

Name: Poof D

Discussion Section: _____

MA 226 Section B – Exam 3a

Spring 2014

Question Number	Possible Points	Student Score
1	16	
2	12	
3	14	
4	12	
5	10	
6	12	
7	10	
8	14	
Total Points	100	

You must show your work to receive full credit

Discussion Sections:

B2: Tuesday 4:30-5:30

B3: Tues : 3:30-4:30

B4: Weds: 9-10

B5: Weds: 10-11

B6: Weds: 4:30-5:30

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1.) (4 pts each) Find the Inverse Laplace Transform of the following expressions:

$$a) \mathcal{L}^{-1}\left[\frac{3}{4s-2}\right] = \frac{3}{4} \mathcal{L}^{-1}\left[\frac{1}{s-\frac{1}{2}}\right] = \boxed{\frac{3}{4} e^{\frac{1}{2}t}}$$

$$b) \mathcal{L}^{-1}\left[\frac{s+3}{s(s^2+3)}\right] = \mathcal{L}^{-1}\left[\frac{1}{s} + \frac{-s+1}{s^2+3}\right]$$

$$= \mathcal{L}^{-1}\left[\frac{1}{s}\right] - \mathcal{L}^{-1}\left[\frac{s}{s^2+3}\right] + \frac{1}{\sqrt{3}} \mathcal{L}^{-1}\left[\frac{\sqrt{3}}{s^2+3}\right]$$

$$= \boxed{1 - \cos\sqrt{3}t + \frac{1}{\sqrt{3}} \sin\sqrt{3}t}$$

$$\frac{s+3}{s(s^2+3)} = \frac{A}{s} + \frac{Bs+C}{s^2+3}$$

$$s+3 = As^2 + 3A + Bs^2 + Cs$$

$$s+3 = (A+B)s^2 + Cs + 3A$$

$$3A=3 \Rightarrow A=1$$

$$C=1$$

$$B=-1$$

check

$$\frac{1}{s} + \frac{-s+1}{s^2+3} = \frac{s^2+3-s^2+s}{s(s^2+3)} = \frac{s+3}{s(s^2+3)} \checkmark$$

$$c) \mathcal{L}^{-1}\left[\frac{e^{-s}}{s^3}\right] = \frac{1}{2} \mathcal{L}^{-1}\left[\frac{2e^{-s}}{s^3}\right] = \boxed{\frac{1}{2} u_1(t)(t-1)^2}$$

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1.) (continued) Find the inverse Laplace transform:

$$d) \mathcal{L}^{-1}\left[\frac{s \cdot e^{-3s}}{s^2 - 4s + 6}\right] = \mathcal{L}^{-1}\left[\frac{s e^{-3s}}{(s-2)^2 + 2}\right]$$

$$= \mathcal{L}^{-1}\left[\frac{((s-2) + 2) e^{-3s}}{(s-2)^2 + 2}\right]$$

$$= \mathcal{L}^{-1}\left[\frac{(s-2) e^{-3s}}{(s-2)^2 + 2}\right] + \sqrt{2} \mathcal{L}^{-1}\left[\frac{\sqrt{2} e^{-3s}}{(s-2)^2 + 2}\right]$$

$$= u_3(t) e^{2(t-3)} \cos(\sqrt{2}(t-3)) +$$

$$\sqrt{2} u_3(t) e^{2(t-3)} \sin(\sqrt{2}(t-3))$$

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2. (12 pts) Six second order equations and four $y(t)$ - graphs are given below. For each $y(t)$ - graph, determine the second-order equation for which $y(t)$ is a solution, and state briefly how you know your choice is correct.

(i) $\frac{d^2y}{dt^2} + 18y = 3\cos 4t$

(ii) $\frac{d^2y}{dt^2} + 16y = 8$

(iii) $\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 16y = 3\cos 4t$

(iv) $\frac{d^2y}{dt^2} + 16y = 3\cos 4t$

(v) $\frac{d^2y}{dt^2} + 16y = -8$

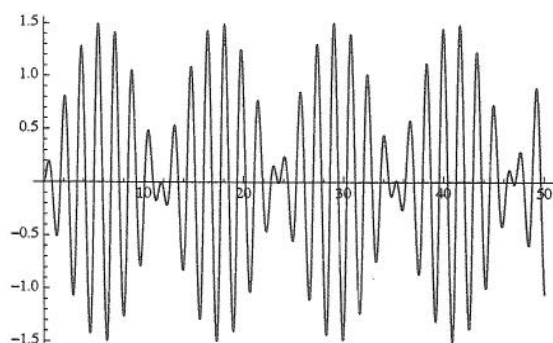
(vi) $\frac{d^2y}{dt^2} + 12y = 3\cos 4t$

$\bar{F}_N = \frac{2\sqrt{3}}{2\pi}$

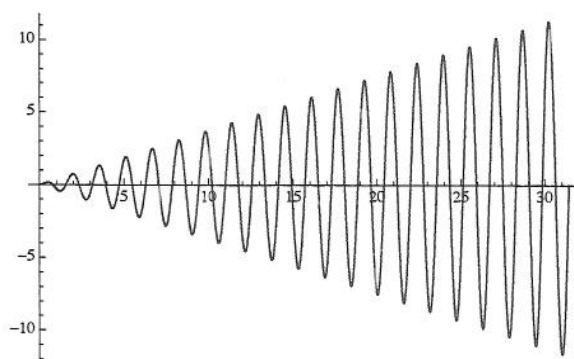
$F_f = \frac{4}{2\pi}$

Beating freq = $\left(\frac{F_N - F_f}{2}\right) \approx$

A

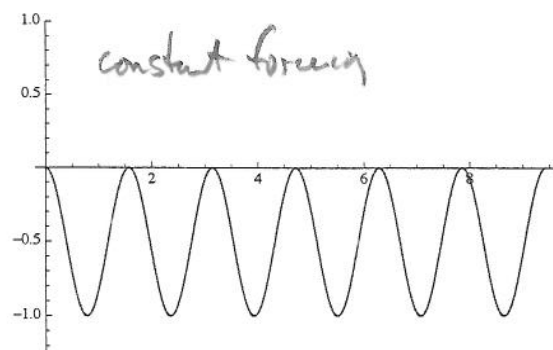
Beating period is ≈ 24 equation: vireason: Beating period is ≈ 24

B

equation: ivreason: resonance frequency
Forcing freq = natural frequency

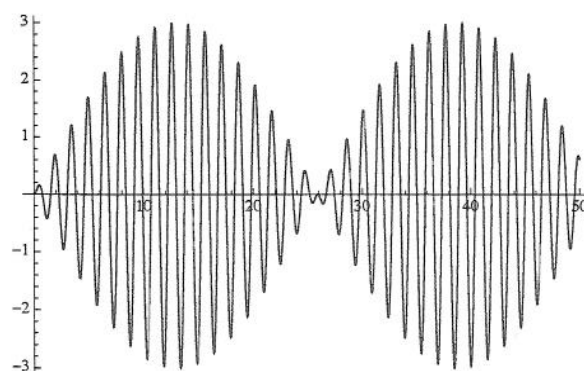
C

constant forcing

equation: ✓

reason: constant negative forcing

D

Beating period ≈ 50 equation: (ii)reason: Beating Period ≈ 50

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3. (14 pts) Find the general solution of : $\frac{d^2y}{dt^2} + 6\frac{dy}{dt} + 8y = 16t + e^{-2t}$ characteristic eqn $s^2 + 6s + 8 = 0$

$$s = \frac{-6 \pm \sqrt{36 - 32}}{2} = \frac{-6 \pm 2}{2} \quad s = -2, -4$$

4pt $y_h(t) = k_1 e^{-2t} + k_2 e^{-4t}$

$$y_p(t) = At + B$$

$$y_p'(t) = A$$

$$y_p''(t) = 0$$

$$0 + 6A + 8(A + B) = 16t$$

$$8At + (6A + 8B) = 16t$$

$$8A = 16$$

$$A = 2$$

$$6A + 8B = 0$$

$$B = -\frac{12}{8} = -\frac{3}{2}$$

General Solution

$$y(t) = y_h(t) + y_{p_1}(t) + y_{p_2}(t)$$

$$y(t) = k_1 e^{-2t} + k_2 e^{-4t} + 2t - \frac{3}{2}$$

$$+ \frac{1}{2} t e^{-2t}$$

5pts $y_{p_1}(t) = 2t - \frac{3}{2}$

$$y_{p_2}(t) = A t e^{-2t}$$

$$y_{p_2}'(t) = A e^{-2t} - 2A t e^{-2t}$$

$$y_{p_2}''(t) = -2A e^{-2t} - 2A e^{-2t} + 4A t e^{-2t}$$

$$-4A e^{-2t} + 4A t e^{-2t} + 6(A e^{-2t} - 2A t e^{-2t}) + 8A t e^{-2t} = e^{-2t}$$

$$(-4A + 6A)A e^{-2t} + 12A t e^{-2t} - 12A t e^{-2t} = 1 \cdot e^{-2t}$$

$$2A = 1 \Rightarrow A = \frac{1}{2}$$

5pts $y_{p_2}(t) = \frac{1}{2} t e^{-2t}$

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4. Short answer (4 pts each)

- a) What is the
- beating frequency
- and the
- rapid response frequency
- of the solution to the

undamped equation: $\frac{d^2y}{dt^2} + 9y = 2\cos(4t)$

$$F_N = \frac{3}{2\pi} \quad F_f = \frac{4}{2\pi}$$

$$F_B = \left| \frac{F_N - F_f}{2} \right| = \frac{1}{4\pi}$$

$$F_R = \frac{F_N + F_f}{2} = \frac{7}{4\pi}$$

- b) Given the 2
- nd
- order linear non-homogeneous differential equation
- $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 13y = 3\cos(2t)$

has general solution $y(t) = k_1 e^{-2t} \cos 3t + k_2 e^{-2t} \sin 3t + \frac{27}{145} \cos 2t + \frac{24}{145} \sin 2t$. What is the generalsolution of $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 13y = 15\cos(2t)$

multiply by 5

$$y(t) = k_1 e^{-2t} \cos 3t + k_2 e^{-2t} \sin 3t + \frac{27}{29} \cos 2t + \frac{24}{29} \sin 2t$$

- c) What is the amplitude of the
- steady state behavior
- of behavior of a 2
- nd
- order differential equation whose general solution is given by:
- $y(t) = k_1 e^{-t} + k_2 e^{-3t} + 3\sin 2t + 5\cos 2t$

steady state behavior

$$A = \sqrt{3^2 + 5^2} = \sqrt{34}$$

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5. (10 pts) Compute the Laplace Transform of the function $w(t)$ using the definition of the Laplace Transform:

$$w(t) = \begin{cases} 2t, & \text{if } 0 \leq t < 1 \\ 2, & \text{if } t \geq 1 \end{cases}$$

$$\mathcal{L}[w(t)] = \int_0^{\infty} w(t) e^{-st} dt$$

$$= \int_0^1 \underbrace{2t}_{u} \underbrace{e^{-st}}_{dv} dt + \int_1^{\infty} 2e^{-st} dt$$

$du = 2dt \quad v = \frac{e^{-st}}{s}$

5 pts

$$= 2t \left(\frac{e^{-st}}{s} \right) \Big|_0^1 - \int_0^1 \frac{e^{-st}}{s} \cdot 2 dt + \lim_{b \rightarrow \infty} 2 \int_1^b e^{-st} dt$$

$$= -\frac{2e^{-s}}{s} - 0 - \frac{2}{s^2} e^{-st} \Big|_0^1 + \lim_{b \rightarrow \infty} -\frac{2}{s} e^{-st} \Big|_1^b$$

5 pts

$$= -\frac{2e^{-s}}{s} - \frac{2}{s^2} e^{-s} + \frac{2}{s^2} + \lim_{b \rightarrow \infty} -\frac{2}{s} e^{-sb} + \frac{2}{s} e^{-s}$$

$\rightarrow 0$

$$= \frac{2}{s^2} - \frac{2}{s^2} e^{-s}$$

$$= \frac{2}{s^2} (1 - e^{-s})$$

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7. (10 pts) The nonlinear autonomous system

$$\frac{dx}{dt} = x(2-x-y) = 2x - x^2 - xy = f(x,y)$$

$$\frac{dy}{dt} = y(y-x^2) = y^2 - x^2y = g(x,y)$$

has an equilibrium point at $(-2,4)$. Use Linearization to classify the type of equilibrium point. If the equilibrium point is a spiral sink or a spiral source give the direction of the spiral.

$$J = \begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} 2-2x-y & -x \\ -2xy & 2y-x^2 \end{pmatrix} \quad 3 \text{ pts}$$

$$J(-2,4) = \begin{pmatrix} 2 & 2 \\ 16 & 4 \end{pmatrix} \quad 2 \text{ pts}$$

Linear System $\frac{d\bar{y}}{d\bar{t}} = \begin{bmatrix} 2 & 2 \\ 16 & 4 \end{bmatrix} \bar{y}$

eigenvalues $\det \begin{bmatrix} 2-\lambda & 2 \\ 16 & 4-\lambda \end{bmatrix} = 0$

$$(2-\lambda)(4-\lambda) - 32 = 0$$

$$\lambda^2 - 6\lambda + 8 - 32 = 0$$

$$\lambda^2 - 6\lambda - 24 = 0$$

$$\lambda = \frac{6 \pm \sqrt{36 - 4(-24)}}{2} = 6 \pm \sqrt{33} \quad 3 \text{ pts}$$

$$\lambda_1 = 3 + \sqrt{33} > 0$$

$$\lambda_2 = 3 - \sqrt{33} < 0$$

$\Rightarrow$ saddle point (2 pts)

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6. (12 pts) Find a particular solution of $\frac{d^2y}{dt^2} + 6\frac{dy}{dt} + 8y = 5\cos 3t$ using complexification.

$$\frac{d^2y}{dt^2} + 6\frac{dy}{dt} + 8y = 5e^{3it}$$

$$\left. \begin{aligned} y_c(t) &= Ae^{3it} \\ y'_c(t) &= 3iAe^{3it} \\ y''_c(t) &= -9Ae^{3it} \end{aligned} \right\} \text{plug in}$$

$$-9Ae^{3it} + 18iAe^{3it} + 8Ae^{3it} = 5e^{3it}$$

$$(-A + 18iA)e^{3it} = 5e^{3it}$$

$$A(-1 + 18i) = 5$$

$$A = \frac{5}{-1 + 18i} = \frac{5}{325}(-1 - 18i)$$

6 pts

$$A = \frac{-1}{65}(1 + 18i)$$

$$y_c(t) = \frac{-1}{65}(1 + 18i)(\cos 3t + i\sin 3t)$$

$$= \frac{-1}{65} \left(\underbrace{(\cos 3t - 18\sin 3t)}_{\text{Re}(y_c(t))} + i(18\cos 3t + \sin 3t) \right)$$

$$y_p(t) = -\frac{1}{65}\cos 3t + \frac{18}{65}\sin 3t$$

(6 pts)

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8. (14 pts) Solve the 2nd order linear non-homogeneous initial value problem:

(you can use the next page too if you need more space)

$$\frac{d^2 y}{dt^2} + 6 \frac{dy}{dt} + 13y = 13u_4(t) \quad \text{with } y(0)=1 \text{ and } y'(0)=2$$

$$s^2 \mathcal{L}[y] - s y(0) - y'(0) + 6[s \mathcal{L}[y] - y(0)] + 13 \mathcal{L}[y] = \mathcal{L}[13u_4(t)]$$

$$s^2 \mathcal{L}[y] - s \cdot 1 - 2 + 6s \mathcal{L}[y] - 6 + 13 \mathcal{L}[y] = 13 \frac{e^{-4s}}{s}$$

$$(s^2 + 6s + 13) \mathcal{L}[y] - s - 8 = 13 \frac{e^{-4s}}{s}$$

5 pts

$$\mathcal{L}[y] = \frac{s+8}{s^2+6s+13} + \frac{13e^{-4s}}{s(s^2+6s+13)}$$

partial fraction 3 pts (next page)

$$\mathcal{L}[y] = \frac{s+8}{(s+3)^2+4} + e^{-4s} \left(\frac{1}{s} - \frac{s+6}{s^2+6s+13} \right)$$

$$= \frac{s+3+5}{(s+3)^2+4} + e^{-4s} \left(\frac{1}{s} - \frac{s+3+3}{(s+3)^2+4} \right)$$

$$\mathcal{L}[y] = \frac{s+3}{(s+3)^2+4} + \frac{5}{2} \frac{2}{(s+3)^2+4} + \frac{e^{-4s}}{s} - \frac{(s+3)e^{-4s}}{(s+3)^2+2^2} + \frac{3}{2} \frac{2 \cdot e^{-4s}}{(s+3)^2+4}$$

2 pts

$$y(t) = e^{-3t} \cos 2t + \frac{5}{2} e^{-3t} \sin 2t + u_4(t) - u_4(t) e^{-3(t-4)} \cos 2(t-4) + \frac{3}{2} u_4(t) e^{-3(t-4)} \sin 2(t-4)$$

4 pts

$$\frac{13}{s(s^2+6s+13)} = \frac{A}{s} + \frac{Bs+C}{s^2+6s+13}$$

$$\frac{As^2+6As+13A+Bs^2+Cs}{s(s^2+6s+13)}$$

$$13 = (A+B)s^2 + (6A+C)s + 13A$$

$$A+B = 0$$

$$6A+C = 0$$

$$13A = 13 \Rightarrow A=1, B=-1, C=-6$$

Table 6.1

Frequently Encountered Laplace Transforms.

$y(t) = \mathcal{L}^{-1}[Y]$	$Y(s) = \mathcal{L}[y]$	$y(t) = \mathcal{L}^{-1}[Y]$	$Y(s) = \mathcal{L}[y]$
$y(t) = e^{at}$	$Y(s) = \frac{1}{s-a} \quad (s > a)$	$y(t) = t^n$	$Y(s) = \frac{n!}{s^{n+1}} \quad (s > 0)$
$y(t) = \sin \omega t$	$Y(s) = \frac{\omega}{s^2 + \omega^2}$	$y(t) = \cos \omega t$	$Y(s) = \frac{s}{s^2 + \omega^2}$
$y(t) = e^{at} \sin \omega t$	$Y(s) = \frac{\omega}{(s-a)^2 + \omega^2}$	$y(t) = e^{at} \cos \omega t$	$Y(s) = \frac{s-a}{(s-a)^2 + \omega^2}$
$y(t) = t \sin \omega t$	$Y(s) = \frac{2\omega s}{(s^2 + \omega^2)^2}$	$y(t) = t \cos \omega t$	$Y(s) = \frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$
$y(t) = u_a(t)$	$Y(s) = \frac{e^{-as}}{s} \quad (s > 0)$	$y(t) = \delta_a(t)$	$Y(s) = e^{-as}$

Table 6.2

Rules for Laplace Transforms:

Given functions $y(t)$ and $w(t)$ with $\mathcal{L}[y] = Y(s)$ and $\mathcal{L}[w] = W(s)$ and constants α and a .

Rule for Laplace Transform	Rule for Inverse Laplace Transform
$\mathcal{L}\left[\frac{dy}{dt}\right] = s\mathcal{L}[y] - y(0) = sY(s) - y(0)$	
$\mathcal{L}[y + w] = \mathcal{L}[y] + \mathcal{L}[w] = Y(s) + W(s)$	$\mathcal{L}^{-1}[Y + W] = \mathcal{L}^{-1}[Y] + \mathcal{L}^{-1}[W] = y(t) + w(t)$
$\mathcal{L}[\alpha y] = \alpha \mathcal{L}[y] = \alpha Y(s)$	$\mathcal{L}^{-1}[\alpha Y] = \alpha \mathcal{L}^{-1}[Y] = \alpha y(t)$
$\mathcal{L}[u_a(t)y(t-a)] = e^{-as} \mathcal{L}[y] = e^{-as} Y(s)$	$\mathcal{L}^{-1}[e^{-as} Y] = u_a(t)y(t-a)$
$\mathcal{L}[e^{at}y(t)] = Y(s-a)$	$\mathcal{L}^{-1}[Y(s-a)] = e^{at} \mathcal{L}^{-1}[Y] = e^{at}y(t)$