

Neuro-Autonomy: Neuroscience-Inspired Perception, Navigation, and Spatial Awareness for Autonomous Robots



Wednesday, November 15, 2019 - Day 3

Location: 15 Saint Mary's Street, Room 105

8:30am-9:00am **Breakfast**

9:00am-9:25am **Iman Shames**, University of Melbourne
When Close Enough is Good Enough: Using Inexact Solutions in Real-Time Decision Making

9:25am-9:50am **Roberto Tron**, Boston University
Robust Localization and Planning: Theory and Algorithms Via Linear Programming

9:50am-10:15am **Nicholas Roy**, Massachusetts Institute of Technology
Introspection and Novel Concept Acquisition

10:15am-10:40am **Yannis Paschalidis**, Boston University
Learning Control Policies from Biological Data

10:40am-11:40am **Coffee break for Marc Steinberg and ONR Reviewers/Guests (closed to PIs)**

11:40am-12:40pm **Lunch and Debriefing with PIs**

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