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High-Speed Chemical Imaging by Dense-Net Learning of Femtosecond Stimulated Raman Scattering

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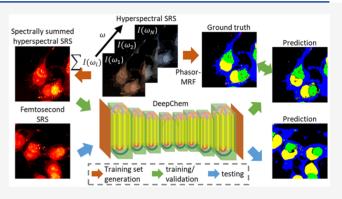
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ABSTRACT: Hyperspectral stimulated Raman scattering (SRS) by spectral focusing can generate label-free chemical images through temporal scanning of chirped femtosecond pulses. Yet, pulse chirping decreases the pulse peak power and temporal scanning increases the acquisition time, resulting in a much slower imaging speed compared to single-frame SRS using femtosecond pulses. In this paper, we present a deep learning algorithm to solve the inverse problem of getting a chemically labeled image from a single-frame femtosecond SRS image. Our DenseNet-based learning method, termed as DeepChem, achieves high-speed chemical imaging with a large signal level. Speed is improved by 2 orders of magnitude with four subcellular components (lipid droplet, endoplasmic reticulum, nuclei, cytoplasm) classified in



MIA PaCa-2 cells and other cell types which were not used for training. Lipid droplet dynamics and cellular response to dithiothreitol in live MIA PaCa-2 cells are demonstrated using this computationally multiplex method.

ibrational spectroscopic imaging of cellular and tissue structures is opening a new window for cell biology research and clinical diagnosis. 1-3 Stimulated Raman scattering (SRS) microscopy is a vibrational imaging technique with label-free chemical specificity. 4,5 SRS microscopy has been implemented with both picosecond and femtosecond pulses, respectively, allowing the single color and hyperspectral imaging capabilities.^{6,7} Despite these advances, the trade-off between speed, signal-to-noise ratio (SNR), and spectroscopic bandwidth prevents its broader application in biology and biomedicine. Using picosecond pulse trains, video-rate SRS imaging was realized via a fast lock-in amplifier.8 SNR was 10fold increased using femtosecond pulse excitation because of the integration over a spectral window compared to picosecond pulse excitation. Although single-shot femtosecond SRS imaging permits real-time skin imaging in live mice and cellular metabolism quantification, 10 it lacks spectroscopic information and thus cannot discriminate chemical components with overlapping Raman signatures. Spectral focusing provides an efficient method for femtosecond pulse based hyperspectral SRS (hSRS) measurements by linear chirping of pump and Stokes pulses. 11,12 However, the speed of time-delay scanning for parallel detection of several Raman bands is often limited by the motorized translational stage due to the waiting time for communication and stabilization.¹³ Improved frequency tuning via a galvanometer mirror has reached a speed of seconds per stack. 13,14 Nevertheless, just as illustrated in Figure 1a, tens to hundreds of times more measurements are needed for an SRS stack than a single-frame image and limits

further improvement of its imaging speed. Multiplex SRS enabled single spectrum recording within several microseconds by wavelength division or modulation division. These multiplex designs, however, either came with deterioration in SNR or loss of spectral selectivity. Collectively, limitations of each modality highlight a need to fill the gap between the low spectral resolution in femtosecond pulse excitation and the low speed in hyperspectral measurement, aiming at a high-speed, high-SNR, hyperspectral SRS imaging method.

In parallel with instrumentation development, computational approaches have been applied to boost the speed and/or SNR in SRS microscopy. With prior knowledge of the low-rankness of SRS images, sparse sampling methods improved the SRS imaging speed with linear models. ^{18–20} Thanks to the recent resurgence of deep neural networks (DNNs), image interpretation and translation problems can be resolved via direct learning of the underlying image mapping relation. ²¹ A recently reported U-Net DNNs based algorithm for SRS image denoising shows applicability to reduce potential photodamage and enable deep tissue imaging. ²² Other applications of DNNs to optical microscopy include image translation, ^{23,24} denois-

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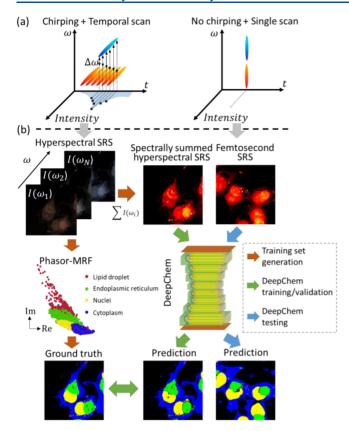


Figure 1. Schematic of SRS imaging and workflow of DeepChem training and prediction. (a) Schematic of two SRS imaging schemes in the 3D domain of time, Raman shift, and intensity. Left: hyperspectral SRS imaging with linearly chirped pulses. Right: single-frame SRS imaging with nonchirped femtosecond pulses. (b) Workflow of DeepChem training and prediction. The training set consists of pairs of spectrally summed hyperspectral SRS images and their corresponding subcellular organelle maps from Phasor-MRF. After training, DeepChem is capable of predicting subcellular organelle maps based on a single-frame femtosecond SRS image. MRF: Markov Random Field.

ing, ^{22,25} super-resolution, ²⁶ cross-modality image fusion, ²⁷ focus correction, ²⁸ and transmission correction, ²⁹ largely in the fluorescence microscopy field.

In this work, we tackle the trade-off among spectral specificity, speed, and SNR by learning the correlation between spectral and spatial features to derive chemical maps from a high-speed femtosecond SRS image. Specifically, we deploy a customized DNN model, namely, a DenseNet-based neural network architecture. 30,31 DenseNet has significant advantages over conventional DNNs such as U-Net in computer vision problems, including semantic segmentation.³² By introducing connections between each layer, DenseNet has achieved advanced performance, such as the alleviation of gradient vanishing and reduction of the number of parameters, encouraging feature reuse.³⁰ We term our DenseNet-based DNN as DeepChem. The pairs of spectrally summed hSRS images of MIA PaCa-2 cells and the spatially segmented subcellular organelle maps are used for training DeepChem. Then the well-trained network is capable of generating subcellular organelle maps using femtosecond SRS images (Figure 1b). On the basis of this method, the needed frame number is reduced to one while the chemical selectivity of four subcellular components (lipid droplet, endoplasmic reticulum,

nuclei, cytoplasm) is preserved. Thus, the trade-off between high SNR, chemical selectivity, and speed qualities is broken, without additional need for fluorescent labels, parameter estimation, or hardware design.

To test this idea, SRS images were acquired using a lab-built SRS microscope previously reported in ref 9 (section S1 and Figure S1, Supporting Information). For hyperspectral SRS imaging under a spectral focusing scheme, both the pump and Stokes beams were chirped with high-dispersion glass, and the hSRS images were collected via spectral scanning controlled by a motorized translational stage. For single-frame femtosecond SRS imaging, no chirping material was used. The schematic of these two imaging schemes in the time, Ramam shift, and intensity domain is illustrated in Figure 1a. For the collected hSRS images, we implemented a hyperspectral image segmentation method based on Phasor analysis and Markov Random Field (Phasor-MRF, see section S2 and Figure S2 for details) to incorporate both spectral and spatial features in segmenting the subcellular organelle maps. Two-photon excitation fluorescence images then confirmed the results from Phasor-MRF (Figure S4, Supporting Information). Section S3 and Figure S5 in the Supporting Information compared the single-frame femtosecond SRS images and the spectrally summed SRS images under the same field of view, showing that images collected using these two modalities have morphological features with high similarity. The data validate our scheme in which spectrally summed hSRS images were used for training. After training, DeepChem is capable of predicting subcellular organelle maps from single-frame femtosecond SRS images. The workflow of DeepChem training and prediction is shown in Figure 1b.

To generate the training set, we applied normalization for each image to accommodate different experimental conditions. Following the normalization, we applied image augmentation, such as image rotation and transpose, to generate a training set with 4000 images, each with 128 × 128 pixels. DeepChem is constructed with repeated dense blocks consisting of several densely connected convolution blocks. Each convolution block consists of one convolutional layer followed by a batch normalization layer and a ReLU activation layer. DeepChem employs an exponentially decaying learning rate with an Adam optimizer and a batch size of 2. Different learning rate initialization is applied for each segmentation class. The neural network is implemented in Keras framework on a single GPU (GEFORCE 2080Ti). The detailed architecture can be found in Figure S6. Test-time augmentation is then applied toward a better segmentation accuracy as in ref 33. For each image in the testing set, the prediction ensemble of multiple transformed versions of this image is first calculated using the pretrained network. Accordingly, we get the final prediction result $\hat{Y} = E(Y|X) = \sum_{1}^{N} y_{n}/N$. y_{n} denotes the probability map of each instance in the prediction ensemble, and X denotes the input image for inference.

Predicted subcellular organelle maps using spectrally summed hSRS show clear biological details and high structural similarity to ground truth images (Figure 2a). The confusion matrix in Figure 2b shows good prediction accuracy (high intensities cluster in the diagonals). Specifically, DeepChem has a 0.787 F_1 score (definition in section S4, Supporting Information) for nuclei segmentation, better than other subcellular organelle segmentation methods using fluorescence images (\sim 0.7).³⁴ For the other three classes (lipid droplets,

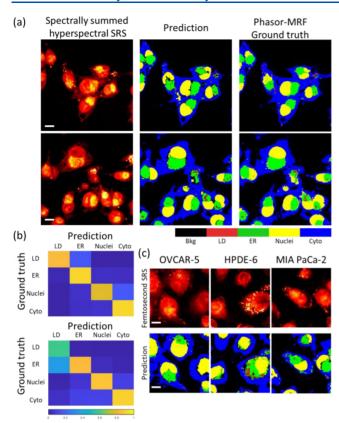


Figure 2. Predicted subcellular organelle maps from spectrally summed hSRS images and single-frame femtosecond SRS images. (a) Predicted subcellular organelle maps from spectrally summed hSRS images. Scale bar: $10~\mu m$. (b) Confusion matrix of subcellular component classes (definition in section S4, Supporting Information): top, normalized by column; bottom, normalized by row. LD, Bkg, ER, and Cyto are abbreviations for lipid droplet, background, endoplasmic reticulum, and cytoplasm. (c) Predicted subcellular organelle maps from single-frame femtosecond SRS images. Scale bar: $10~\mu m$.

ER, cytoplasm), our method has F_1 scores of 0.645, 0.805, and 0.789. In addition, our method is greatly simplified and easier to use compared with networks deploying multiscale branches with different z-depth inputs. 23,24 Moreover, compared with the U-Net DNNs trained on the same data set, DenseNetbased DeepChem achieves higher segmentation performance (section S5 and Figure S7, Supporting Information).³² Figure 2c and Figure S8 show predicted subcellular organelle maps from femtosecond SRS images including those cell types (OVCAR-5 and HPDE-6) that never appeared in the training set. It means the neural network "has learned" to provide reliable results from new input of different modalities and different cell types. This result demonstrates the generalization ability of our method and heralds potential in functional cell imaging with high speed and chemical selectivity. In terms of the speed performance, a hSRS stack ($256 \times 256 \times 100$, FOV $64 \times 64 \,\mu\text{m}^2$) takes 110 s, while a single shot femtosecond SRS image with the same size takes 1-2 s. This dramatic speed improvement allows real-time imaging of living cells.

To demonstrate the advantage of our DenseNet-based method over single-frame femtosecond SRS imaging, we show lipid droplet tracking with paralleled ER label in live MIA PaCa-2 cells using high-speed high-sensitivity femtosecond pulses excitation. Previous research has shown the correlation between the spatial-temporal dynamics of lipid droplets and

cellular lipid metabolism.³⁵ However, the previous method using single-frame femtosecond SRS was unable to detect other subcellular organelles simultaneously. A traditional frame-by-frame SRS imaging system can provide multiple subcellular organelles simultaneously, but the speed is around 100 times slower than our method. In our experiment, we imaged live MIA PaCa-2 cells with a temporal resolution of 1.5 s per frame for about 2 min. Then, DeepChem predicted lipid droplet maps from the collected femtosecond SRS images. These maps were then analyzed by the particle-tracking plugin in ImageJ.³⁶ Two sample images are shown in Figure 3a. To

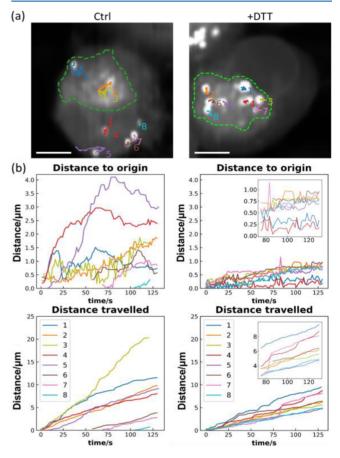


Figure 3. Lipid droplet tracking in live MIA PaCa-2 cells by femtosecond SRS and DeepChem. (a) Trajectories of lipid droplets (solid lines) and contours of the ER regions (dashed green lines). Scale bar: 5 μ m. (b) Quantification of lipid droplet dynamics. The insets in the right column show corresponding plots in the range 75–125 s.

quantify the lipid droplets dynamics, we define two parameters: traveled distance (the cumulative position displacement between consecutive frames) and distance to the origin (the displacement of the current position to the origin of the movement). Using the two parameters defined above, less active lipid droplet movement is observed in cells treated with 0.5 mM dithiothreitol (DTT) for 1 h (Figure 3b). DTT is a strong reducing agent that can break down dislide bond formation and thus lead to ER stress in minutes. A lipid droplet has been shown as a functional organelle connected as to the ER lumen. Thus, our observation implies that the enlarged ER lumen is more likely to trap the lipid droplets and limit their movement. Besides lipid metabolism, DeepChem based femtosecond SRS has the hyperspectral competence to

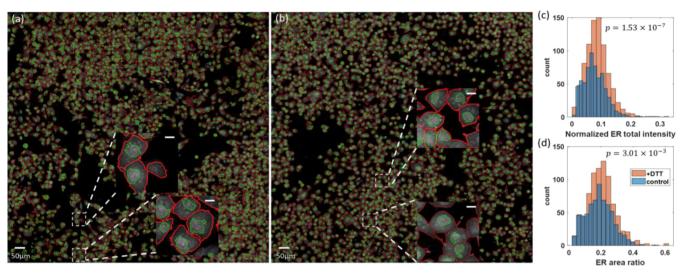


Figure 4. Quantification of cellular response to DTT in live MIA PaCa-2 cells. (a, b) Large-area femtosecond SRS images from the control and the DTT treated group. The insets show areas framed with white boxes. Scale bar: 10 μm. Green lines denote the contour of the ER region predicted. Red lines denote the cell contour analyzed by CellProfiler. (c, d) Histogram showing the distribution of the normalized ER total intensity and ER area ratio from the two groups. *ER area ratio* = *ER area/Cell area; normalized ER total intensity* = *ER area* × *ER intensity/Cell area.* ER intensity is defined by the averaged SRS signal in the ER region given the linear relationship between SRS signal intensity and the concentration of resonant molecules.

address the rising interest in understanding organelle interaction and cooperation from different aspects, including morphology and functionality.

Another strong desire in biomedical applications is largescale imaging with single-cell resolution. The strengths of our method in resolving this need are motion artifacts suppression and quantitative evaluation of each population. To illustrate these strengths, 400 images (64 \times 64 μ m² each) were captured in 10 min for both the control and DTT treated group (0.5 mM DTT, 1 h incubation) (Figure 4a,b). We then quantify the cellular response by normalized ER total intensity and ER area ratio, defined in the caption of Figure 4. In the DTT treated group, ER total intensity (Figure 4c) and ER area ratio (Figure 4c) are both increased compared to the control group, indicating an expansion of ER lumen induced by DTT. The hyperspectral capability of our method enables this large-scale high-speed imaging with high SNR displaying great advantage over the conventional frame-by-frame SRS imaging system. In contrast to the flow setting where the sample cannot be retrieved, our image cytometry method can perform continuous imaging of the same field of view. Potential applications for this method include SRS-enabled cell sorting.

We note that in our manuscript, the subcellular components ER, nucleus, cytoplasm, and lipid droplets can be differentiated on the basis of the intensity of femtosecond SRS images. This condition implies that machine learning is not magic; it pushes the limit in one domain by leveraging information in another domain. Nevertheless, compared to the threshold approach, machine learning ensures higher accuracy through a sophisticated network. Figure S9 compares the prediction results between brightness thresholding and DeepChem, showing that brightness thresholding based on a simple linear scheme suffers from different experimental conditions and cell-to-cell variation. The advantage of this DenseNet-based learning method is that it trains a nonlinear network utilizing the information on both the intensity and the morphological features in the training process, and after training, it outputs

much more robust segmentation results with high accuracy (section S6, Supporting Information).

In conclusion, we demonstrated a high-speed multiplex chemical imaging method by DenseNet-based learning of femtosecond SRS images. This method is capable of revealing rapid cellular dynamics, including lipid droplet movement and cellular response to DTT, an inducer of ER stress. High speed and chemical selectivity provided by this method offers various possibilities, and potential applications including large-area tissue segments imaging and deciphering cell metabolism. An optimized algorithm may be applied to enable massive parallel visualization of subcellular organelles in the future. On the basis of rapid developments in both SRS microscopy and deep learning methods, we foresee a more integrated computational SRS microscope providing advanced imaging schemes for comprehensive understanding of biology and materials.

ASSOCIATED CONTENT

Supporting Information

The Supporting Information is available free of charge at https://pubs.acs.org/doi/10.1021/acs.jpclett.0c01598.

SRS microscope setup, implementing phasor-MRF, comparison between spectrally summed hyperspectral SRS and femtosecond SRS, quantification of DeepChem prediction, comparison between subcellular organelle maps from phasor-MRF and fluorescence images, comparison between DeepChem and U-Net, DeepChem prediction of subcellular organelle maps from spectrally summed hyperspectral SRS images and femtosecond SRS images, DeepChem architecture, confusion matrix of subcellular component classes (PDF)

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Author Contributions

[#]J. Zhang, J. Zhao, and H. Lin contributed equally to this work. **Notes**

The authors declare no competing financial interest.

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