

Name: Pat D

Discussion Section: _____

MA 226 Section B – Exam 3a
Fall 2014

Question Number	Possible Points	Student Score
1	24	
2	12	
3	14	
4	10	
5	12	
6	12	
7	16	
Total Points	100	

You must show your work to receive full credit

Discussion Sections:

B2: Wednesday 9-10

B3: Wednesday 2-3

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1.) Find the Inverse Laplace Transform of the following expressions:

$$a) \mathcal{L}^{-1}\left[\frac{6}{s^2-1}\right] = \mathcal{L}^{-1}\left[\frac{6}{(s-1)(s+1)}\right] = \mathcal{L}^{-1}\left[\frac{3}{s-1} - \frac{3}{s+1}\right] = \boxed{3e^t - 3e^{-t}} \quad (6 \text{ pts})$$

$$\frac{6}{(s-1)(s+1)} = \frac{A}{s-1} + \frac{B}{s+1} = \frac{A(s+1) + B(s-1)}{(s-1)(s+1)}$$

$$6 = (A+B)s + (A-B)$$

$$0 = A+B$$

$$6 = A-B$$

$$2A = 6$$

$$\boxed{A=3} \quad \boxed{B=-3}$$

$$b) \mathcal{L}^{-1}\left[\frac{2s}{s^3(s-1)}\right] = \mathcal{L}^{-1}\left[\frac{-2s^2-2s}{s^3} + \frac{2}{s-1}\right] = \mathcal{L}^{-1}\left[-\frac{2}{s}\right] - \mathcal{L}^{-1}\left[\frac{2}{s^2}\right] + \mathcal{L}^{-1}\left[\frac{2}{s-1}\right] \quad (8 \text{ pts})$$

$$\frac{2s}{s^3(s-1)} = \frac{As^2+Bs+C}{s^3} + \frac{D}{s-1}$$

$$= \frac{As^3 + Bs^2 + Cs - As^2 - Bs + C + s^3D}{s^3(s-1)}$$

$$2s = (A+D)s^3 + (B-A)s^2 + (C-B)s - C$$

$$\Rightarrow A+D=0 \quad D=2$$

$$B-A=0 \quad A=-2$$

$$C-B=2 \Rightarrow B=-2$$

$$C=0$$

$$\boxed{-2 - 2t + 2e^t}$$

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1.) (continued) Find the inverse Laplace transform:

$$c) \mathcal{L}^{-1}\left[\frac{s \cdot e^{-2s}}{s^2+9}\right] = \boxed{u_2(t) \cos(3(t-2))}$$

(4 pts)

$$d) \mathcal{L}^{-1}\left[\frac{(s+1) \cdot e^{-4s}}{s^2+6s+13}\right] = \mathcal{L}^{-1}\left[e^{-4s} \cdot \frac{s+1}{(s+3)^2+4}\right]$$

(6 pts)

$$= \mathcal{L}^{-1}\left[e^{-4s} \cdot \frac{s+1+2-2}{(s+3)^2+4}\right]$$

$$= \mathcal{L}^{-1}\left[e^{-4s} \cdot \frac{s+3}{(s+3)^2+4}\right] - \mathcal{L}^{-1}\left[e^{-4s} \cdot \frac{2}{(s+3)^2+4}\right]$$

$$= u_4(t) e^{-3(t-4)} \cos(2(t-4)) - u_4(t) e^{-3(t-4)} \sin(2(t-4))$$

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2. (12 pts) Six second order equations and four $y(t)$ - graphs are given below. For each $y(t)$ - graph, determine the second-order equation for which $y(t)$ is a solution, and state briefly how you know your choice is correct.

(i) $\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 16y = 3\cos 4t$

(ii) $\frac{d^2y}{dt^2} + 12y = 3\cos 4t$

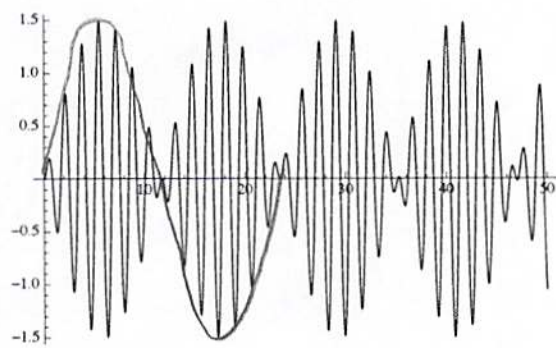
(iii) $\frac{d^2y}{dt^2} + 18y = 3\cos 4t$

(iv) $\frac{d^2y}{dt^2} + 16y = -8$

(v) $\frac{d^2y}{dt^2} + 16y = 3\cos 4t$

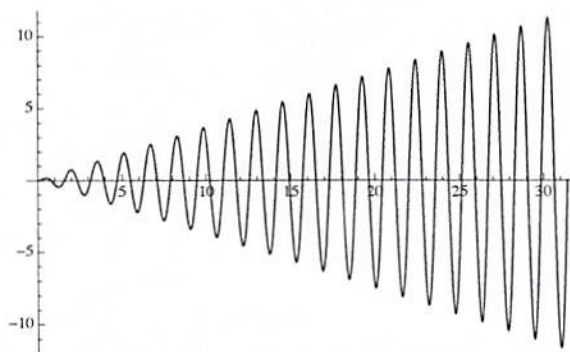
(vi) $\frac{d^2y}{dt^2} + 16y = 8$

A

equation: ii

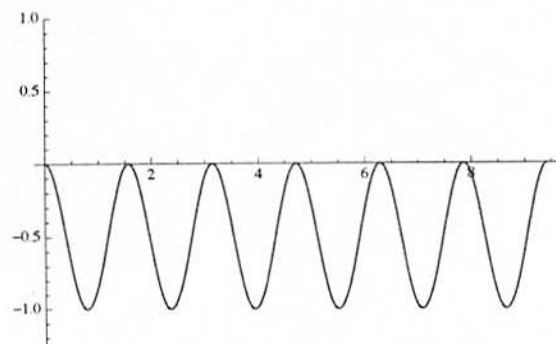
reason: Beating Period ≈ 25
 Beating Freq $\approx \frac{1}{25} \approx .04$
 $F_{\text{Beating}} = \frac{4 - \sqrt{12}}{4\pi} \approx .042$

B

equation: v

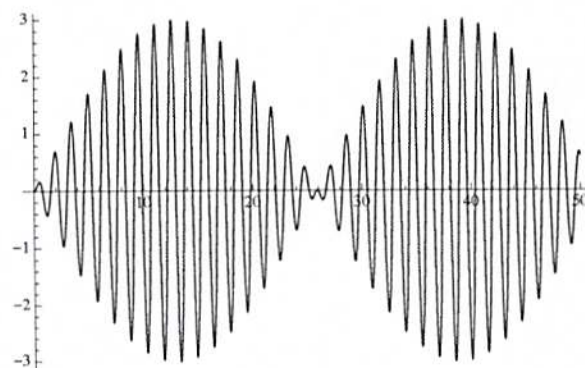
reason: $F_N = F_f = \frac{4}{2\pi}$

C

equation: iv

reason: forcing function negative constant

D

equation: iii

reason: Beating Period ≈ 50
 Beating Freq $\approx \frac{1}{50} = .02$
 $F_{\text{Beating}} = \frac{\sqrt{18} - 4}{4\pi} = .019$

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3. (14 pts) Find the general solution of : $\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 2y = 4t^2 + 2 + e^{-2t}$

$$\textcircled{1} y_h(t) \Rightarrow y(t) = e^{st} \quad s^2 + 3s + 2 = 0$$

$$(s+2)(s+1) = 0 \Rightarrow s = -2, s = -1$$

$$y_h(t) = k_1 e^{-2t} + k_2 e^{-t} \quad (3 \text{ pts})$$

$$\textcircled{2} \left. \begin{aligned} y_{p1}(t) &= At^2 + Bt + C \\ y_{p1}'(t) &= 2At + B \\ y_{p1}''(t) &= 2A \end{aligned} \right\} \begin{aligned} 2A + 3(2A + B) + 2(At^2 + Bt + C) &= 4t^2 + 2 \\ 2At^2 + (6A + 2B)t + (2A + 3B + 2C) &= 4t^2 + 2 \\ 2A = 4 &\Rightarrow \boxed{A = 2} \\ 6A + 2B = 0 &\Rightarrow \boxed{B = -3A = -6} \\ 2A + 3B + 2C = 2 &\Rightarrow 4 - 18 + 2C = 2 \Rightarrow \boxed{C = 8} \end{aligned}$$

$$y_{p1}(t) = 2t^2 - 6t + 8$$

$$\left. \begin{aligned} y_{p2}(t) &= Ate^{-2t} \\ y_{p2}'(t) &= -2Ate^{-2t} + Ae^{-2t} \\ y_{p2}''(t) &= 4Ate^{-2t} - 2Ae^{-2t} - 2Ae^{-2t} \end{aligned} \right\} \begin{aligned} &\text{plug into} \\ &\text{eqn} \end{aligned}$$

$$4Ate^{-2t} - 4Ae^{-2t} + 3(-2Ate^{-2t} + Ae^{-2t}) + 2Ate^{-2t} = e^{-2t}$$

$$4Ate^{-2t} - 6Ate^{-2t} + 2Ate^{-2t} - 4Ae^{-2t} + 3Ae^{-2t} = e^{-2t}$$

$$-Ae^{-2t} = e^{-2t} \Rightarrow A = -1$$

$$y_{p2}(t) = te^{-2t}$$

$$y(t) = k_1 e^{-2t} + k_2 e^{-t} + 2t^2 - 6t + 8 - te^{-2t}$$

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4. (10 pts) Compute the Laplace Transform of the function $w(t)$ using the definition of the Laplace Transform:

$$w(t) = \begin{cases} e^{-t}, & \text{if } 0 \leq t < 1 \\ 3, & \text{if } t \geq 1 \end{cases}$$

$$\mathcal{L}\{w(t)\} = \int_0^{\infty} w(t) e^{-st} dt = \int_0^1 e^{-t} e^{-st} dt + \int_1^{\infty} 3 e^{-st} dt$$

$$= \int_0^1 e^{-t(s+1)} dt + \lim_{b \rightarrow \infty} 3 \int_1^b e^{-st} dt$$

$$= \left. \frac{-1}{s+1} e^{-t(s+1)} \right|_0^1 + \lim_{b \rightarrow \infty} \left. \frac{-3}{s} e^{-st} \right|_1^b$$

$$= \frac{-1}{s+1} (e^{-(s+1)} - e^0) + \lim_{b \rightarrow \infty} \frac{-3}{s} (e^{-sb} - e^{-s})$$

$$= \boxed{\frac{1}{s+1} (1 - e^{-(s+1)}) + \frac{3}{s} e^{-s}}$$

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5. (12 pts) Find a particular solution of $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 13y = 3\sin(2t)$ using complexification.

$$\text{Let } y_p(t) = Ae^{2ti}$$

$$y_p'(t) = 2iAe^{2ti}$$

$$y_p''(t) = -4Ae^{2ti}$$

plug into eqn

$$-4Ae^{2ti} + 4 \cdot 2iAe^{2ti} + 13Ae^{2ti} = 3e^{2ti}$$

$$(9A + 8iA)e^{2ti} = 3e^{2ti}$$

$$(9 + 8i)A = 3$$

$$A = \frac{3}{9 + 8i} = \frac{3}{9 + 8i} \cdot \frac{9 - 8i}{9 - 8i} = \frac{27 - 24i}{145}$$

$$A = \frac{3}{145}(9 - 8i)$$

$$y_p(t) = Ae^{2it} = \frac{3}{145}(9 - 8i)(\cos 2t + i\sin 2t)$$

$$= \frac{3}{145}((9\cos 2t + 8\sin 2t) + i(9\sin 2t - 8\cos 2t))$$

We need the imaginary part

$$y_p(t) = \frac{3}{145}(9\sin(2t) - 8\cos(2t))$$

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6. (12 pts) Given the nonlinear autonomous system

$$\frac{dx}{dt} = x(2-x-y) = 2x - x^2 - xy = f(x,y)$$

$$\frac{dy}{dt} = y(6-2x-y) = 6y - 2xy - y^2 = g(x,y)$$

Use Linearization to classify the behavior at the equilibrium point $(4, -2)$. If the equilibrium point is a spiral source or a spiral sink determine the direction of rotation as clockwise or counter clockwise.

$$J(x,y) = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} = \begin{bmatrix} 2-2x-y & -x \\ -2y & 6-2x-2y \end{bmatrix}$$

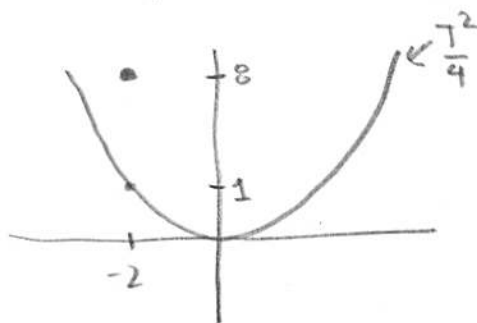
$$J(4,-2) = \begin{bmatrix} 2-8+2 & -4 \\ 4 & 6-8+4 \end{bmatrix} = \begin{bmatrix} -4 & -4 \\ 4 & 2 \end{bmatrix}$$

Linearized
system
at $(4, -2)$

$$\frac{d\bar{y}}{dt} = J(4,-2)\bar{y} = \begin{bmatrix} -4 & -4 \\ 4 & 2 \end{bmatrix} \bar{y}$$

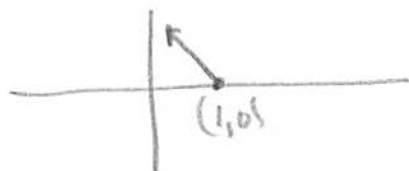
$$\text{Trace} = -2$$

$$\text{Det} = -8 + 16 = 8$$



spiral sink

$$\begin{bmatrix} -4 & -4 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -4 \\ 4 \end{bmatrix} \leftarrow y \text{ is positive} \Rightarrow \text{counter clockwise rotation}$$



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7. (16 pts) Solve the 2nd order linear non-homogeneous initial value problem:

(you can use the next page too if you need more space)

$$\frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 6y = 6u_3(t) \quad \text{with } y(0) = 2 \text{ and } y'(0) = 4$$

$$\mathcal{L}\left[\frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 6y\right] = \mathcal{L}[6u_3(t)]$$

$$s^2 \mathcal{L}[y] - sy(0) - y'(0) + 4[s\mathcal{L}[y] - y(0)] + 6\mathcal{L}[y] = \mathcal{L}\left[6\frac{e^{-3s}}{s}\right]$$

$$(s^2 + 4s + 6)\mathcal{L}[y] - 2s - 4 - 0 = 6\frac{e^{-3s}}{s}$$

$$\mathcal{L}[y] = \frac{2s + 12}{s^2 + 4s + 6} + e^{-3s} \cdot \frac{6}{s(s^2 + 4s + 6)}$$

Two separate problem.

$$\mathcal{L}^{-1}\left[\frac{2s + 12}{s^2 + 4s + 6}\right] = 2\mathcal{L}^{-1}\left[\frac{s + 6}{(s+2)^2 + 2}\right] = 2\mathcal{L}^{-1}\left[\frac{s+2+4}{(s+2)^2 + 2}\right]$$

$$= 2\mathcal{L}^{-1}\left[\frac{s+2}{(s+2)^2 + 2}\right] + 2\mathcal{L}^{-1}\left[\frac{4}{(s+2)^2 + 2}\right]$$

$$= 2 \cdot e^{-2t} \cos(\sqrt{2}t) + \frac{8}{\sqrt{2}} \mathcal{L}^{-1}\left[\frac{\sqrt{2}}{(s+2)^2 + 2}\right]$$

$$= 2 \cdot e^{-2t} \cos(\sqrt{2}t) + 4\sqrt{2} e^{-2t} \sin(\sqrt{2}t)$$

$$7.) \mathcal{L}^{-1} \left[e^{-3s} \cdot \frac{6}{s(s^2+4s+6)} \right]$$

$$\frac{6}{s(s^2+4s+6)} = \frac{A}{s} + \frac{Bs+C}{s^2+4s+6} = \frac{As^2+4As+6A+Bs^2+Cs}{s(s^2+4s+6)}$$

$$\Rightarrow (A+B)s^2 + (4A+C)s + 6A = 6$$

$$A=1 \Rightarrow B=-1 \Rightarrow C=-4$$

$$\mathcal{L}^{-1} \left[e^{-3s} \cdot \left(\frac{1}{s} - \frac{s+4}{s^2+4s+6} \right) \right] = \mathcal{L}^{-1} \left[\frac{e^{-3s}}{s} \right] - \mathcal{L}^{-1} \left[\frac{(s+4)e^{-3s}}{(s+2)^2+2} \right]$$

$$= u_3(t) - \mathcal{L}^{-1} \left[\frac{(s+2+2)e^{-3s}}{(s+2)^2+2} \right]$$

$$= u_3(t) - \mathcal{L}^{-1} \left[e^{-3s} \cdot \frac{s+2}{(s+2)^2+2} \right] - \sqrt{2} \mathcal{L}^{-1} \left[e^{-3s} \cdot \frac{\sqrt{2}}{(s+2)^2+2} \right]$$

$$= u_3(t) - u_3(t) e^{-2(t-3)} \cos(\sqrt{2}(t-3)) - \sqrt{2} u_3(t) e^{-2(t-3)} \sin(\sqrt{2}(t-3))$$

$$y(t) = 2e^{-2t} \left(\cos \sqrt{2}t + 2\sqrt{2} \sin \sqrt{2}t \right) +$$

$$u_3(t) \left(1 - e^{-2(t-3)} \left(\cos(\sqrt{2}(t-3)) + \sqrt{2} \sin(\sqrt{2}(t-3)) \right) \right)$$