u+t, v+\tau) = i \} |, \quad t, \tau \in V_m \text{ over } GF(q), \quad (18)$$

is given as follows.

(i) For i=0,

$$B_i(t, \tau) = \begin{cases} q^{2m-1} - q^{m-1}, & t=\tau=0; \\ q^{2m-2} \pm q^{m-1}, & \text{otherwise.} \end{cases} \quad (19)$$

Moreover, for p=2

$$B_i(t, \tau) = \begin{cases} q^{2m-1} - q^{m-1}, & t=\tau=0; \\ q^{2m-2} + \mu(i, T)q^{m-1}, & \text{otherwise;} \end{cases} \quad (20)$$

where

$$T = \langle t, \tau \rangle \quad \text{and} \quad \mu(i, T) = \begin{cases} 1, & \text{Tr}(iT^{-1})=0, T \neq 0; \\ -1, & \text{otherwise,} \end{cases} \quad (21)$$

and $\text{Tr}(\alpha) = 1 + \alpha + \alpha^2 + \dots + \alpha^{2^s-1}$, $\text{Tr}(\alpha) \in GF(2)$.

(ii) For i=0,

$$B_i(t, \tau) = \begin{cases} q^{2m-1} + q^{m-1}, & t=\tau=0; \\ q^{2m-2} + q^{m-1} + \delta_T \cdot (q-2)q^{m-1}, & \text{otherwise,} \end{cases} \quad (22)$$

where $\delta_T \in \{0, 1\}$, $\delta_T=1$ iff $T=0$. □

From the above formulae (20) and (22) we have the following theorem.

Theorem 5

The binary function given by (17) is asymptotically bent, that is, as $n \rightarrow \infty$,

$$B_i(t, \tau) \sim q^{n-2} \quad \text{for all } (t, \tau) \neq 0, \quad i \in GF(q). \quad (23) \quad \square$$

A Lower bound on $\text{Max}_{(t, \tau) \neq 0} B_i(t, \tau)$ can also be derived similarly to (5) and it is given by the following theorem.

Theorem 6

$$\text{Max}_{(t, \tau) \neq 0} B_i(t, \tau) \geq \begin{cases} 2 \left[\frac{B_i(0)(B_i(0) - 1)}{2(q^n - 1)} \right], & p=2; \\ \left[\frac{B_i(0)(B_i(0) - 1)}{(q^n - 1)} \right], & p>2. \end{cases} \quad (24)$$

Note that, for p=2, $B_i(t, \tau)$ is an even integer. □

By substituting the values of $B_i(0)$ given in (20) and (22) into (24) one can see that the asymptotical value of $B_i(t, \tau) = q^{2n-2}$ indeed satisfies (24) as $n \rightarrow \infty$.

In Section 4.2 error-detecting codes constructed from an equivalent class induced by a q-ary bent function will be discussed.

4 Applications of Bent Functions to VLSI Testing and Error-Detection

Bent functions can be applied to error detection in messages transmitted over noisy channels. In particular, we will consider the problem of error (fault) detection/testing for computation channels (VLSI chips) and a design of error-detecting codes for communication channels. For channels in which the statistics of errors are difficult to model (unknown) or uniformly distributed, a viable strategy for error detection is to provide equal protection against all errors. Hence, bent functions are of interest because of their constant-autocorrelation property.

4.1 Optimal Compression for VLSI Test Responses

Testing of Very Large Scale Integration (VLSI) chips typically require millions of test patterns [13]. Thus, the problem of excessive size of memory storing the correct (fault-free) responses is encountered. To render this excessive storage problem test responses are compressed into an r-symbol word called "signature" (or "syndrome" as in error-control-codings' terminology). Thus, only the signature of the correct responses is kept as the reference data. By comparing the reference signature and the test responses' signature we decide whether there occurred physical failures (faults) causing a malfunction of the device-under-test.

To analyze the performance of the test responses compression scheme, we assume that faults manifest themselves as errors in test responses. (This is guaranteed for the case of exhaustive testing, of course, excluding physical failures in redundant components.) The performance measure for a compressor of test responses is defined in terms of the conditional error-masking probabilities given errors. These probabilities are defined in the following way.

Let x be the fault-free response which is viewed as an n-dimensional vector over q-ary symbols, that is, $x \in V_n$ over $GF(q)$, $q=p^s$ (For most VLSI applications $p=2$). With the probability space of the fault-free responses attained from testing of an ensemble of VLSI devices we can assume equally-likely probabilities for all x . Now, the conditional error-masking probabilities given error vector e , $e \in V_n$ over $GF(q)$, $e \neq 0$, is defined as

$$Q_{\Sigma}(e) \triangleq \frac{|\{x \mid f(x)=f(x+e)\}|}{q^n} = q^{-n} B_{\Sigma}(e), \quad (25)$$

where $f(x)$ is the signature of the fault-free response x and the compression is defined by the mapping $f: V_n$ over $GF(q) \rightarrow GF(q)$. Moreover, an error (x, e) is masked iff $f(x)=f(x+e)$.

In the following theorem we summarize the application of q-ary ($q=p^s$) bent function to the compression testing of VLSI devices.

Corollary 1 [3].

Quadratic compressors $G(x) = \{g_0(x), g_1(x), \dots, g_{r-1}(x)\}$ where $G(x)$ is a subset of $f(x) = \{f_0(x), f_1(x), \dots, f_{s-1}(x)\} = f(u,v) = \langle u,v \rangle$, $u,v \in V_m$ over $GF(q)$, $f(x) \in GF(q)$, $q=p^s$, $f_i(x) \in GF(p)$, are optimal with respect to the lower bound

$$\text{Min}_{\{f\}} \text{Max}_{e \neq 0} Q_{\Sigma}(e) \geq p^{-r}, \quad r \leq s. \quad (26)$$

From the above corollary we conclude that for the case when the probability distribution of errors in VLSI test responses is difficult to characterize quadratic compressors provide an optimal protection with $Q_{\Sigma}(e) = p^{-r}$ for all $e \neq 0$ (where r is the size of signature). In other words, the average performance of quadratic compressors

$$Q_{\text{total}} = \sum_{e \neq 0} Q_{\Sigma}(e) \text{Pr}[e | e \neq 0] = p^{-r}, \quad (27)$$

is independent of a probability distribution of errors $\text{Pr}[e | e \neq 0]$.

4.2 Quadratic Codes

In this section we will consider the problem of constructing optimal error-detecting codes for communication channels with unknown errors characteristics which may arise due to jammings or other modeling uncertainties [15].

Let x be a codeword and \bar{x} be a received message, possibly corrupted by an error e , $\bar{x} = x+e$. We define the conditional error-masking probability, given error e ($e \neq 0$), for the code C as follows

$$Q(e) \triangleq \frac{|\{(x, \bar{x}) | \bar{x} = x+e, x, \bar{x} \in C\}|}{|C|} - 1. \quad (28)$$

Our goal is for a given number of codewords $|C|$ and a block size n , to construct a code such that maxima of $Q(e)$ over all $e \neq 0$ are minimal. In other words, for a given code rate [1] $R = n^{-1} \log_q |C|$ (codewords are blocks of q -ary symbols of length n), construct a code satisfying the minimax criterion on $Q(e)$, that is, $\text{Min}_{C \in S_R} \text{Max}_{e \neq 0} Q(e)$, where S_R is a set of all codes with rate R .

The following corollaries summarize the definition and parameters of quadratic codes C and show that these codes are asymptotically optimal with respect to the minimax criterion on error detection. (This minimax criterion has been widely used in estimation theory [15,16]).

Corollary 2 [6]

Let for a given $\sigma \in GF(q)$,

$$(u,v) \in C \Leftrightarrow \langle u,v \rangle = \sigma, \quad (29)$$

where a codeword (u,v) is a block q -ary symbols of length $n=2m$, that is, $u,v \in V_m$ over $GF(q)$, $q=p^s$. Then the number of q -ary information symbols for C

is $k = n-1$ and the number q -ary check symbols is $r = 1$. Further, we have for the conditional error-masking probability, given error $e=(t, \tau)$ ($e \neq 0$),

$$Q(t, \tau) = |\{(u, v) \mid \langle u, v \rangle = \langle u+t, v+\tau \rangle = \sigma\}| \cdot |C|^{-1} = B_\sigma(t, \tau) B_\sigma(0, 0)^{-1}, \quad (30)$$

and the formulae for $|C| = B_\sigma(0, 0)$ and $Q(t, \tau)$ are given as follows.

(i) For $\sigma=0$,

$$|C| = q^{2m-1} - q^{m-1}, \quad (31)$$

$$Q(t, \tau) = (q^{2m-2} - q^{m-1}) (q^{2m-1} - q^{m-1})^{-1} - q^{-1} \text{ as } n \rightarrow \infty, (t, \tau) \neq 0. \quad (32)$$

Moreover, for $q=2^s$

$$Q(t, \tau) = (2^{2ms-2s+\mu(\sigma, T)} - 2^{ms-1}) (2^{2ms-s} - 2^{ms-s})^{-1} - 2^{-s} \text{ as } n \rightarrow \infty, \quad (33)$$

$(t, \tau) \neq 0$, where $T = \langle t, \tau \rangle$ and $\mu(\sigma, T) \in \{1, -1\}$, $\mu(\sigma, T) = 1$ iff $\text{Tr}(\sigma T^{-1}) = 0$, $T \neq 0$.

(ii) For $\sigma \neq 0$,

$$|C| = q^{2m-1} - q^{m-1} + q^m, \quad (34)$$

$$Q(t, \tau) = (q^{2m-2} + q^{m-1} + \delta_T \cdot (q-2)q^{m-1}) (q^{2m-1} - q^{m-1} + q^m)^{-1} - q^{-1} \text{ as } n \rightarrow \infty, \quad (35)$$

$(t, \tau) \neq 0$ where $\delta_T \in \{0, 1\}$, $\delta_T = 1$ iff $T = 0$. □

Corollary 3 [5]

The lower bound on the conditional error-masking probability given error e ($e \neq 0$) is given by

$$\text{Max}_{(t, \tau) \neq 0} Q(t, \tau) \geq \begin{cases} \frac{2}{|C|} \left[\frac{|C| (|C| - 1)}{2 (q^n - 1)} \right], & p=2; \\ \frac{1}{|C|} \left[\frac{|C| (|C| - 1)}{(q^n - 1)} \right], & p>2. \end{cases} \quad (36)$$

Therefore, quadratic codes are asymptotically optimal with respect to (36). □

In summary, quadratic codes provide equal protection against all errors. For these codes a total error-masking probability

$$Q_{\text{total}} = \sum_{e \neq 0} Q(e) \text{Pr}[e \mid e \neq 0] - q^{-1} \quad (37)$$

is independent on a distribution of errors $\text{Pr}[e \mid e \neq 0]$. Hence, quadratic codes offer a viable alternative for error-detecting for channels with unknown or difficult to model noise characteristics.

We will conclude this section with an example of a quadratic code which also illustrates the encoding and decoding procedures.

Example 4. The quadratic code with the block size $n=4$ and symbols from $GF(2^2)$ where the number of information symbols is $k=3$, the number of redundant symbol is $r=1$ and syndrome $\sigma=1, 1 \in GF(2^2)$ is presented in Table 2(a). For a codeword (u_0, u_1, v_0, v_1) , $u_i, v_i \in GF(2^2)$, v_1 is the redundant symbol if $M_1=0$ and v_0 is the redundant symbol if $M_1=1$ (redundant symbol is underlined for every codeword shown). Note that $(M_0, M_1) = (u_0, u_1) \neq (0, 0)$ since for this example $(u, v) \in C$ iff $\langle u, v \rangle = \sigma = 1$. For this code $|C| = 60$ and the maximum value of $Q(e)$ is 0.3333.

Message M_0, M_1, M_2	Codewords (u_0, u_1, v_0, v_1)
0 1 0	0 1 0 <u>1</u>
0 1 1	0 1 <u>1</u> 1
0 1 α	0 1 α <u>1</u>
0 1 α^2	0 1 α^2 <u>1</u>
0 α 0	0 α 0 <u>α^2</u>
...	...
1 0 0	1 0 <u>1</u> 0
1 0 1	1 0 <u>1</u> 1
1 0 α	1 0 <u>1</u> α
1 0 α^2	1 0 <u>1</u> α^2
1 1 0	1 0 <u>1</u> <u>1</u>
...	...
α^2 α^2 α	α^2 α^2 α <u>0</u>
α^2 α^2 α^2	α^2 α^2 α^2 <u>1</u>

- $(u_0, u_1, v_0, v_1) \in C \iff \langle (u_0, u_1), (v_0, v_1) \rangle = 1$
- $(u_0, u_1), (v_0, v_1) \in V_2$ over $GF(2^2)$
- $u_i, v_i \in GF(2^2)$

0	0 0
1	0 1
α	1 0
α^2	1 1

Table 2(b). Elements of $GF(2^2)$

Table 2(a). Example of a Quadratic Code

5 Conclusion

A theory of bent (flat autocorrelation) functions and their applications to error-detection in computation and communication channels have been presented. Traditionally, bent functions were defined as mapping from n -dimensional vector space over $\{0,1\}$ onto $\{0,1\}$ and generally as quadratic forms over $GF(2)$. We have shown that bent functions, which are characterized by their autocorrelation functions being a constant, can also be constructed as mappings from V_n over $GF(q)$ onto $GF(q)$, $q=p^s$. However, these generalized bent functions $f(x)=f(u,v)=\langle u,v \rangle$ (quadratic forms) have only the total autocorrelation functions being constant $B_{\Sigma}(e) = |\{x \mid f(x)=f(x+e)\}| = q^{n-1}$ for all $e \neq 0$. We have shown further that the autocorrelation function of the characteristic function $f_i(x) \in \{0,1\}$, $f_i(x)=1$ iff $f(x)=i$, $B_i(e)$ is asymptotically constant as $n \rightarrow \infty$. Therefore, a class of binary asymptotically bent functions has been developed. Applications of q -ary bent functions to error-detection are justified when the statistic of errors are unknown. For error detection schemes based on minimax criteria, we have shown that compression of test responses techniques and error-detection codes constructed by bent functions are optimal.

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