

SE/EC/ME 724 Advanced Optimization Theory and Methods

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Lecture 12: Outline

- 1 Lagrange multipliers: sufficient optimality conditions for problems with equality constraints.
- 2 Sensitivity.
- 3 Inequality constraints: Karush-Kuhn-Tucker conditions.

Sufficient optimality conditions

Define the **Lagrangian Function**: $L(\mathbf{x}, \boldsymbol{\lambda}) = f(\mathbf{x}) + \sum_{i=1}^m \lambda_i h_i(\mathbf{x})$.

Proposition

Let $\mathbf{x}^*, \boldsymbol{\lambda}^*$ satisfy

$$\nabla_{\mathbf{x}} L(\mathbf{x}^*, \boldsymbol{\lambda}^*) = \mathbf{0}, \quad \nabla_{\boldsymbol{\lambda}} L(\mathbf{x}^*, \boldsymbol{\lambda}^*) = \mathbf{0}$$

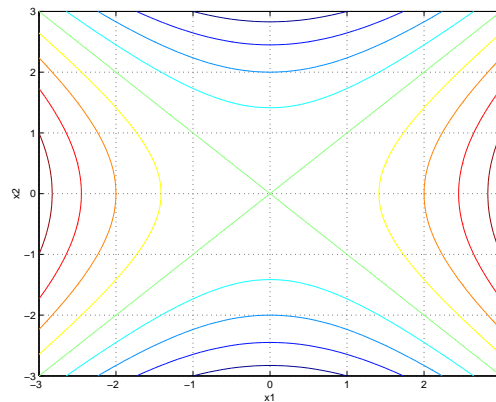
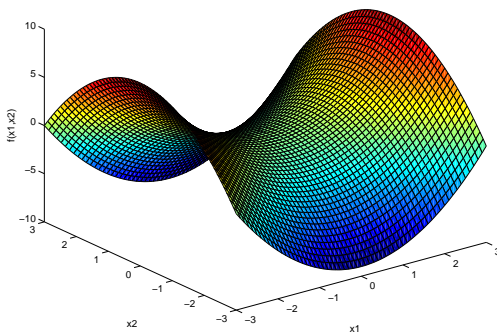
$$\mathbf{y}' \nabla_{\mathbf{xx}}^2 L(\mathbf{x}^*, \boldsymbol{\lambda}^*) \mathbf{y} > 0, \quad \forall \mathbf{y} \neq \mathbf{0} \text{ s.t. } \nabla \mathbf{h}(\mathbf{x}^*)' \mathbf{y} = \mathbf{0}.$$

Then \mathbf{x}^* is a **strict** local min of f over $\mathbf{h}(\mathbf{x}) = \mathbf{0}$, i.e., $\exists \gamma, \epsilon > 0$ s.t.

$$f(\mathbf{x}) \geq f(\mathbf{x}^*) + \frac{\gamma}{2} \|\mathbf{x} - \mathbf{x}^*\|^2, \quad \forall \mathbf{x} \text{ s.t. } \mathbf{h}(\mathbf{x}) = \mathbf{0} \text{ with } \|\mathbf{x} - \mathbf{x}^*\| < \epsilon.$$

Example

$$\begin{aligned} \min \quad & f(\mathbf{x}) = x_1^2 - x_2^2 \\ \text{s.t.} \quad & x_1^2 + 2x_2^2 = 4 \end{aligned}$$



Problems with equality and inequality constraints

$$\begin{aligned} \min \quad & f(\mathbf{x}) \\ \text{s.t.} \quad & \mathbf{h}(\mathbf{x}) = (h_1(\mathbf{x}), \dots, h_m(\mathbf{x})) = \mathbf{0}, \\ & \mathbf{g}(\mathbf{x}) = (g_1(\mathbf{x}), \dots, g_r(\mathbf{x})) \leq \mathbf{0}, \end{aligned}$$

where f, h_i, g_j are continuously differentiable (in a open set containing the minimum).

Define the **Lagrangian Function**:

$$L(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}) = f(\mathbf{x}) + \sum_{i=1}^m \lambda_i h_i(\mathbf{x}) + \sum_{j=1}^r \mu_j g_j(\mathbf{x}).$$

Let $A(\mathbf{x}) = \{j \mid g_j(\mathbf{x}) = 0\}$.

Karush-Kuhn-Tucker necessary optimality conditions

Proposition

Let \mathbf{x}^* be a regular local minimum, i.e., $\nabla h_1(\mathbf{x}^*), \dots, \nabla h_m(\mathbf{x}^*), \nabla g_j(\mathbf{x}^*), j \in A(\mathbf{x}^*)$ are linearly independent. Then, there exists Lagrange multiplier vectors $\boldsymbol{\lambda}^* = (\lambda_1^*, \dots, \lambda_m^*)$ and $\boldsymbol{\mu}^* = (\mu_1^*, \dots, \mu_r^*)$ s.t.

$$\begin{aligned} \nabla_{\mathbf{x}} L(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) &= \mathbf{0}, \quad \boldsymbol{\mu}^* \geq \mathbf{0}, \\ \mu_j^* &= 0, \quad \forall j \notin A(\mathbf{x}^*) \end{aligned}$$

If $f, \mathbf{h}, \mathbf{g}$ are twice continuously differentiable

$$\mathbf{y}' \nabla_{\mathbf{xx}}^2 L(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) \mathbf{y} \geq 0, \quad \forall \mathbf{y} \in V(\mathbf{x}^*),$$

where $V(\mathbf{x}^*) = \{\mathbf{y} \mid \nabla h_i(\mathbf{x}^*)' \mathbf{y} = 0, \forall i, \nabla g_j(\mathbf{x}^*)' \mathbf{y} = 0, j \in A(\mathbf{x}^*)\}$.

Sufficient conditions

Proposition

Let \mathbf{x}^* , $\boldsymbol{\lambda}^*$, $\boldsymbol{\mu}^*$ satisfy

$$\begin{aligned}\nabla_{\mathbf{x}}L(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*) &= \mathbf{0}, & \mathbf{h}(\mathbf{x}^*) &= \mathbf{0}, & \mathbf{g}(\mathbf{x}^*) &\leq \mathbf{0} \\ \boldsymbol{\mu}^* &\geq \mathbf{0}, & \mu_j^* &= 0, \forall j \notin A(\mathbf{x}^*), \\ \mathbf{y}'\nabla_{\mathbf{xx}}^2L(\mathbf{x}^*, \boldsymbol{\lambda}^*, \boldsymbol{\mu}^*)\mathbf{y} &> 0, & \forall \mathbf{y} \neq \mathbf{0}, \mathbf{y} &\in V(\mathbf{x}^*), \\ \mu_j^* &> 0, \forall j &\in A(\mathbf{x}^*).\end{aligned}$$

Then \mathbf{x}^* is a strict local minimum of the constrained problem.